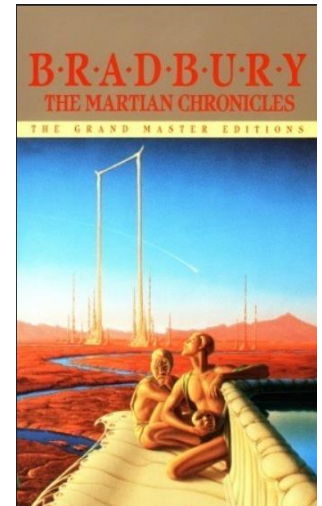


# You Don't Have to be a Rocket Scientist: JMP Martian Chronicles

October 20, 2017




Kristo Kriechbaum, Jet Propulsion Lab, California Institute of Technology

[Kristopher.L.Kriechbaum@jpl.nasa.gov](mailto:Kristopher.L.Kriechbaum@jpl.nasa.gov)

Jim Wisnowski, Adsurgo LLC

[james.wisnowski@adsurgo.com](mailto:james.wisnowski@adsurgo.com)

- The Mars 2020 rover will robotically explore the red planet's surface for at least 1 Martian year (687 Earth days)
- Builds on success of Mars Science Laboratory's Curiosity Rover to minimize program risk



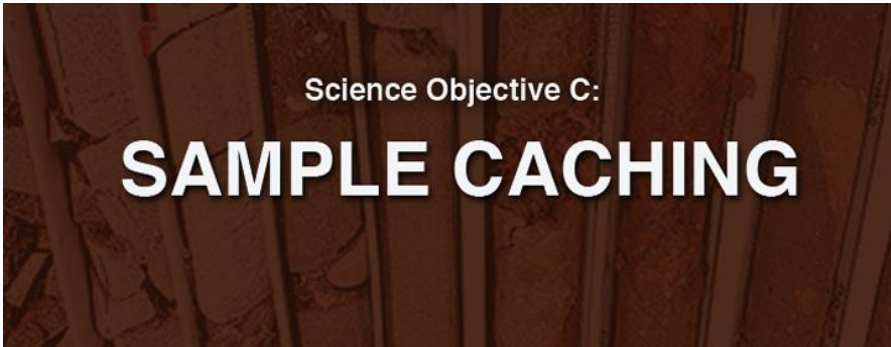
Science Objective A:

**GEOLOGY**




Science Objective B:

**ASTROBIOLOGY**



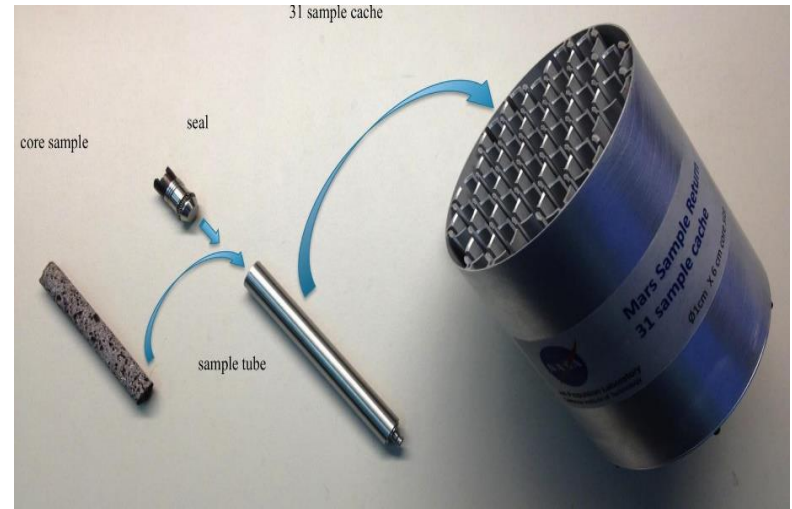
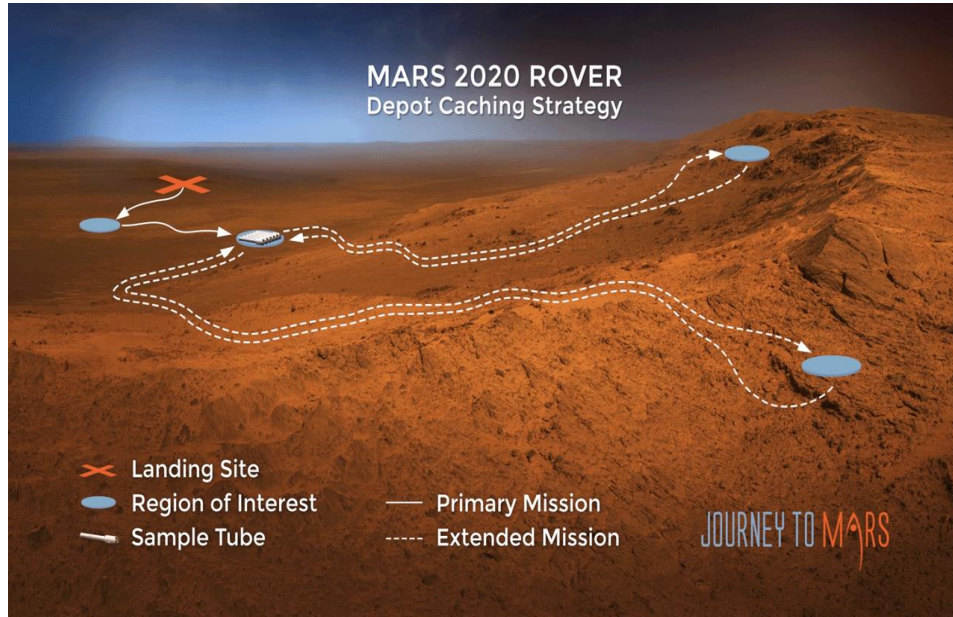
Science Objective C:

**SAMPLE CACHING**

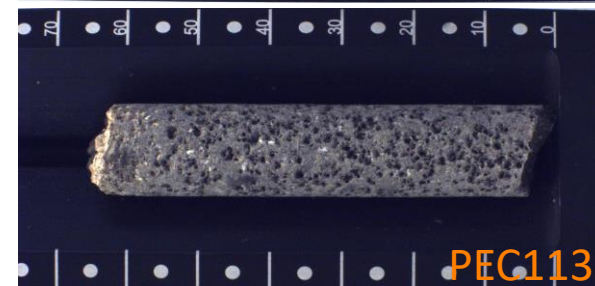
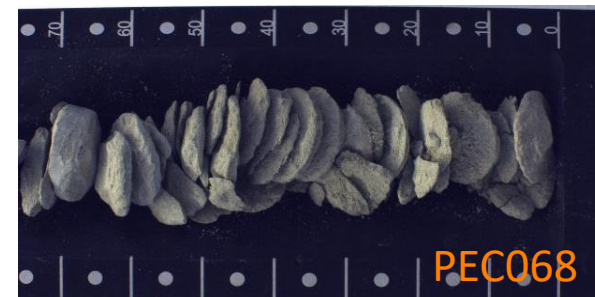


Science Objective D:

**PREPARATION  
FOR HUMANS**



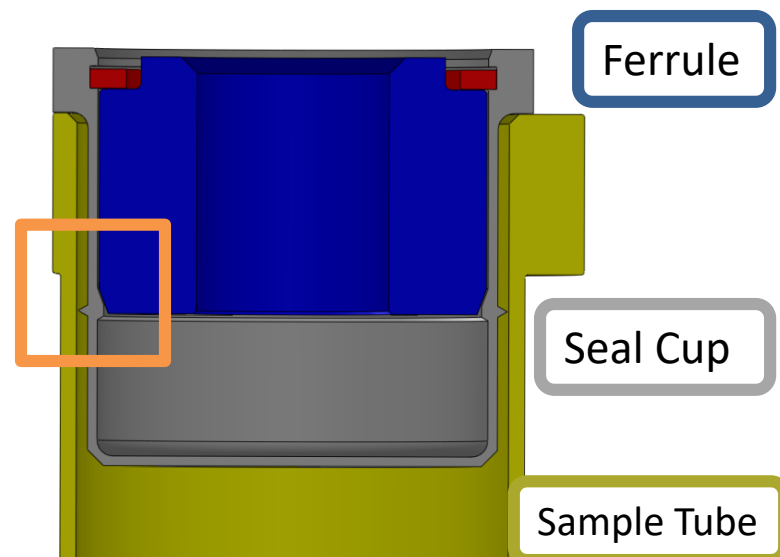
- We don't get to control Mars!
  - Subsystem design highly informed by testing
- Key requirements:
  - Collect ~40 cores of varying sample types, based on notional distribution of Earth analog rocks
  - Core quality - Best core has a few number of large pieces
  - Samples must be “hermetically” sealed
- Measurable responses
  - Core quality
    - Mass and number of pieces to pass through sieves of 2, 5, 10 and >10 mm
    - Sample volume
  - Seal leak rate
  - Drilling Performance
    - Avg cycle sideload
    - Avg cycle percussion current
    - Avg drilling torque
    - Avg percussion power
    - Avg rate of penetration



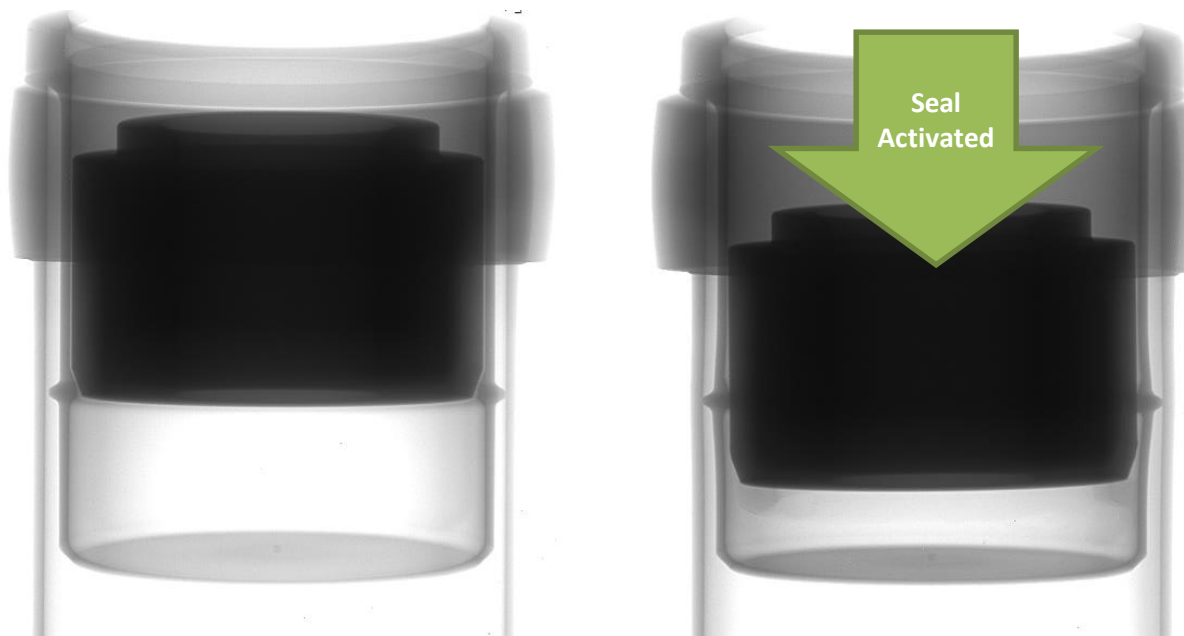
# Vignette 1.

## Space Filling Designs

- Problem: Prior tests showed hermetic seal performance is highly dependent on line load, but it is not directly measurable! Line load is estimated via nonlinear FEA model
- Knew important factors from previous FEA runs
- Platforms and topics: space filling design, predictive modeling, profiler and optimization
- Methodology: Create space filling design with candidate factors, fit neural models holding back a few runs as validation,
- Results:
  - Simple neural network model captures the nonlinearities
  - First form of line load model used before sealing test to compute ideal part dimensions
  - Second form of line load model used after sealing test to estimate actual achieved line load



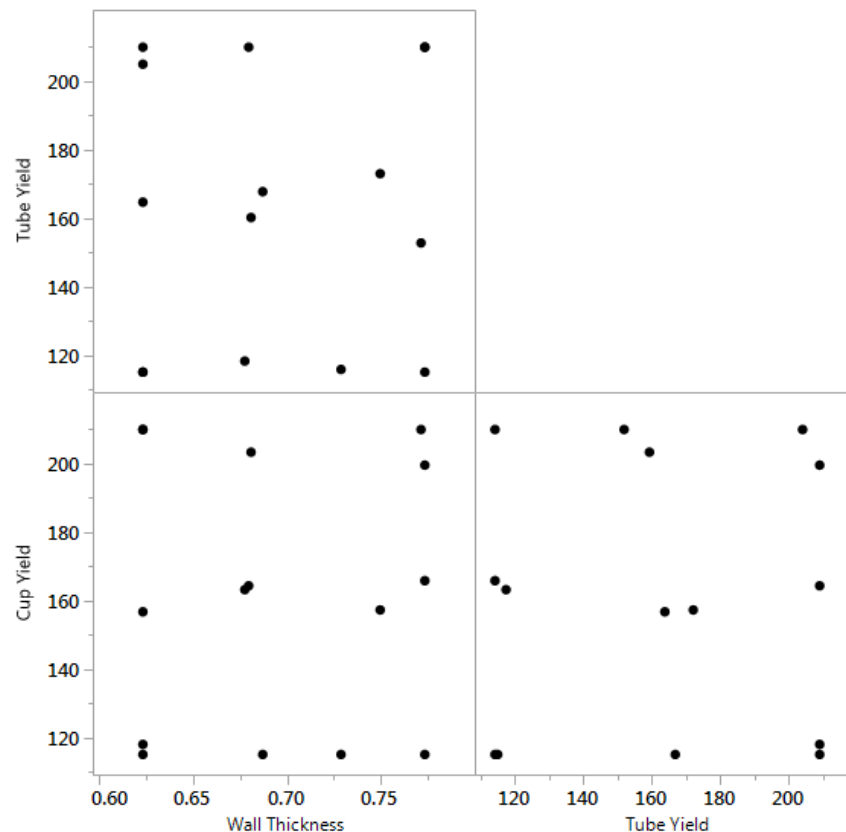
# Vignette 1. Space Filling Design



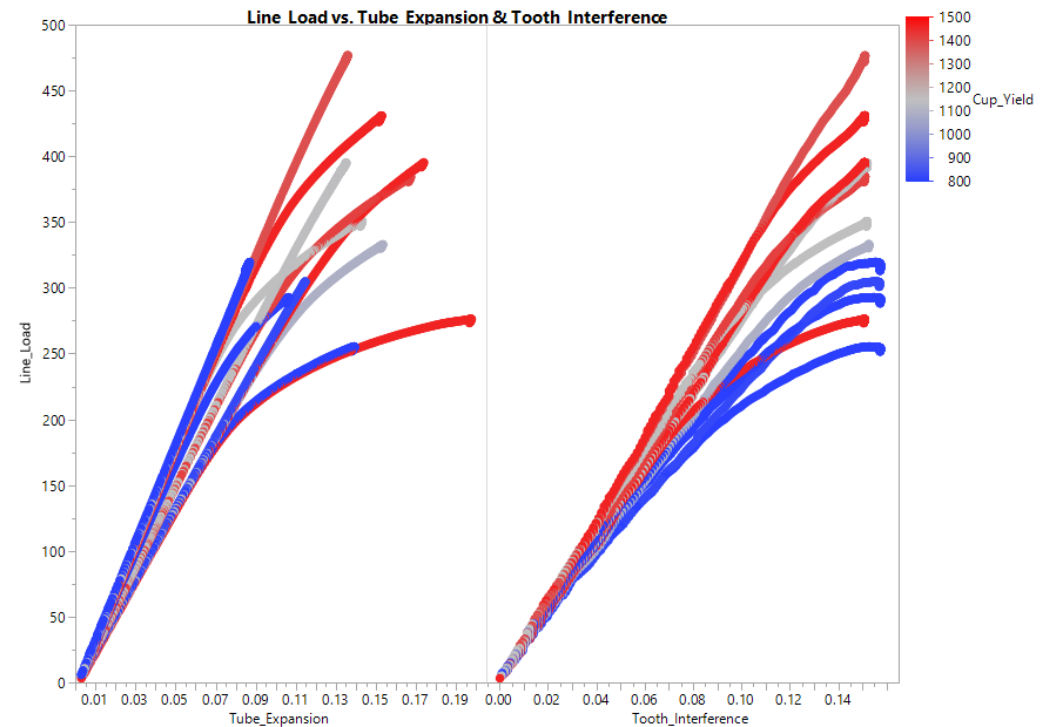
- Need 2 forms of model
  - Form 1 – given a target Line Load, what Tooth Interference do we need?
    - $\text{Line\_Load} = f(\text{Tooth Interference, Wall Thickness, Tube Yield, Cup Yield})$
    - This tells us how to grind the ferrule OD based on the Ramp ID
  - Form 2 – given a measured tube expansion (and other factors), what is the estimated Line Load?
    - $\text{Line\_Load} = f(\text{Tube Expansion, Wall Thickness, Tube Yield, Cup Yield})$
    - Used after seal is activated to estimate actual Line Load

# Vignette 1. Space Filling Design

- Space filling design with 3 factors
- 15 runs chosen as a good balance between filling the space and not overwhelming the FEA analyst

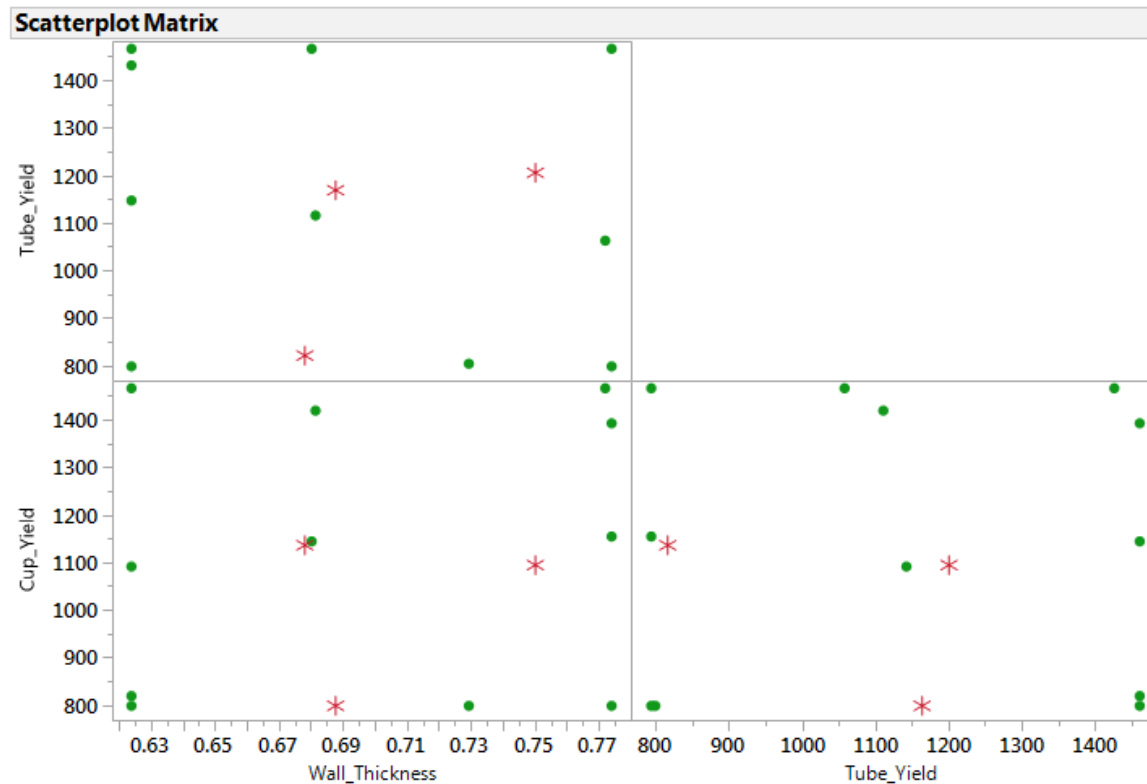


- Single FEA run gives 100's of data points for Tooth Interference and Tube Expansion





- 3 runs randomly selected to hold back for validation

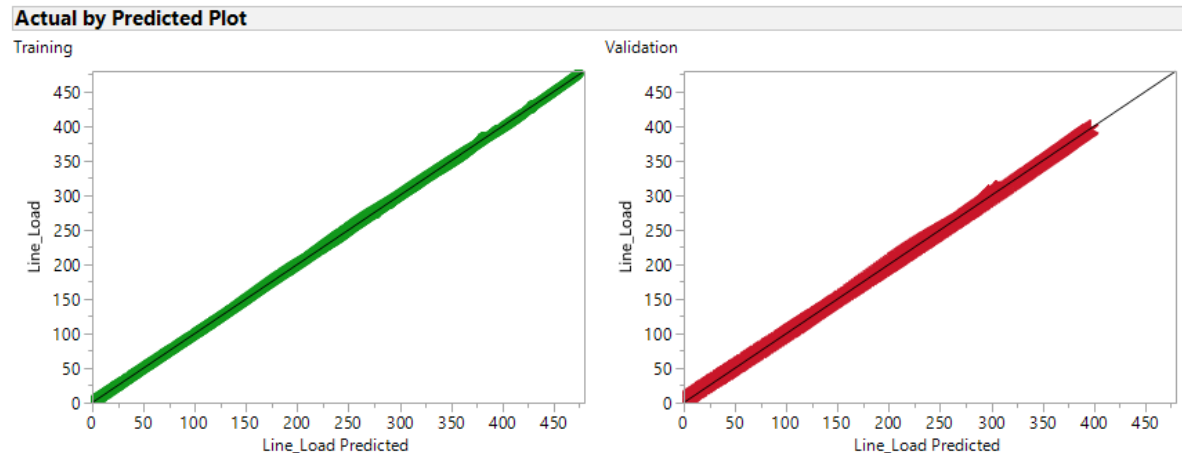
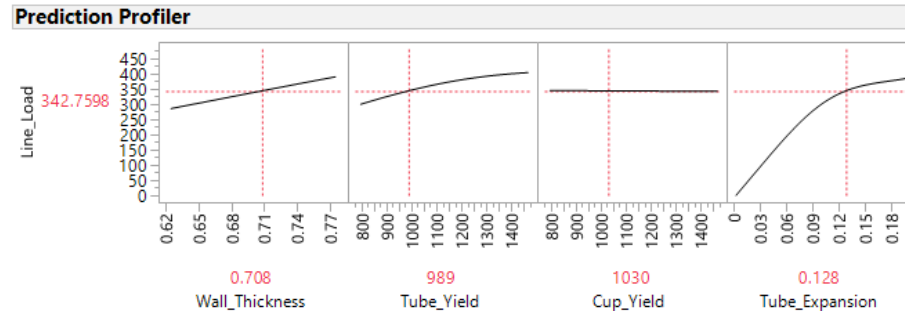


# Vignette 1.

## Space Filling Design

- Use Profiler and Desirability to find Tooth Interference required to achieve desired Line Load
- Likewise, use Profiler after test is performed to estimate actual Line Load from measured Tube Expansion

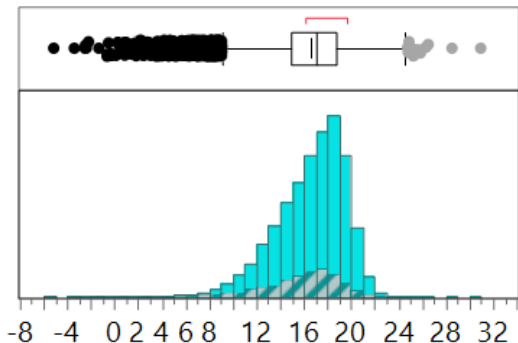
Training		Validation	
Line_Load		Line_Load	
Measures	Value	Measures	Value
RSquare	0.9998587	RSquare	0.9997298
RMSE	1.4252988	RMSE	1.8032011
Mean Abs Dev	1.1331251	Mean Abs Dev	1.4909835
-LogLikelihood	7800.8348	-LogLikelihood	2161.1482
SSE	8936.4661	SSE	3498.651
Sum Freq	4399	Sum Freq	1076



- Problem: What is the overall distribution for Core Total Mass given we have test data for the 4 types of rocks but at much different percentages than expected for 2020 missions?
- Platforms and topics: data cleaning, data visualization, filtering, fitting non-normal distributions, simulation
- Methodology: For each rock type, determine the best distribution and parameters, generate 100,000 \* (expected percent on Mars) observations, concatenate all 4 random variates, fit all 100,000 observations to a new distribution
- Results:
  - Log Generalized Gamma is best fit
  - Dynamic exploration with profilers
  - Quantify risk of having less than 15g



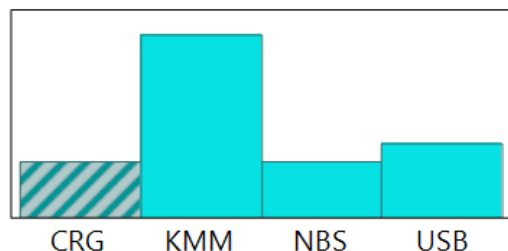
# Vignette 2. Complex Distribution



## Model Comparisons

Distribution	AICc
Log Generalized Gamma	483924.04
SEV	484454.23
Logistic	494677.33
Normal	495485.46
LEV	538932.46

### RockCode

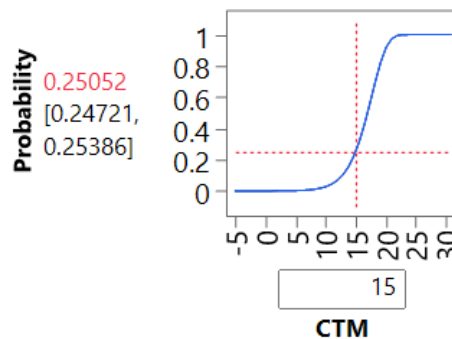


### Frequencies

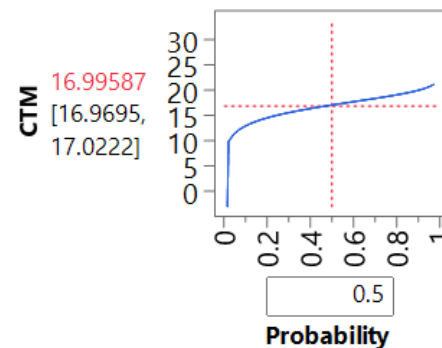
Level	Count	Prob
CRG	15000	0.15000
KMM	50000	0.50000
NBS	15000	0.15000
USB	20000	0.20000
Total	100000	1.00000

N Missing 0  
4 Levels

### Distribution Profiler



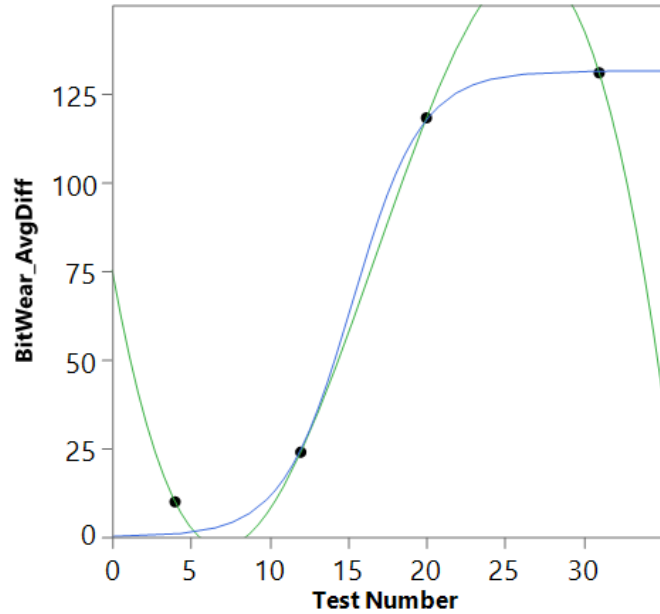
### Quantile Profiler



# Vignette 3. Modelling Bit Wear

- Problem: How can we model the impact of bit wear on drill performance metrics? Is there a surrogate measure for bit wear?
- Platforms and topics: data visualization, fit curve, nonlinear modelling, column switcher, multivariate, fit model stepwise
- Methodology: Measure bit wear 4 times over a series of 30 tests, fit candidate nonlinear models, create new control variable as bit wear over time, run regression models
- Results:
  - Bit wear approximated well by Logistic 3Parameter Sigmoid Curve
  - Makes sense from physics of failure/degradation models
  - Highly correlated with Time in USB rocks
  - Useful control variable for many of the responses





## Prediction Model

$$\frac{c}{1 + \exp(-a \cdot (\text{Test Number} - b))}$$

a = Growth Rate

b = Inflection Point

c = Asymptote

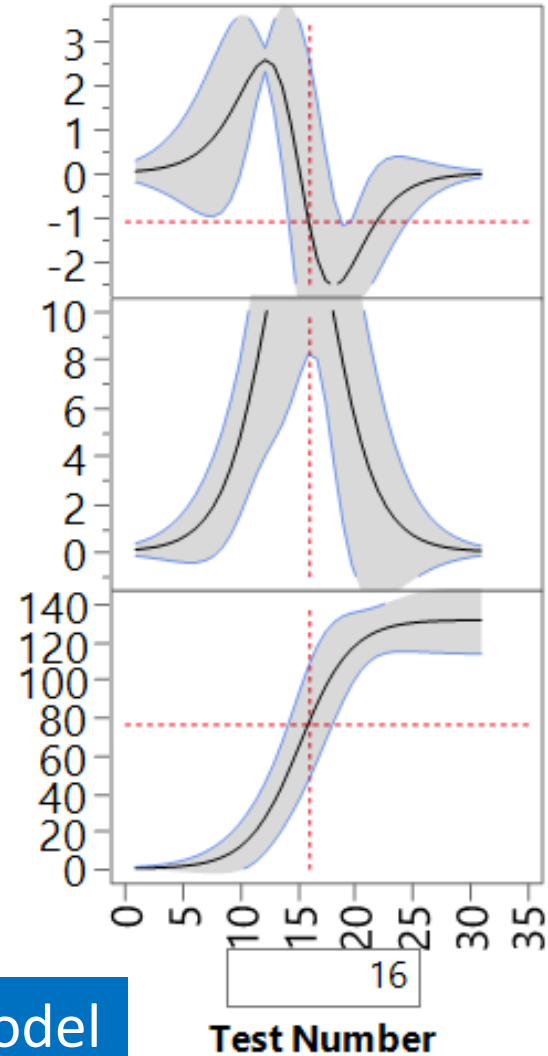
## 3 Parameter Logistic Model

## Prediction Profiler

**Second Derivative**  
-1.07703  
[-4.8552, 2.70111]

**First Derivative**  
14.3979  
[8.21207, 20.5837]

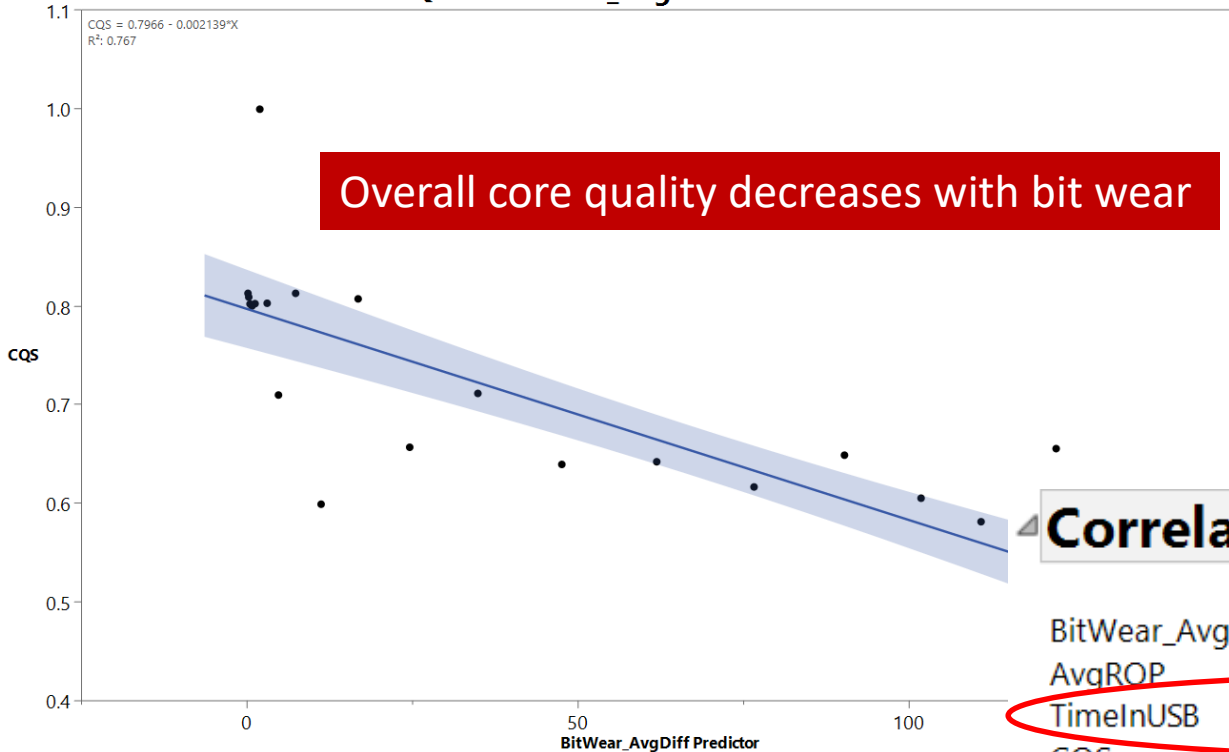
**BitWear\_AvgDi**  
ff 76.65  
[46.3615, 106.939]



# Vignette 3. Modelling Bit Wear

**Graph Builder**

**CQS vs. BitWear\_AvgDiff Predictor**



**Correlations**

	BitWear_AvgDiff Predictor
BitWear_AvgDiff Predictor	1.0000
AvgROP	-0.5094
TimeInUSB	0.9684
CQS	-0.8756
CoreTotalMass	-0.2533
CoreVolRatio	0.7149
TPEL_error	0.6313
CoreMassGT10mm	-0.3997
CoreNumPieces10_above	0.8828
CoreMassPerPiece_above_10mm	-0.8112
CoreVol_GT_10mm	-0.3997
CoreNumPieces	0.6037

# Vignette 3. Modelling Bit Wear

## Stepwise Fit for CoreTotalMass

### Stepwise Regression Control

Stopping Rule:

Direction:

Rules:

1 rows not used due to excluded rows or missing values.

SSE	DFE	RMSE	RSquare	RSquare Adj	Cp	p	AICc	BIC
14.395064	24	0.7744639	0.6662	0.5967	12.812759	6	82.19786	86.91533

### Current Estimates

Lock	Entered	Parameter	Estimate	nDF	SS	"F Ratio"	"Prob>F"
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	Intercept	153.987214	1	0	0.000	1
<input type="checkbox"/>	<input checked="" type="checkbox"/>	BitWear_AvgDiff Predictor	-0.3984135	3	11.22554	6.239	0.00276
<input type="checkbox"/>	<input checked="" type="checkbox"/>	FixtureName{EDT-PEC}	79.1205223	2	13.97101	11.647	0.00029
<input type="checkbox"/>	<input type="checkbox"/>	DrilSpindleRate	0	1	0.034134	0.055	0.8172
<input type="checkbox"/>	<input type="checkbox"/>	AvgCycleWOB	0	1	1.22575	2.141	0.15696
<input type="checkbox"/>	<input type="checkbox"/>	Bits_ToothRakeAngle	0	0	0	.	.
<input type="checkbox"/>	<input checked="" type="checkbox"/>	DrillingOrientation	-4842.4669	2	10.07633	8.400	0.00172
<input type="checkbox"/>	<input type="checkbox"/>	AbsPercLevel	0	1	0.738844	1.244	0.27615
<input type="checkbox"/>	<input checked="" type="checkbox"/>	(BitWear_AvgDiff Predictor-66.8819)*FixtureName{EDT-PEC}	-1.2538818	1	6.88123	11.473	0.00243
<input type="checkbox"/>	<input type="checkbox"/>	(BitWear_AvgDiff Predictor-66.8819)*(DrilSpindleRate-197.933)	0	2	0.096273	0.074	0.92884
<input type="checkbox"/>	<input type="checkbox"/>	(BitWear_AvgDiff Predictor-66.8819)*(AvgCycleWOB-79.9826)	0	2	1.9251	1.698	0.20614
<input type="checkbox"/>	<input type="checkbox"/>	(BitWear_AvgDiff Predictor-66.8819)*(Bits_ToothRakeAngle--20)	0	0	0	.	.
<input type="checkbox"/>	<input checked="" type="checkbox"/>	(BitWear_AvgDiff Predictor-66.8819)*(DrillingOrientation-0.01718)	75.7241276	1	9.366442	15.616	0.0006
<input type="checkbox"/>	<input type="checkbox"/>	(BitWear_AvgDiff Predictor-66.8819)*(AbsPercLevel-32.8331)	0	2	1.526238	1.305	0.29146
<input type="checkbox"/>	<input type="checkbox"/>	FixtureName{EDT-PEC}*(DrilSpindleRate-197.933)	0	0	0	.	.



- High priority Mars 2020 program is experimenting to accurately characterize and optimize coring performance
- JMP has enabled JPL engineers to quickly discover relationships with graphical displays and use advanced statistical methods to accurately model complex behavior across a variety of vignettes
- JMP efficiency allows team to focus more on technical challenges rather than data wrangling
- *“I would like to die on Mars—just not on impact”* Elon Musk

# Questions

