

Different goals, different models: How to use models to sharpen up your questions

Ron Kenett and Chris Gotwalt

Agenda

- Intro and a simple example – Ron
 - What is the role of models?
 - The sensor data case study
- A complex example and conclusions – Chris
 - Variable importance and SHAP values
 - More complex models

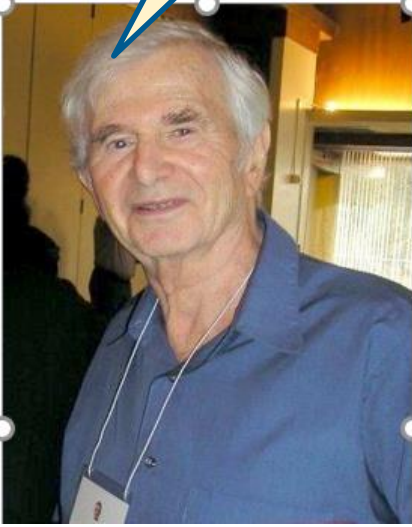
All models are wrong, but some are **useful**



George Box
(1919 – 2013)

Yes, but which ones?

The purpose of models is not to fit the data but to **sharpen the question**



Sam Karlin, 1924-2007

Yes, but how?

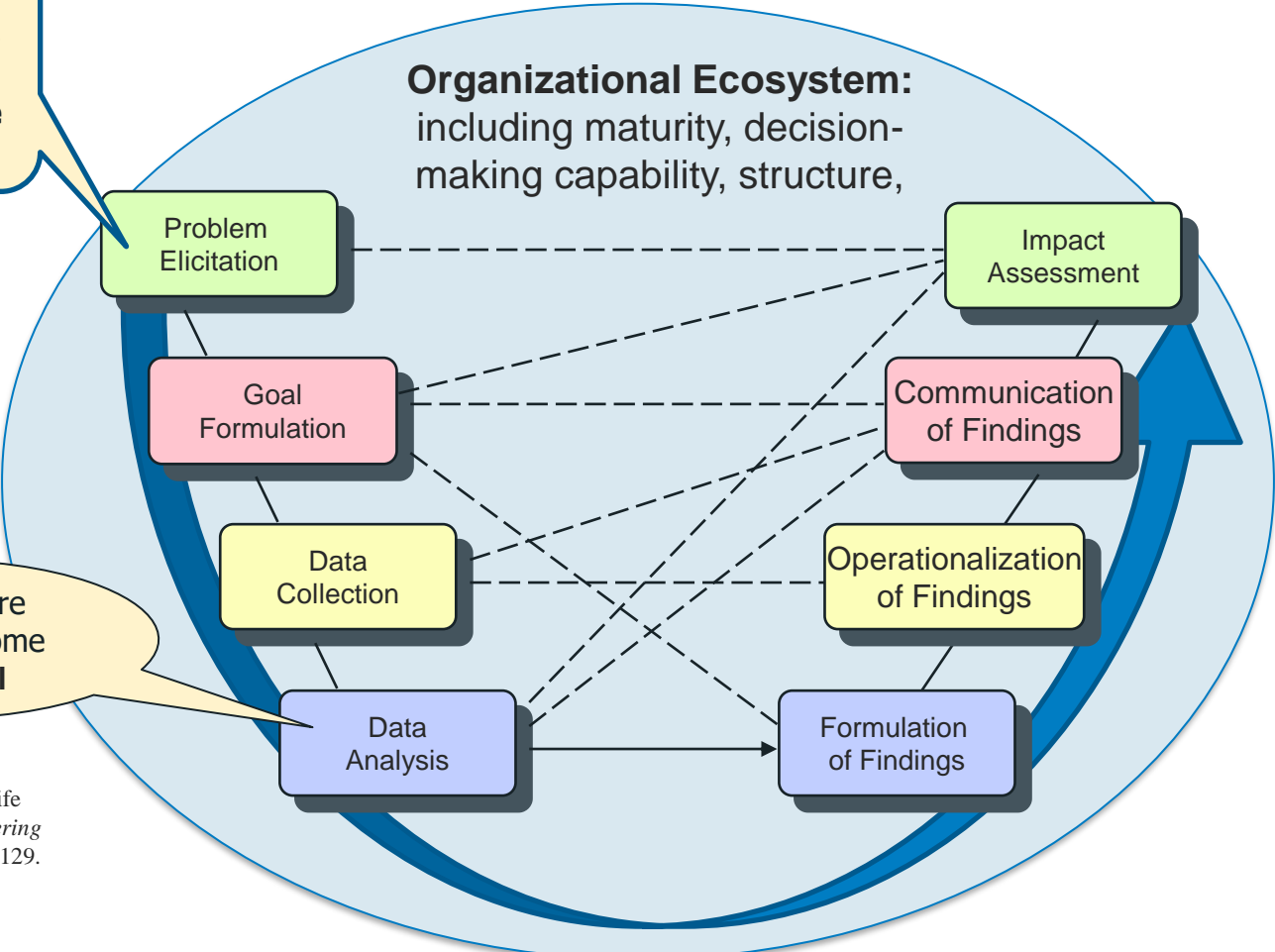
This is the key difference between a model and a computer program
RSK



Pablo Picasso, 1881-1973

"Computers are useless. They can only give you answers"

The purpose of models is not to fit the data but to **sharpen the question**



All models are wrong, but some are **useful**

Kenett (2015) Statistics: A Life Cycle View, *Quality Engineering* (with discussion), 27(1):111-129.

63 sensors, one response

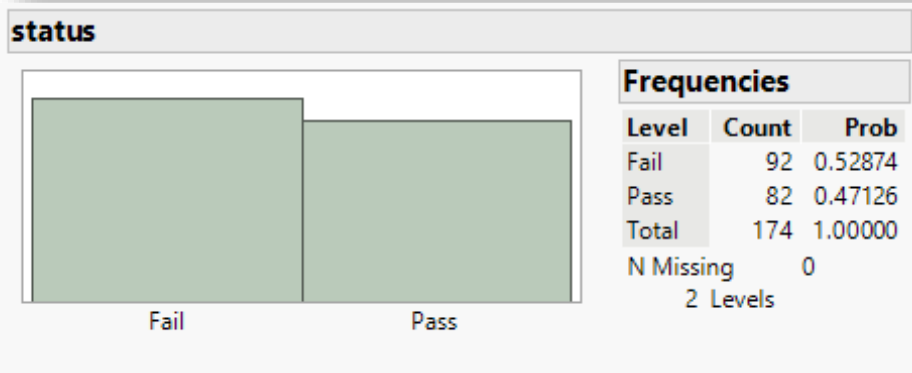
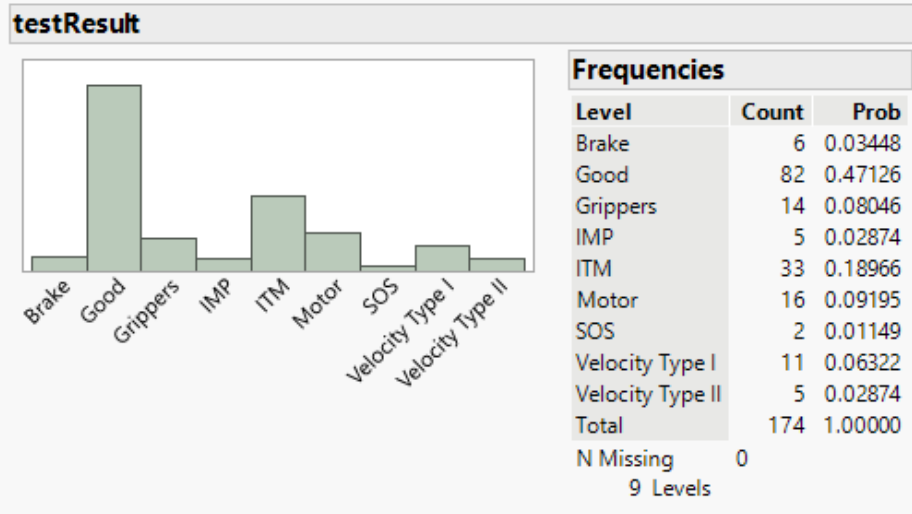


SENSORS.jmp

SENSORS		sensor01	sensor02	sens
Source				
Decision...of status				
Columns (65/1)				
sensor0...tc. (63/0)				
testResult				
status *				
Rows				
All rows	174			

Boosted
Tree

Random
Forrest



Goal: Determine system status from the sensor data



SENSORS.jmp

Achieving this goal would enable us to create on-line quality control and avoid the cost and delays of testing

BT

Boosted Tree - JMP Pro

Builds a decision tree that is a sequence of smaller trees to predict a response.

Select Columns

66 Columns

Enter column name

- sensor01 etc. (63/0)
- testResult
- status
- Validation**

Cast Selected Columns into Roles

Y, Response: status (optional)

X, Factor: sensor01, sensor02, sensor03, sensor04

Weight: optional numeric

Freq: optional numeric

Validation: Validation

By: optional

Action

OK

Cancel

Remove

Recall

Help

Options


Method: Boosted Tree

Validation Portion: 0

Informative Missing

Ordinal Restricts Order

There are two main differences between the gradient boosting trees (BT) and the random forests (RF). **We train the former sequentially, one tree at a time, each to correct the errors of the previous ones. In contrast, we construct the trees in a random forest independently**

 Boosted Tree

Gradient-Boosted

Boosted trees (BT) are derived by optimizing an objective function. They can be used to solve most objective functions. **This includes Poisson regression which is harder to achieve with RF.**

 BT

Boosting

Number of Layers:

Splits per Tree:

Learning Rate:

Overfit Penalty:

Minimum Size Split:

Multiple Fits

Multiple Fits over Splits and Learning Rate

Max Splits Per Tree

Max Learning Rate

Use Tuning Design Table

Stochastic Boosting

Row Sampling Rate

Column Sampling Rate

Reproducibility

Suppress Multithreading

Random Seed

BT training generally takes longer than RF because trees are built sequentially. There are typically three parameters: number of trees, depth of trees and learning rate.

OK

Cancel

Boosted Tree for status

Specifications

Target	status	Number of training rows:	131
Validation Column:	Validation	Number of validation rows:	43
Number of Layers:	122		
Splits per Tree:	2		
Learning Rate:	0.036		
Overfit Penalty:	0.0001		

Overall Statistics

Measure	Training	Validation	Definition
Entropy RSquare	0.9981	0.5788	$1 - \text{Loglike}(\text{model}) / \text{Loglike}(0)$
Generalized RSquare	0.9991	0.7352	$(1 - (L(0)/L(\text{model}))^{2/n}) / (1 - L(0)^{2/n})$
Mean -Log p	0.0013	0.2909	$\sum -\text{Log}(p[j]) / n$
RASE	0.0025	0.2649	$\sqrt{\sum (y[j] - p[j])^2 / n}$
Mean Abs Dev	0.0013	0.0875	$\sum y[j] - p[j] / n$
Misclassification Rate	0.0000	0.0930	$\sum (p[j] \neq p\text{Max}) / n$
N	131	43	n

Confusion Matrix

Training			Validation		
Actual	Predicted Count		Actual	Predicted Count	
status	Fail	Pass	status	Fail	Pass
Fail	69	0	Fail	20	3
Pass	0	62	Pass	1	19

Actual	Predicted Rate	
status	Fail	Pass
Fail	1.000	0.000
Pass	0.000	1.000

Actual	Predicted Rate	
status	Fail	Pass
Fail	0.870	0.130
Pass	0.050	0.950

BT

9.3%

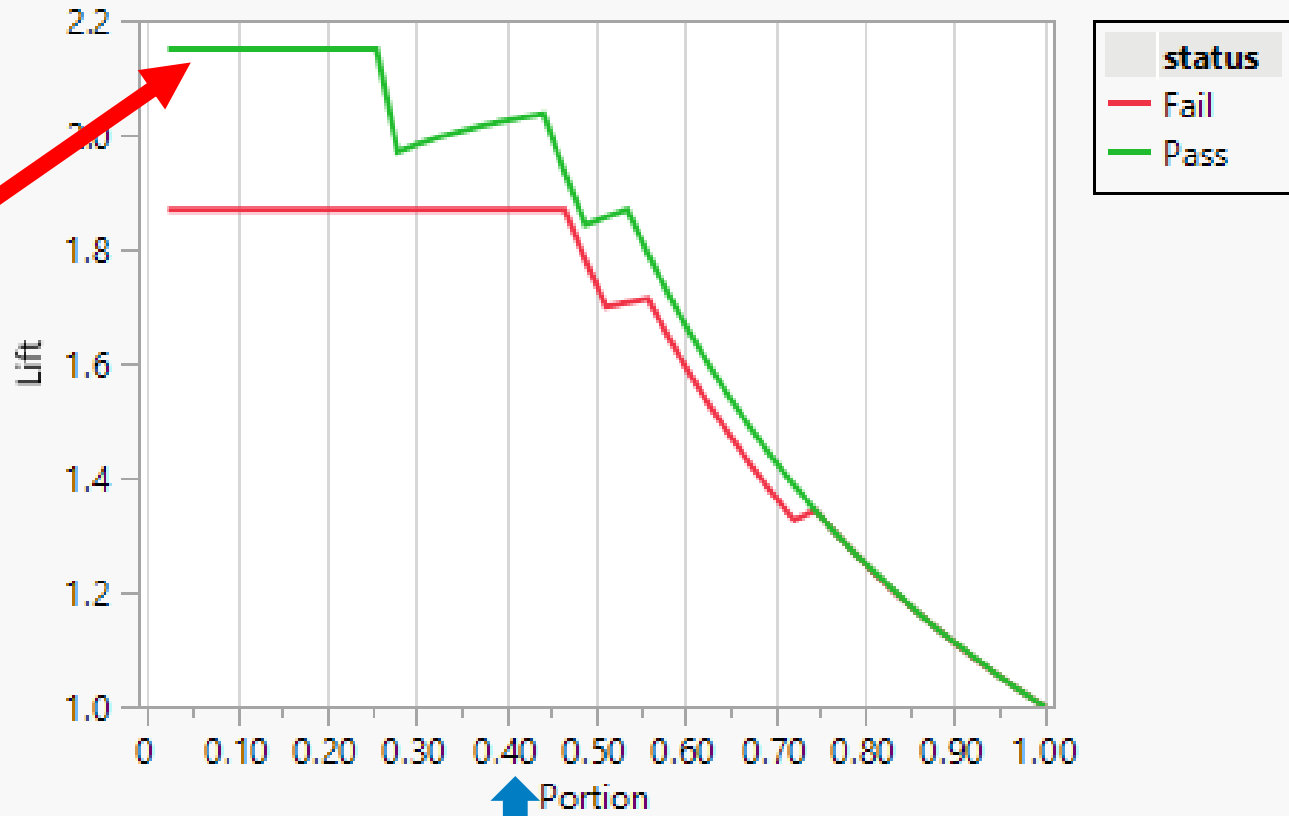
Actual Validation Pass = 20
of these, predicted Pass = 19
False predicted Pass = 3 (13%)

Column Contributions

Term	Number of Splits	G^2	Portion
sensor56	82	4634.8525	0.2065
sensor18	27	4200.54219	0.1872
sensor11	21	2735.54419	0.1219
sensor61	19	2431.70533	0.1084
sensor48	17	2414.82121	0.1076
sensor57	22	2016.84895	0.0899
sensor58	10	1456.34648	0.0649
sensor59	8	726.693834	0.0324
sensor26	2	343.87221	0.0153
sensor52	2	323.166652	0.0144
sensor09	6	286.922646	0.0128
sensor01	9	194.974174	0.0087
sensor55	2	165.247012	0.0074
sensor24	4	151.216612	0.0067
sensor07	4	128.858022	0.0057
sensor12	4	117.421132	0.0052
sensor15	2	44.7671089	0.0020
sensor44	1	37.6713347	0.0017
sensor54	1	15.5711294	0.0007
sensor27	1	12.8974036	0.0006

...some overfitting

Lift Curve on Validation Data



BT

Bootstrap Forest - JMP Pro

Builds a collection of decision trees using random sampling and averages the results to predict a response.

Select Columns

66 Columns

Enter column name

- sensor01 etc. (63/0)
- testResult
- status
- Validation

Cast Selected Columns into Roles

Y, Response: status (optional)

X, Factor: sensor01, sensor02, sensor03, sensor04

Weight: optional numeric

Freq: optional numeric

Validation: Validation

By: optional

Action

OK

Cancel

Remove

Recall

Help

Options

Method: Bootstrap Forest

Validation Portion: 0

Informative Missing

Ordinal Restricts Order

RF

For features with categorical variables and missing data use BT



RF algorithm with a large number of trees is slow. For categorical variables with different number of levels, RF are biased in favor of attributes with more levels. RF is much easier to tune than BT

Bootstrap Forest

Bootstrap Forest Specification

Number of Rows: 174
Number of Terms: 63

Forest

Number of Trees in the Forest: 1000

Number of Terms Sampled per Split: 49

Bootstrap Sample Rate: 1

Minimum Splits per Tree: 10

Maximum Splits per Tree: 2000

Minimum Size Split: 5

Early Stopping

Multiple Fits

Multiple Fits over Number of Terms
Max Number of Terms: 49

Use Tuning Design Table

Reproducibility

Suppress Multithreading
Random Seed: 0

OK Cancel

There are typically two parameters in RF: number of trees and number of features to be selected at each node.

Bootstrap Forest for status

Specifications

Target	status	Training Rows:	131
Validation Column:	Validation	Validation Rows:	43
		Test Rows:	0
Number of Trees in the Forest:	1000	Number of Terms:	63
Number of Terms Sampled per Split:	49	Bootstrap Samples:	131
		Minimum Splits per Tree:	10
		Minimum Size Split:	5

Actual Validation Pass = 20
of these, predicted Pass = 20
False predicted Pass = 3 (13%)

Overall Statistics

Measure	Training	Validation	Definition
Entropy RSquare	0.9186	0.6736	1-Loglike(model)/Loglike(0)
Generalized RSquare	0.9601	0.8089	$(1-L(0)/L(model))^{2/n} / (1-L(0)^{2/n})$
Mean -Log p	0.0563	0.2254	$\sum -\log(p[j])/n$
RASE	0.1016	0.2543	$\sqrt{\sum (y[j]-p[j])^2/n}$
Mean Abs Dev	0.0491	0.1253	$\sum y[j]-p[j] /n$
Misclassification Rate	0.0076	0.0698	$\sum (p[j] \neq pMax)/n$
N	131	43	n

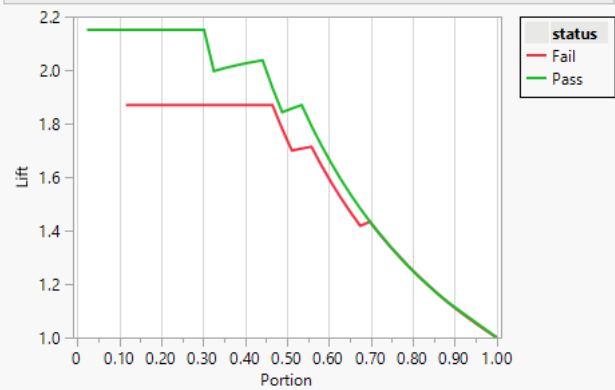


Confusion Matrix

Training			Validation		
Actual	Predicted Count		Actual	Predicted Count	
status	Fail	Pass	status	Fail	Pass
Fail	68	1	Fail	20	3
Pass	0	62	Pass	0	20

Actual	Predicted Rate		Actual	Predicted Rate	
status	Fail	Pass	status	Fail	Pass
Fail	0.986	0.014	Fail	0.870	0.130
Pass	0.000	1.000	Pass	0.000	1.000

Lift Curve on Validation Data



Bootstrap Forest for testResult

Specifications

Target	testResult	Training Rows:	131
Validation Column:	Validation	Validation Rows:	43
		Test Rows:	0
Number of Trees in the Forest:	1000	Number of Terms:	63
Number of Terms Sampled per Split:	49	Bootstrap Samples:	131
		Minimum Splits per Tree:	10
		Minimum Size Split:	5

Overall Statistics

Measure	Training	Validation	Definition
Entropy RSquare	0.8203	0.5474	$1 - \text{Loglike}(\text{model}) / \text{Loglike}(0)$
Generalized RSquare	0.9669	0.8703	$(1 - (L(0) / L(\text{model}))^{2/n}) / (1 - L(0) / L(\text{model}))$
Mean -Log p	0.2871	0.7564	$\sum -\text{Log}(p_{ij}) / n$
RASE	0.3070	0.4699	$\sqrt{\sum (y_{ij} - p_{ij})^2 / n}$
Mean Abs Dev	0.1982	0.3136	$\sum y_{ij} - p_{ij} / n$
Misclassification Rate	0.0534	0.2326	$\sum (p_{ij} \neq \text{Max}) / n$
N	131	43	n

RF

23.4%

Actual Validation Good = 20
of these, predicted Good = 20
False predicted Good = 5 (20%)

For detailed testResults

Confusion Matrix

Actual testResult	Training								
	Predicted Count								
	Brake	Good	Grippers	IMP	ITM	Motor	SOS	Velocity Type I	Velocity Type II
Brake	2	0	0	0	0	1	0	0	0
Good	0	62	0	0	0	0	0	0	0
Grippers	0	1	7	0	1	0	0	0	0
IMP	0	1	0	3	0	0	0	0	0
ITM	0	1	0	0	25	1	0	0	0
Motor	0	0	0	0	0	13	0	0	0
SOS	0	0	0	0	1	0	1	0	0
Velocity Type I	0	0	0	0	0	0	0	9	0
Velocity Type II	0	0	0	0	0	0	0	0	2

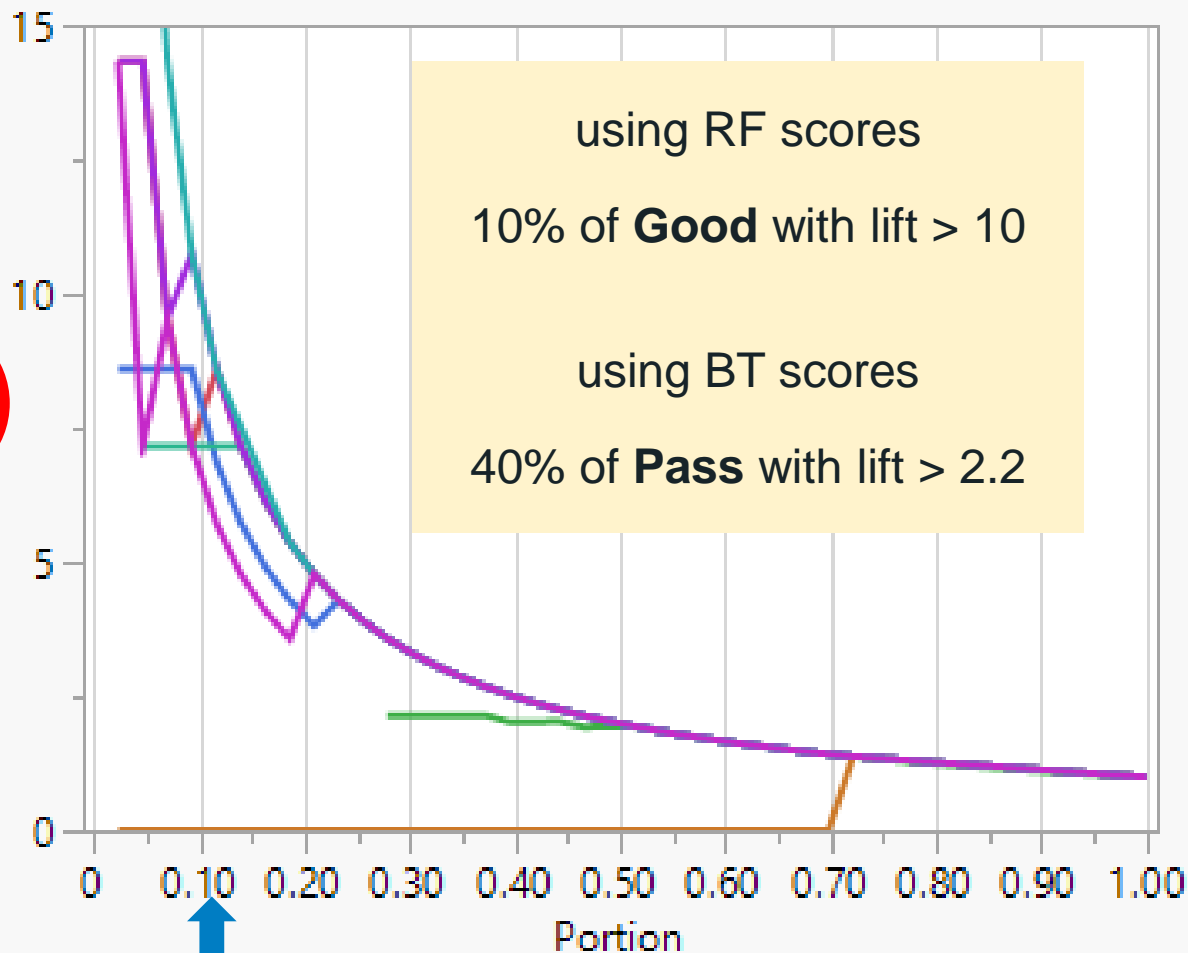
Actual testResult	Validation								
	Predicted Count								
	Brake	Good	Grippers	IMP	ITM	Motor	SOS	Velocity Type I	Velocity Type II
Brake	0	1	0	2	0	0	0	0	0
Good	0	20	0	0	0	0	0	0	0
Grippers	0	1	1	0	2	1	0	0	0
IMP	0	1	0	0	0	0	0	0	0
ITM	0	0	0	0	6	0	0	0	0
Motor	0	0	0	0	0	3	0	0	0
SOS	0	0	0	0	0	0	0	0	0
Velocity Type I	0	0	0	0	0	0	0	2	0
Velocity Type II	0	2	0	0	0	0	0	0	1

Actual testResult	Predicted Rate								
	Predicted Rate								
	Brake	Good	Grippers	IMP	ITM	Motor	SOS	Velocity Type I	Velocity Type II
Brake	0.667	0.000	0.000	0.000	0.000	0.333	0.000	0.000	0.000
Good	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
Grippers	0.000	0.111	0.778	0.000	0.111	0.000	0.000	0.000	0.000
IMP	0.000	0.250	0.000	0.750	0.000	0.000	0.000	0.000	0.000
ITM	0.000	0.037	0.000	0.000	0.926	0.037	0.000	0.000	0.000
Motor	0.000	0.000	0.000	0.000	0.000	1.000	0.000	0.000	0.000
SOS	0.000	0.000	0.000	0.000	0.500	0.000	0.500	0.000	0.000
Velocity Type I	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000
Velocity Type II	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000

Actual testResult	Predicted Rate								
	Predicted Rate								
	Brake	Good	Grippers	IMP	ITM	Motor	SOS	Velocity Type I	Velocity Type II
Brake	0.000	0.333	0.000	0.667	0.000	0.000	0.000	0.000	0.000
Good	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
Grippers	0.000	0.200	0.200	0.000	0.400	0.200	0.000	0.000	0.000
IMP	0.000	1.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
ITM	0.000	0.000	0.000	0.000	1.000	0.000	0.000	0.000	0.000
Motor	0.000	0.000	0.000	0.000	0.000	1.000	0.000	0.000	0.000
SOS	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
Velocity Type I	0.000	0.000	0.000	0.000	0.000	0.000	0.000	1.000	0.000
Velocity Type II	0.000	0.667	0.000	0.000	0.000	0.000	0.000	0.000	0.333

Lift Curve on Validation Data

RF



testResult

- Brake
- Good
- Grippers
- IMP
- ITM
- Motor
- SOS
- Velocity Type I
- Velocity Type II

Do we want to
Identify top score Good?
or predict a high
proportion of Pass?





Boosted Tree for status

Column Contributions

Term	Number of Splits	G^2	Portion
sensor56	82	4634.8525	0.2065
sensor18	27	4200.54219	0.1872
sensor11	21	2735.54419	0.1219
sensor61	19	2431.70533	0.1084
sensor48	17	2414.82121	0.1076
sensor57	22	2016.84895	0.0899
sensor58	10	1456.34648	0.0649
sensor59	8	726.693834	0.0324
sensor26	2	343.87221	0.0153
sensor52	2	323.166652	0.0144
sensor09	6	286.922646	0.0128
sensor01	9	194.974174	0.0087
sensor55	2	165.247012	0.0074
sensor24	4	151.216612	0.0067
sensor07	4	128.858022	0.0057
sensor12	4	117.421132	0.0052
sensor15	2	44.7671089	0.0020
sensor44	1	37.6713347	0.0017
sensor54	1	15.5711294	0.0007
sensor27	1	12.8974036	0.0006

Bootstrap Forest for status

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	579	54.9167342	0.5024
sensor61	198	18.7389273	0.1714
sensor52	145	13.1320295	0.1201
sensor53	56	5.26374221	0.0482
sensor44	33	2.53070023	0.0232
sensor48	42	2.45696551	0.0225
sensor46	31	2.08993095	0.0191
sensor11	114	1.34630042	0.0123
sensor54	12	1.01688952	0.0093
sensor58	111	0.73127415	0.0067
sensor07	61	0.68014104	0.0062
sensor26	89	0.5292647	0.0048
sensor12	40	0.51092374	0.0047
sensor50	8	0.41943383	0.0038
sensor57	75	0.3901658	0.0036
sensor01	44	0.35310066	0.0032
sensor05	47	0.3400086	0.0031
sensor21	8	0.30245908	0.0028

Bootstrap Forest for testResult

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	5	54.8827138	0.2325
sensor52	3	29.2773568	0.1240
sensor48	2	18.0919607	0.0766
sensor61	1	12.7377835	0.0540
sensor04	4	11.2268386	0.0476
sensor62	3	9.74427579	0.0413
sensor19	4	8.91209343	0.0378
sensor17	2	7.31785078	0.0310
sensor40	1	6.4025967	0.0271
sensor50	1	5.95404634	0.0252
sensor63	1	5.83025113	0.0247
sensor28	1	5.71751006	0.0242
sensor42	1	5.48313999	0.0232
sensor41	1	5.20440610	0.0220
sensor36			0.0214
sensor07			0.207
sensor05			0.0181
sensor57	4	4.25005910	0.0180
sensor53	2	3.88027473	0.0164

For detailed testResults

What is your goal?

Bootstrap Forest - JMP

Builds a collection of decision trees using random sampling and averages the results to predict a response.

Select Columns

67 Columns

Enter column name

- sensor01 etc. (63/1)
- testResult
- status
- Bad Validation
- Stratified Validation

Cast Selected Columns into Roles

Y, Response: status

X, Factor: sensor01, sensor02, sensor03, sensor04

Weight: optional numeric

Freq: optional numeric

Validation: Stratified Validation

By: optional

Options

Method: Bootstrap Forest

Validation Portion: 0

Informative Missing

Ordinal Restricts Order

Action

OK

Cancel

Remove

Recall

Help

Bootstrap Forest

Bootstrap Forest Specification

Number of Rows: 174
Number of Terms: 63

Forest

Number of Trees in the Forest: 1000
Number of Terms Sampled per Split: 49
Bootstrap Sample Rate: 1
Minimum Splits per Tree: 10
Maximum Splits per Tree: 2000
Minimum Size Split: 5

Early Stopping

Multiple Fits

Multiple Fits over Number of Terms
Max Number of Terms: 49

Use Tuning Design Table

Reproducibility

Suppress Multithreading
Random Seed: 0

OK Cancel

RF

Column Contributions

Term	Number of Splits	G ²	Portion
sensor18	522	36.5630568	0.3709
sensor53	248	19.0040464	0.1928
sensor55	163	9.18530792	0.0932
sensor48	107	7.43395874	0.0754
sensor52	88	4.51699905	0.0458
sensor54	65	3.1209684	0.0317
sensor61	48	3.08165918	0.0313
sensor11	76	2.20715869	0.0224
sensor21	44	1.8102253	0.0184
sensor46	31	0.98045171	0.0099
sensor24	37	0.97068784	0.0098
sensor50	33	0.77981921	0.0079
sensor44	15	0.75054722	0.0076
sensor26	67	0.74422853	0.0075
sensor17	36	0.52835424	0.0054

Binomial Ridge with Validation Column

Parameter Estimates for Original Predictors

Term	Estimate	Std Error	Wald ChiSquare	Prob > ChiSquare
Intercept	-5.678926	10.351753	0.3009571	0.5833
sensor57	0.0074349	0.0192829	0.1486652	0.6998
sensor58	-0.004759	0.0174843	0.0740924	0.7855
sensor22	0.0001382	0.0007282	0.0360128	0.8495
sensor59	0.0027809	0.0155676	0.0319105	0.8582
sensor23	0.0001047	0.0007698	0.0184902	0.8918
sensor49	-0.023623	0.1845799	0.0163801	0.8982
sensor20	0.0000964	0.0010633	0.0082211	0.9278
sensor21	8.8042e-5	0.0011147	0.006238	0.9370
sensor29	0.0001312	0.0017377	0.0056977	0.9398
sensor17	0.3125492	4.2247778	0.005473	0.9410
sensor56	-0.00097	0.0160737	0.0036419	0.9519
sensor41	-0.000499	0.0085741	0.0033923	0.9536
sensor37	-0.000381	0.0074011	0.0026455	0.9590
sensor63	0.0080211	0.1920101	0.0017451	0.9667

Binomial Lasso with Validation Column

Parameter Estimates for Original Predictors

Term	Estimate	Std Error	Wald ChiSquare	Prob > ChiSquare
sensor17	1.0154108	0.4506304	5.077413	0.0242*
Intercept	-3.287154	2.1404982	2.3583615	0.1246
sensor21	0.0003969	0.0003088	1.6521055	0.1987
sensor52	0.0493613	0.0486158	1.0309056	0.3099
sensor20	0.0001786	0.0002831	0.3980931	0.5281
sensor18	0.3648566	0.6438341	0.3211415	0.5709
sensor29	8.7425e-5	0.0003001	0.0848859	0.7708
sensor01	6.9577e-5	0.000528	0.0173639	0.8952
sensor02	0	0	0	1.0000
sensor03	0	0	0	1.0000
sensor04	0	0	0	1.0000
sensor05	0	0	0	1.0000
sensor06	0	0	0	1.0000
sensor07	0	0	0	1.0000
sensor08	0	0	0	1.0000

Binomial Elastic Net with Validation Column

Parameter Estimates for Original Predictors

Term	Estimate	Std Error	Wald ChiSquare	Prob > ChiSquare
Intercept	-4.563879	2.0946723	4.7471847	0.0293*
sensor17	0.9999637	0.7369391	1.8412183	0.1748
sensor52	0.0524902	0.0574976	0.8334072	0.3613
sensor29	0.0002216	0.0002958	0.5615393	0.4536
sensor20	0.0002296	0.0003917	0.3437918	0.5576
sensor21	0.0002095	0.000441	0.2255527	0.6348
sensor22	0.0001835	0.0004571	0.1611644	0.6881
sensor18	0.3325641	0.8331405	0.1593361	0.6898
sensor01	0.0001942	0.0006893	0.0793924	0.7781
sensor04	0.0001689	0.0006879	0.0602512	0.8061
sensor11	-5.539e-5	0.0011937	0.0021528	0.9630
sensor57	9.2889e-5	0.014103	4.3382e-5	0.9947
sensor02	0	0	0	1.0000
sensor03	0	0	0	1.0000
sensor05	0	0	0	1.0000



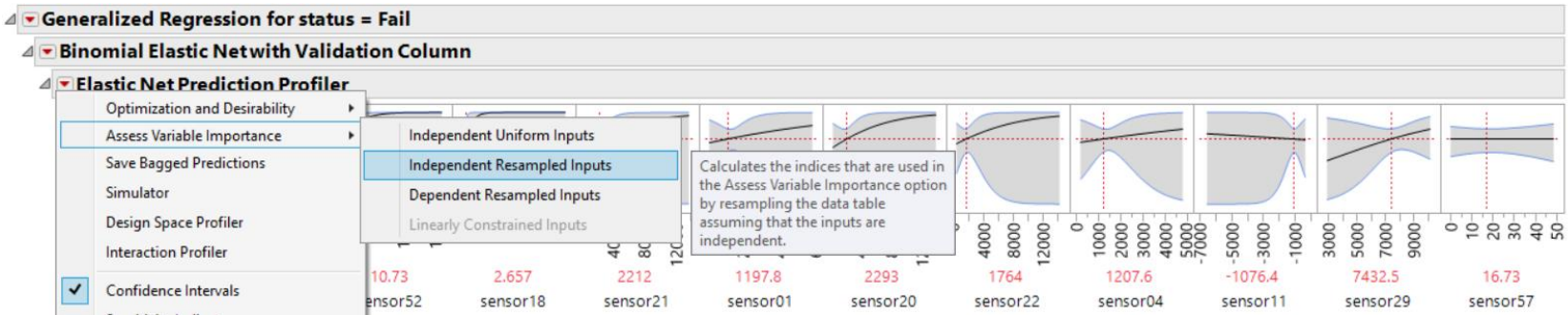
Binomial Elastic Net with Validation Column

Parameter Estimates for Original Predictors

Term	Estimate	Std Error	Wald ChiSquare	Prob > ChiSquare ^
Intercept	-4.563879	2.0946723	4.7471847	0.0293*
sensor17	0.9999637	0.7369391	1.8412183	0.1748
sensor52	0.0524902	0.0574976	0.8334072	0.3613
sensor29	0.0002216	0.0002958	0.5615393	0.4536
sensor20	0.0002296	0.0003917	0.3437918	0.5576
sensor21	0.0002095	0.000441	0.2255527	0.6348
sensor22	0.0001835	0.0004571	0.1611644	0.6881
sensor18	0.3325641	0.8331405	0.1593361	0.6898
sensor01	0.0001942	0.0006893	0.0793924	0.7781
sensor04	0.0001689	0.0006879	0.0602512	0.8061
sensor11	-5.539e-5	0.0011937	0.0021528	0.9630
sensor57	9.2889e-5	0.014103	4.3382e-5	0.9947
sensor02	0	0	0	1.0000
sensor03	0	0	0	1.0000
sensor05	0	0	0	1.0000

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	522	36.5630568	0.3709
sensor53	248	19.0040464	0.1928
sensor55	163	9.18530792	0.0932
sensor48	107	7.43395874	0.0754
sensor52	88	4.51699905	0.0458
sensor54	65	3.1209684	0.0317
sensor61	48	3.08165918	0.0313
sensor11	76	2.20715869	0.0224
sensor21	44	1.8102253	0.0184
sensor46	31	0.98045171	0.0099
sensor24	37	0.97068784	0.0098
sensor50	33	0.77981921	0.0079
sensor44	15	0.75054722	0.0076
sensor26	67	0.74422853	0.0075
sensor17	36	0.52835424	0.0054





▼ Elastic Net Prediction Profiler

▼ Variable Importance: Independent Resampled Inputs

Summary Report

Column	Main Effect	Total Effect	.2	.4	.6	.8
sensor17	0.179	0.233				
sensor52	0.178	0.227				
sensor18	0.173	0.216				
sensor20	0.098	0.136				
sensor21	0.093	0.128				
sensor22	0.036	0.063				
sensor01	0.02	0.038				
sensor29	0.02	0.036				
sensor04	0.014	0.026				
sensor11	0.001	0.002				
sensor57	9e-6	3e-5				

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	522	36.5630568	0.3709
sensor53	248	19.0040464	0.1928
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sensor26	67	0.74422853	0.0075
sensor17	36	0.52835424	0.0054

Model Driven Multivariate Control Chart - JMP

Creates multivariate control charts based on principal components or partial least squares methods.

Select Columns

157 Columns

Enter column name

- Sensor Measurements (63/0)
- testResult
- status
- Stratified Validation

Historical Data End at Row 81

Cast Selected Columns into Roles

Process

- sensor01
- sensor02
- sensor03
- sensor04

Time ID optional numeric

By optional

Action

OK

Cancel

Remove

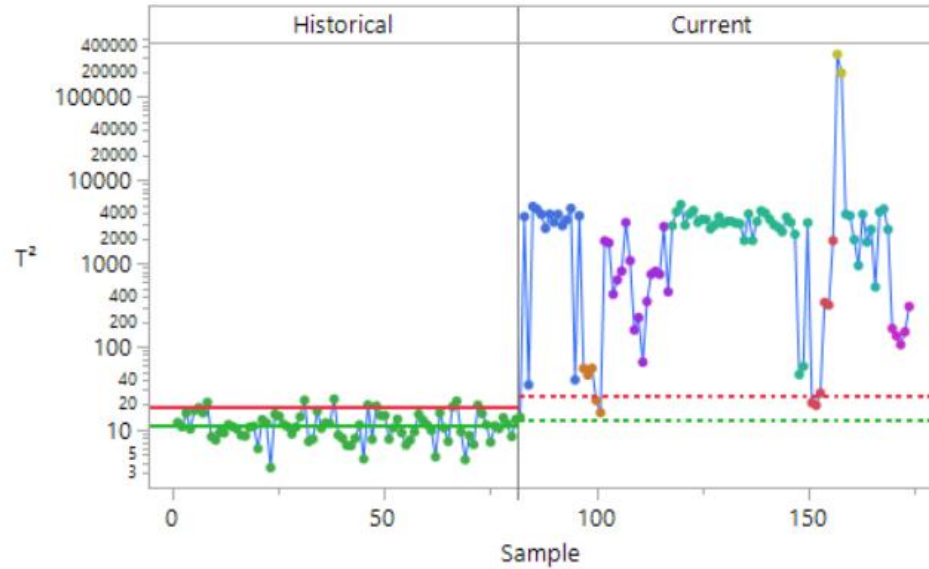
Recall

Help

PCA Model Driven Multivariate Control Chart

Monitor the Process

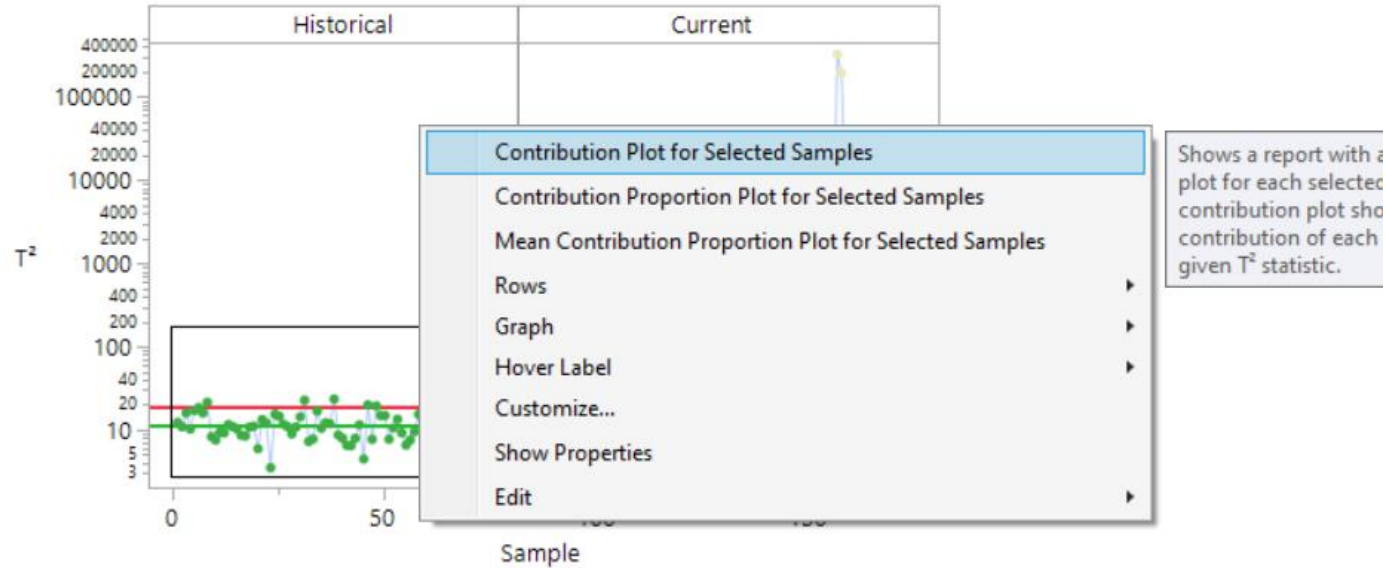
T² for 13 Principal Components



PCA Model Driven Multivariate Control Chart

Monitor the Process

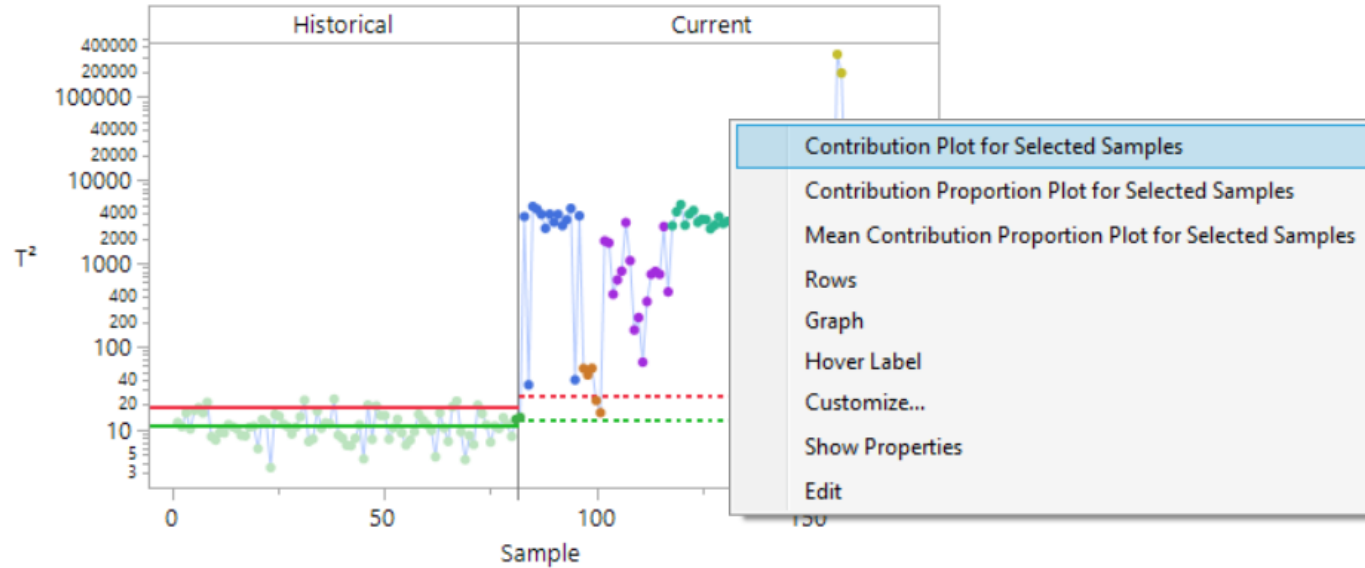
T² for 13 Principal Components



PCA Model Driven Multivariate Control Chart

Monitor the Process

T² for 13 Principal Components

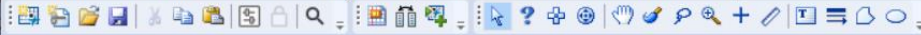


T² Contribution Plot for status=Pass



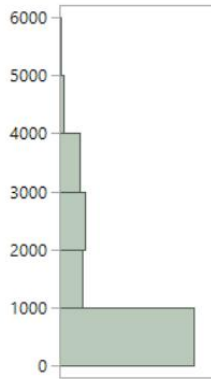
T² Contribution Plot for status=Fail



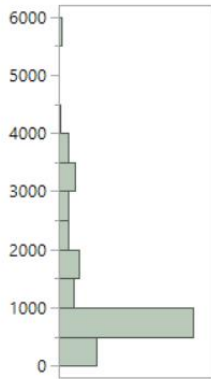


Distributions

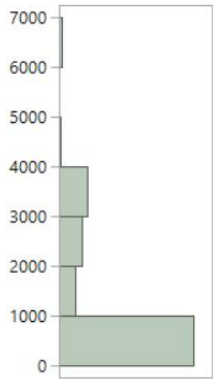
sensor01



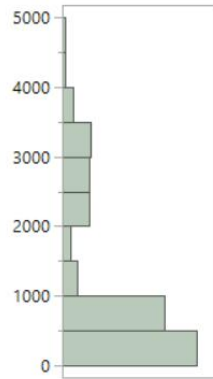
sensor02



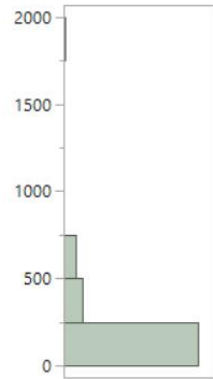
sensor03



sensor04



sensor05



The screenshot shows the JMP software interface. The 'Continuous Fit' menu is open, listing various distribution options. 'Fit Johnson' is highlighted. Below the menu, three histograms are displayed for 'sensor03', 'sensor04', and 'sensor05'. A tooltip for the 'Fit Johnson' option states: 'Fits a Johnson distribution to the data. The most appropriate of the three types of Johnson distributions (Su, Sb, and SI) is chosen based on the quantiles.'

Sensors July 13 2022 - Distribution 2 - JMP

File Edit Tables Rows Cols DOE Analyze Graph Tools Add-Ins View Window Help

Distributions

sensor01

Compare Distributions

Show	Distribution	AICc ^	BIC	-2*LogLikelihood
<input checked="" type="checkbox"/>	Johnson Sb	2788.5753	2800.9748	2780.3386

Fitted Johnson Sb Distribution

	Error	Lower 95%	Upper 95%
Density Curve			
Diagnostic Plots	8516	0.5992993	0.9789505
Profilers	8686	0.3526331	0.4543076

Save Columns

Process Capability

Remove Fit

AICc 2788.5753

BIC 2800.9748

Save Transformed

Saves a column to the data table that contains a formula used to transform the analysis column to normality using the specified fitted distribution.

sensor02

Compare Distributions

Show	Distribution	AICc ^	BIC	-2*LogLikelihood
<input checked="" type="checkbox"/>	Johnson Su	2706.2838	2718.6833	2698.0471

Fitted Johnson Su Distribution

Parameter	Estimate	Std Error	Lower 95%	Upper 95%
Shape γ	-1.107392	0.1247941	-1.351984	-0.8628
Shape δ	0.6756394	0.0374785	0.6060352	0.7532377
Location θ	486.20761	23.684068	439.78769	532.62753
Scale σ	113.62197	0	113.62197	113.62197

Measures

-2*LogLikelihood 2698.0471

sensor03

Compare Distributions

Show	Distribution	AICc ^	BIC	-2*LogLikelihood
<input checked="" type="checkbox"/>	Johnson Sb	2880.6212	2893.0207	2877.3845

Fitted Johnson Sb Distribution

Parameter	Estimate	Std Error	Lower 95%	Upper 95%
Shape γ	0.7891857	0.1150968	0.5636002	1.0147712
Shape δ	0.4247852	0.0279451	0.3733978	0.4832445
Location θ	194.59048	52.238366	92.205161	296.97579
Scale σ	6780.8524	0	6780.8524	6780.8524

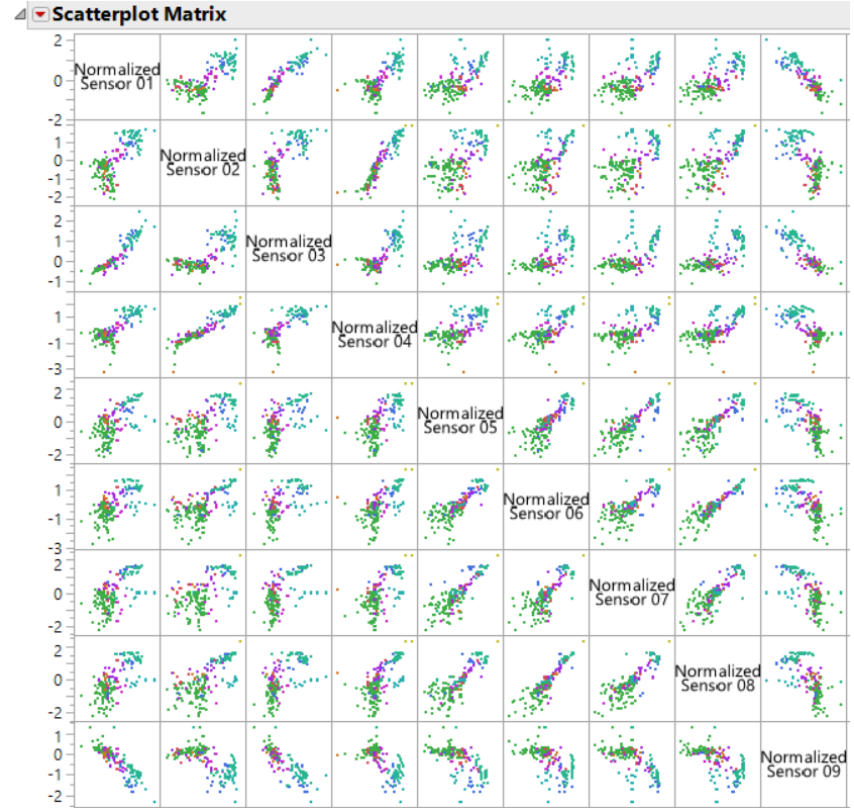
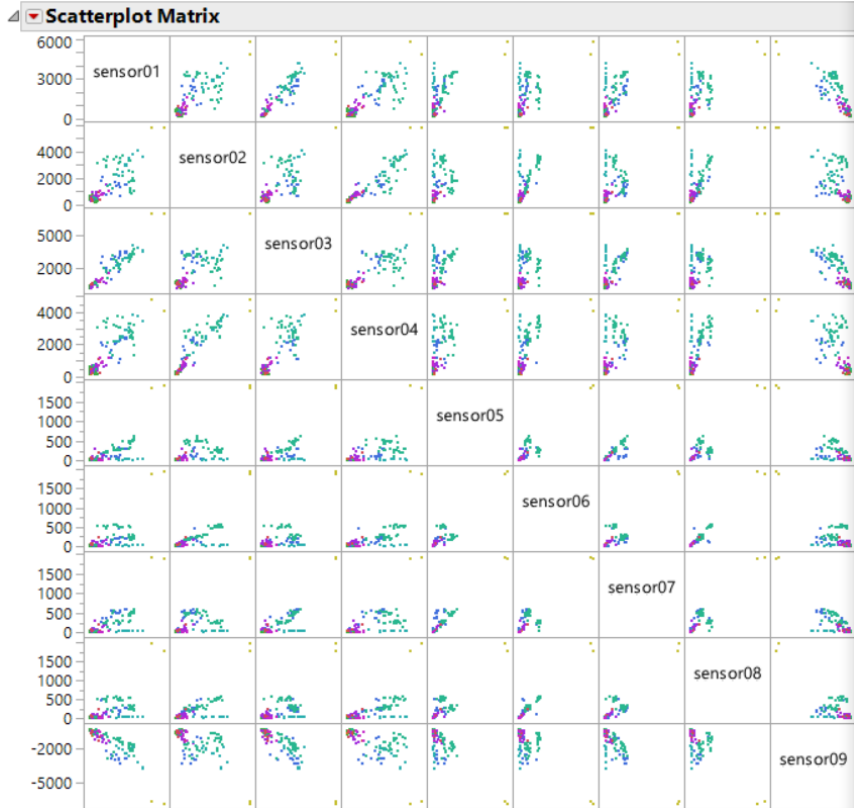
Measures

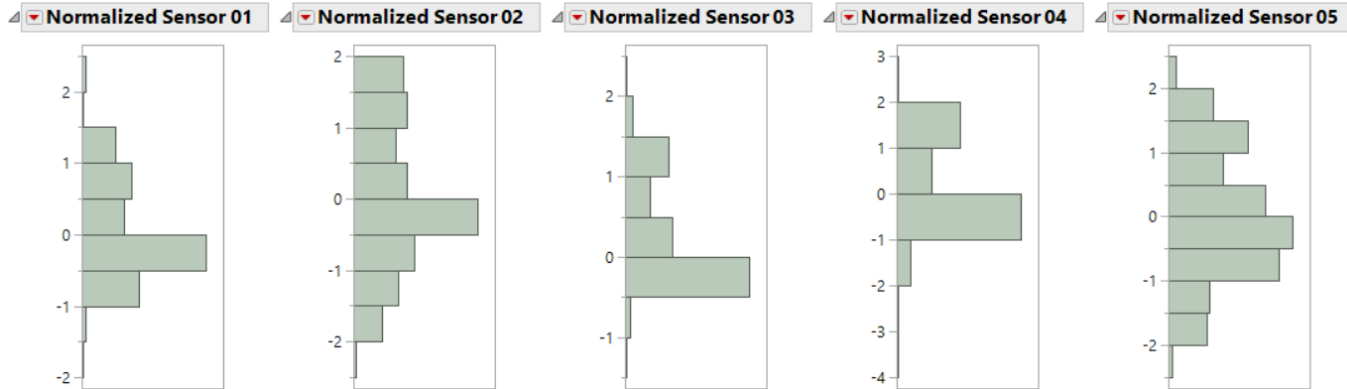
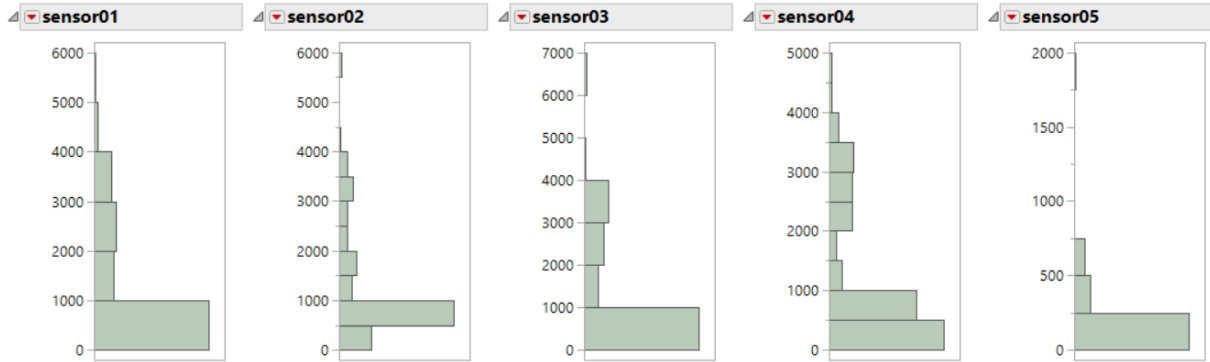
-2*LogLikelihood 2872.3845

AICc 2880.6212

BIC 2893.0207

	Normalized Sensor 01	Normalized Sensor 02	Normalized Sensor 03	Normalized Sensor 04	Normalized Sensor 05	Normalized Sensor 06	Normalized Sensor 07	Normalized Sensor 08
1	-0.429462541	-0.023164209	-0.180868093	-0.045175325	0.2103355703	-0.013999938	-0.147937751	-0.000344392
2	-0.055300886	-1.63236901	0.0946350653	-1.649470993	-1.009090647	-1.042115859	-1.120255017	-1.525902819
3	-0.111839132	-0.187981022	0.0190318601	-0.321027105	0.0413421482	-0.274633425	-0.277695263	-0.53213534
4	-0.545119593	-0.394709423	-0.250233244	-0.502509817	-0.35310491	-0.19353877	-0.09709766	-0.969841771
5	-0.592368033	-0.381589246	-0.202267621	-0.067493582	-0.021463294	-0.083870644	-0.131019005	-0.055471228
6	0.0314637112	-2.059472445	0.0999572363	-1.329631387	-0.047036417	-0.310192693	-0.124253218	-0.525600034
7	-0.768441134	-0.068940672	-0.417092494	0.0214536018	-0.420836258	-0.424783097	-0.262673168	-0.762969287
8	-0.30113471	-0.3561646	-0.139427747	-0.229023302	-0.523040338	-0.000297651	-0.046667654	0.133640498
9	-0.860416254	-0.790455797	-0.458553392	-0.622679123	-1.647412021	-0.44909209	-0.591129387	-0.670397594
10	-0.516276499	-0.09857755	-0.194884031	-0.159489881	-1.334245723	-0.871892236	-0.866731627	-0.635561702
11	-0.447437398	-0.337014942	-0.285230865	-0.233164785	0.0729605379	-0.303294366	0.041864424	-0.947967663
12	-0.247673385	-0.168014048	-0.027250896	-0.184571798	-1.529483355	-1.024703913	-1.240298412	-0.993812537
13	-0.482567866	-0.919694837	-0.201434875	-0.716976459	-2.034307511	-0.532455295	-0.752553719	-0.648544939
14	-0.22067253	-0.744586147	-0.112670362	-0.494764669	-0.30377406	-2.456479871	-0.239149348	-1.247260093
15	-0.291032767	-0.084932408	-0.116938339	-0.205684568	-1.44825592	-1.926141272	-1.261958747	-1.125094932





Cluster Variables - JMP

Clusters variables (columns) into groups of highly correlated variables.

Select Columns

157 Columns

Enter column name

- Sensor Measurements (63/0)
 - testResult
 - status
 - Stratified Validation
 - Johnson Sensor Measurements (63/0)
 - Normalized Sensor 01
 - Normalized Sensor 02

Cast Selected Columns into Roles

Y, Columns

- Normalized Sensor 01
- Normalized Sensor 02
- Normalized Sensor 03
- Normalized Sensor 04

Weight optional numeric

Freq optional numeric

By optional

Action

OK

Cancel

Remove

Recall

Help

Cluster Summary

Cluster	Number of Members	Most Representative Variable	Cluster Proportion of Variation Explained	Total Proportion of Variation Explained
1	25	Normalized Sensor 46	0.797	0.316
2	10	Normalized Sensor 36	0.77	0.122
3	7	Normalized Sensor 38	0.818	0.091
4	4	Normalized Sensor 31	0.622	0.04
5	5	Normalized Sensor 51	0.466	0.037
9	3	Normalized Sensor 62	0.747	0.036
8	3	Normalized Sensor 35	0.675	0.032
6	4	Normalized Sensor 63	0.478	0.03
7	2	Normalized Sensor 43	0.861	0.027

Proportion of variation explained by clustering: 0.731



Cluster Members

Cluster	Members	RSquare with Own Cluster	RSquare with Next Closest	1-RSquare Ratio
1	Normalized Sensor 46	0.915	0.514	0.174
1	Normalized Sensor 48	0.894	0.455	0.194
1	Normalized Sensor 50	0.905	0.517	0.197
1	Normalized Sensor 25	0.888	0.473	0.214
1	Normalized Sensor 44	0.869	0.427	0.229
1	Normalized Sensor 18	0.922	0.667	0.235
1	Normalized Sensor 08	0.87	0.471	0.246
1	Normalized Sensor 53	0.9	0.643	0.28
1	Normalized Sensor 24	0.844	0.465	0.291
1	Normalized Sensor 06	0.812	0.431	0.33
1	Normalized Sensor 61	0.878	0.639	0.336
1	Normalized Sensor 07	0.799	0.411	0.341
1	Normalized Sensor 05	0.798	0.412	0.343
1	Normalized Sensor 54	0.88	0.656	0.349
1	Normalized Sensor 27	0.76	0.354	0.371
1	Normalized Sensor 14	0.773	0.407	0.383
1	Normalized Sensor 13	0.739	0.362	0.408
1	Normalized Sensor 52	0.824	0.582	0.422
1	Normalized Sensor 55	0.851	0.667	0.449
1	Normalized Sensor 15	0.681	0.348	0.489
1	Normalized Sensor 26	0.685	0.36	0.492
1	Normalized Sensor 16	0.683	0.366	0.499
1	Normalized Sensor 21	0.72	0.588	0.679
1	Normalized Sensor 41	0.373	0.217	0.8
1	Normalized Sensor 20	0.655	0.623	0.915



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Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	522	36.5630568	0.3709
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1	Normalized Sensor 21	0.72	0.588	0.679
1	Normalized Sensor 41	0.373	0.217	0.8
1	Normalized Sensor 20	0.655	0.623	0.915

Fit Model 2 - JMP

Model Specification

Select Columns

- 175 Columns
- Sensor Measurements (63/0)
- testResult
- status
- Stratified Validation
- Johnson Senso...ments (63/25)
 - Normalized Sensor 01
 - Normalized Sensor 02
 - Normalized Sensor 03
 - Normalized Sensor 04
 - Normalized Sensor 05
 - Normalized Sensor 06
 - Normalized Sensor 07
 - Normalized Sensor 08
 - Normalized Sensor 09
 - Normalized Sensor 10
 - Normalized Sensor 11
 - Normalized Sensor 12
 - Normalized Sensor 13
 - Normalized Sensor 14
 - Normalized Sensor 15

Pick Role Variables

Y: status

Weight: optional numeric

Freq: optional numeric

Validation: Stratified Validation

By: optional

Personality: Generalized Regression

Distribution: Binomial

Target Level: Fail

Buttons: Help, Run, Recall, Remove

Keep dialog open

Construct Model Effects

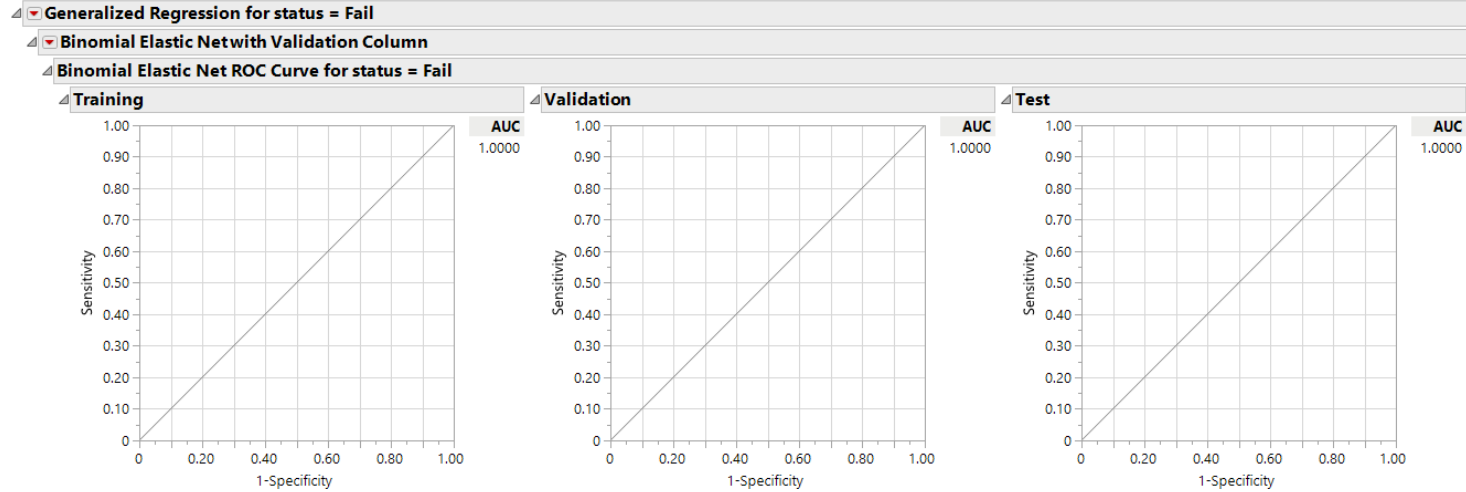
Add: Normalized Sensor 05, Normalized Sensor 06, Normalized Sensor 07, Normalized Sensor 08, Normalized Sensor 13, Normalized Sensor 14, Normalized Sensor 15, Normalized Sensor 16, Normalized Sensor 18, Normalized Sensor 20

Cross, Nest, Macros

Degree: 2

Attributes, Transform

No Intercept





Generalized Regression for status = Fail

Binomial Elastic Net with Validation Column

Parameter Estimates for Original Predictors

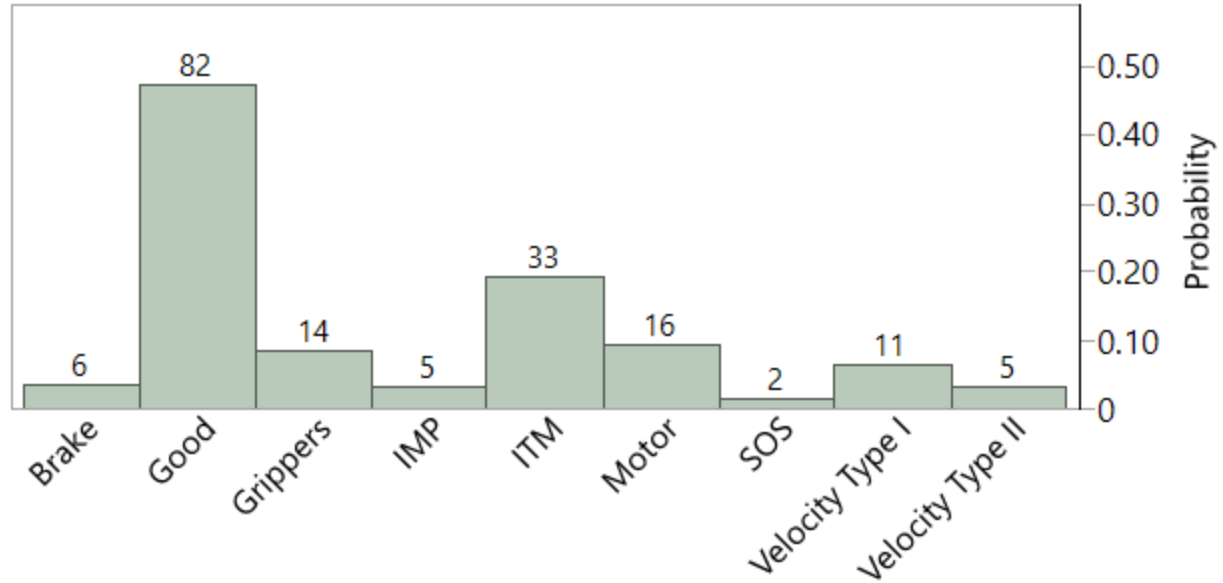
Term	Estimate	Std Error	Wald ChiSquare	Prob > ChiSquare
Intercept	10.090548	1.8017642	31.364152	<.0001*
Normalized Sensor 18	13.755492	2.5555089	28.973268	<.0001*
Normalized Sensor 27	-4.513064	1.9010799	5.6356271	0.0176*
Normalized Sensor 41	-0.875506	0.4462948	3.8483516	0.0498*
Normalized Sensor 26	1.9403476	1.3346853	2.1134955	0.1460
Normalized Sensor 15	-0.622552	0.7173161	0.7532344	0.3855
Normalized Sensor 52	3.841615	4.4366523	0.7497507	0.3866
Normalized Sensor 21	0.94501	1.2462852	0.5749604	0.4483
Normalized Sensor 08	0.6791519	1.1816369	0.3303434	0.5655
Normalized Sensor 05	0.3684318	0.8110402	0.2063619	0.6496
Normalized Sensor 55	2.4557393	6.4177539	0.1464193	0.7020
Normalized Sensor 61	1.6776547	6.6668107	0.0633241	0.8013
Normalized Sensor 06	0.2655408	1.2046963	0.0485856	0.8255
Normalized Sensor 14	-0.113737	0.681085	0.0278868	0.8674
Normalized Sensor 53	0.4410189	5.6487227	0.0060956	0.9378
Normalized Sensor 54	0.6979234	9.6499351	0.0052308	0.9423
Normalized Sensor 16	-0.003632	0.3813282	9.0716e-5	0.9924
Normalized Sensor 07	0	0	0	1.0000
Normalized Sensor 13	0	0	0	1.0000
Normalized Sensor 20	0	0	0	1.0000

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	522	36.5630568	0.3709
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sensor44	15	0.75054722	0.0076
sensor26	67	0.74422853	0.0075
sensor17	36	0.52835424	0.0054

“Can the sensor data predict the outcome (test result)?”

testResult



“Can the sensor data predict the outcome (test result)?”

“Can the sensor data predict the ‘Good’ ones?”

Model Driven Multivariate Control Chart - JMP [2]

Creates multivariate control charts based on principal components or partial least squares methods.

Select Columns

67 Columns

Enter column name

- Original Sensors (63/63)
- testResult
- status
- Validation
- Validation Random Formula

Cast Selected Columns into Roles

Process: sensor01, sensor02, sensor03, sensor04

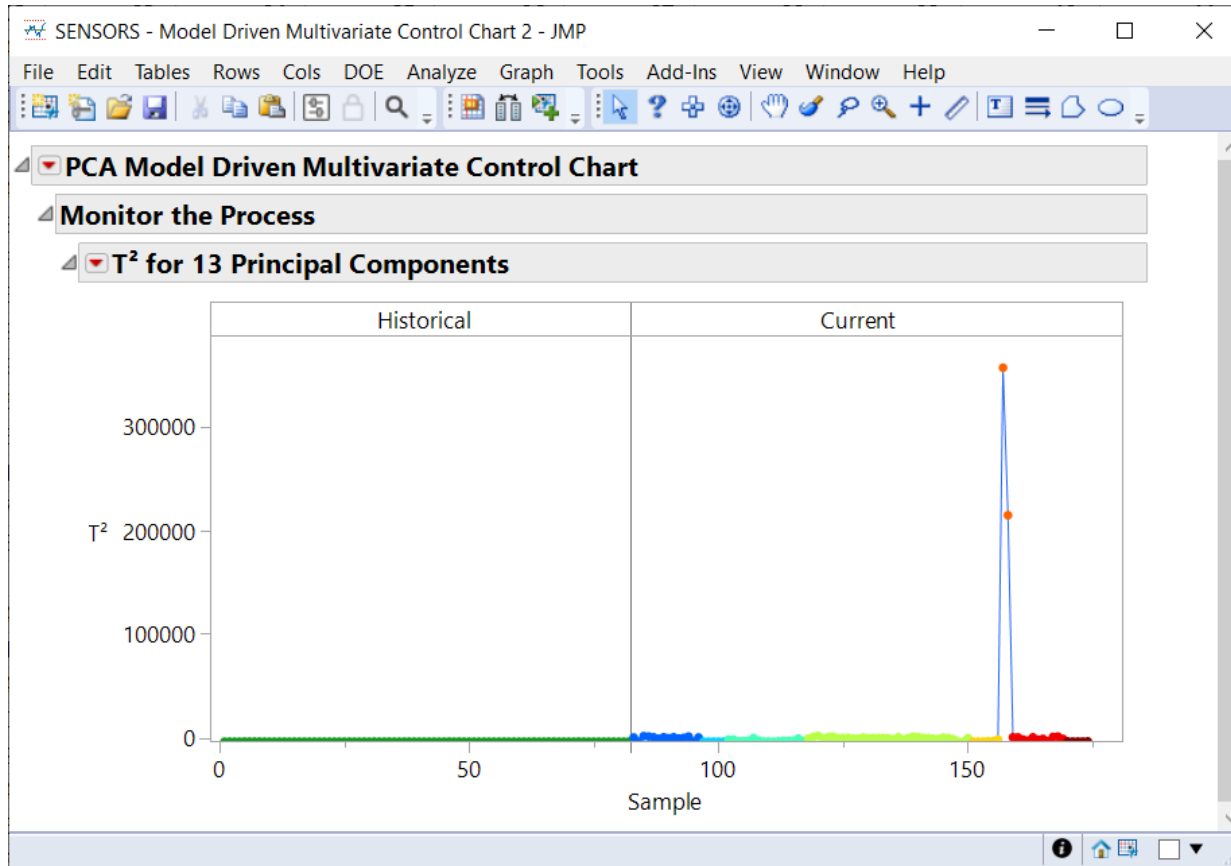
Time ID: optional numeric

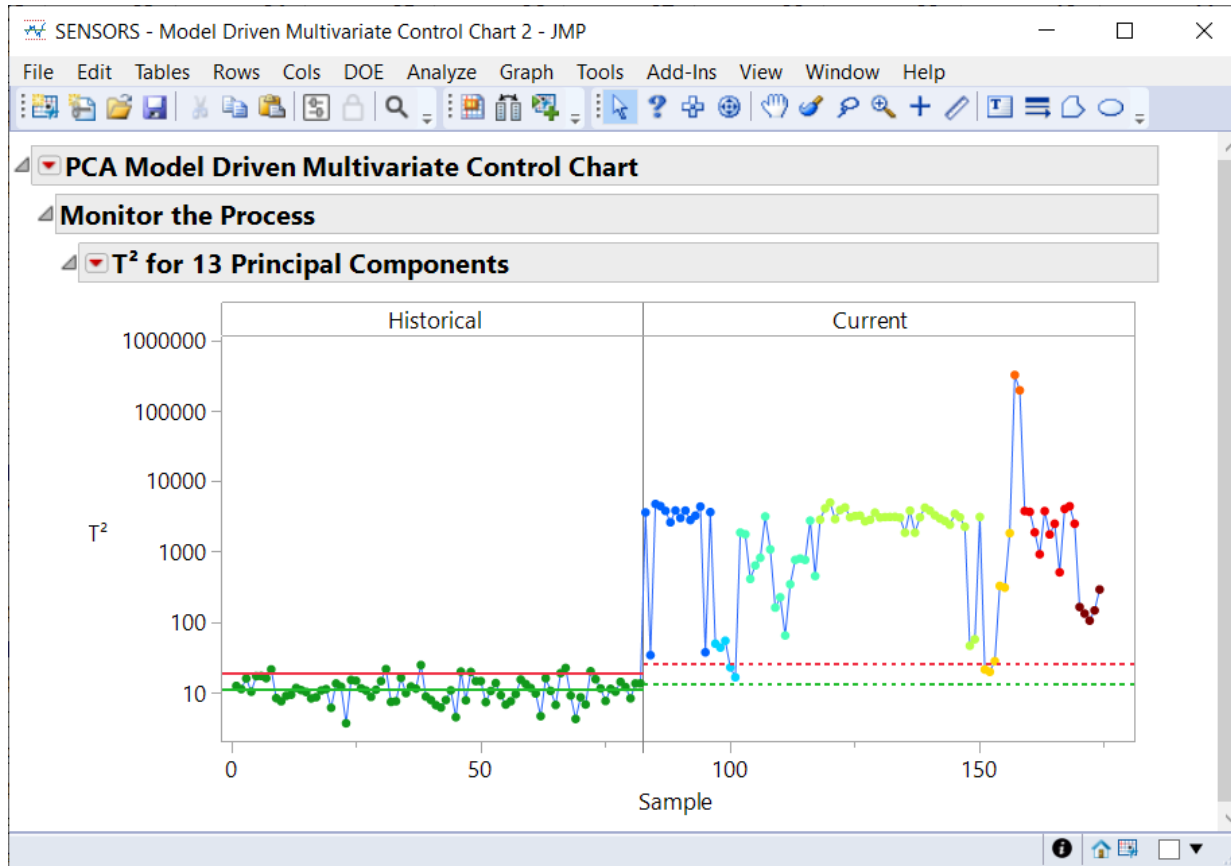
By: optional

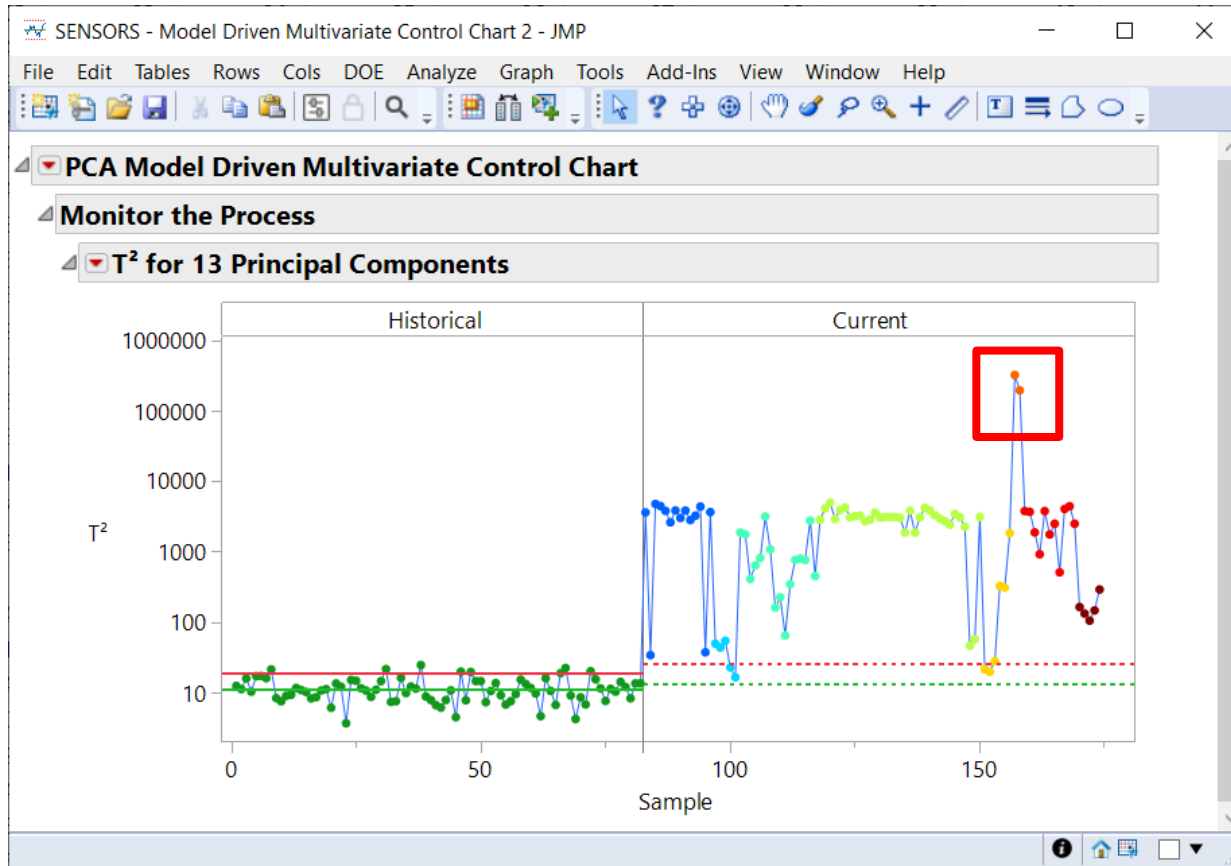
Action

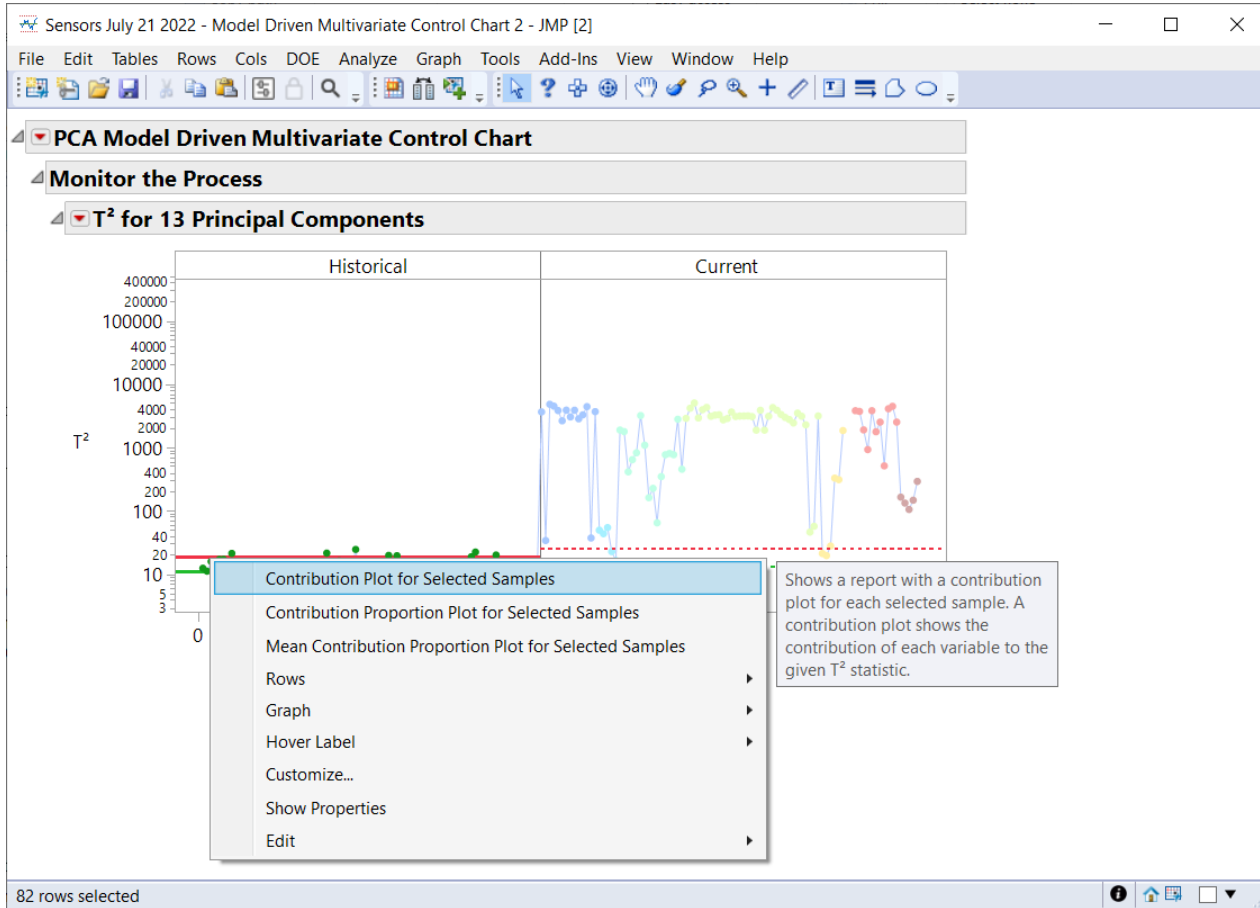
OK, Cancel, Remove, Recall, Help

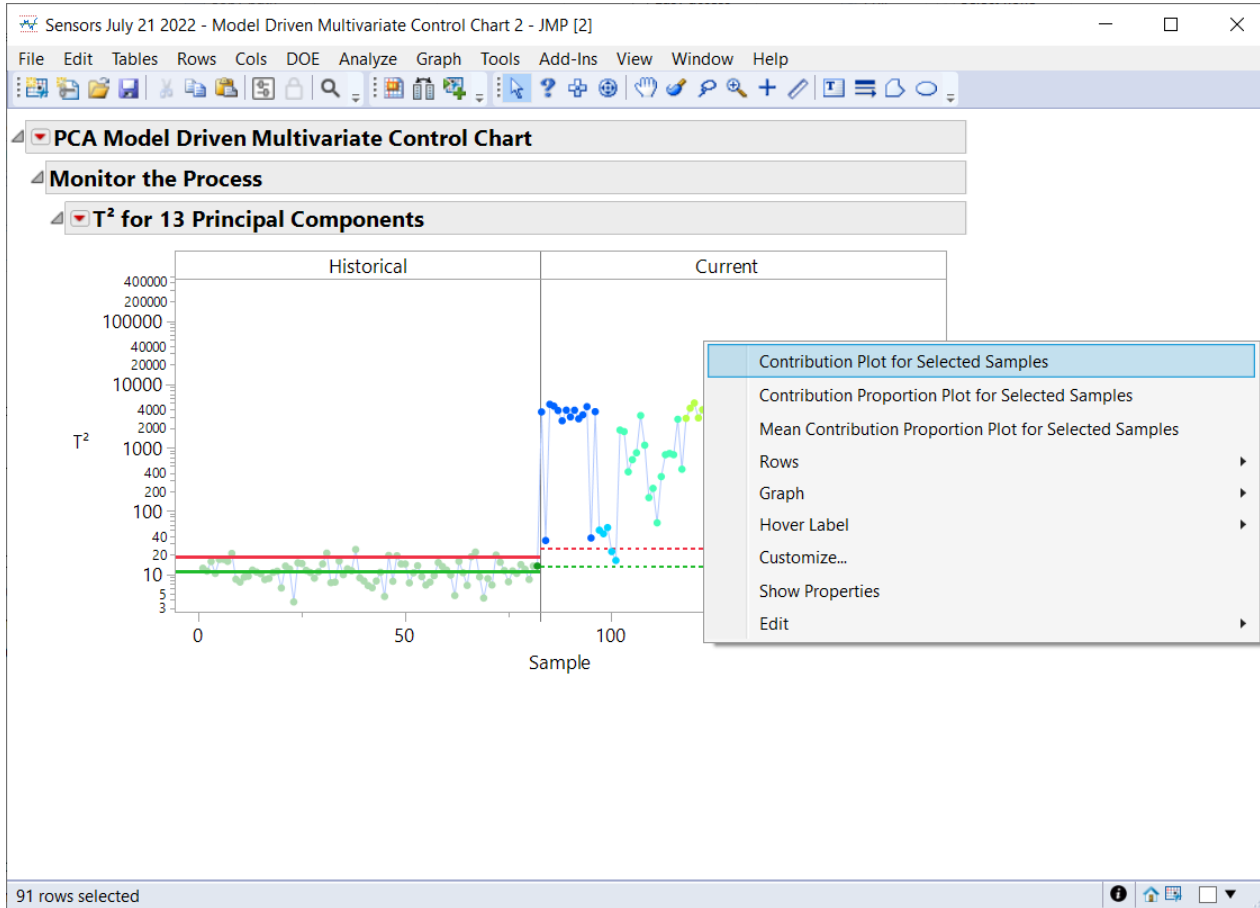
Historical Data End at Row: 82











T² Contribution Plot for status=Pass



T² Contribution Plot for status=Fail





Boosted Tree for status

Column Contributions

Term	Number of Splits	G^2	Portion
sensor56	82	4634.8525	0.2065
sensor18	27	4200.54219	0.1872
sensor11	21	2735.54419	0.1219
sensor61	19	2431.70533	0.1084
sensor48	17	2414.82121	0.1076
sensor57	22	2016.84895	0.0899
sensor58	10	1456.34648	0.0649
sensor59	8	726.693834	0.0324
sensor26	2	343.87221	0.0153
sensor52	2	323.166652	0.0144
sensor09	6	286.922646	0.0128
sensor01	9	194.974174	0.0087
sensor55	2	165.247012	0.0074
sensor24	4	151.216612	0.0067
sensor07	4	128.858022	0.0057
sensor12	4	117.421132	0.0052
sensor15	2	44.7671089	0.0020
sensor44	1	37.6713347	0.0017
sensor54	1	15.5711294	0.0007
sensor27	1	12.8974036	0.0006

Bootstrap Forest for status

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	579	54.9167342	0.5024
sensor61	198	18.7389273	0.1714
sensor52	145	13.1320295	0.1201
sensor53	56	5.26374221	0.0482
sensor44	33	2.53070023	0.0232
sensor48	42	2.45696551	0.0225
sensor46	31	2.08993095	0.0191
sensor11	114	1.34630042	0.0123
sensor54	12	1.01688952	0.0093
sensor58	111	0.73127415	0.0067
sensor07	61	0.68014104	0.0062
sensor26	89	0.5292647	0.0048
sensor12	40	0.51092374	0.0047
sensor50	8	0.41943383	0.0038
sensor57	75	0.3901658	0.0036
sensor01	44	0.35310066	0.0032
sensor05	47	0.3400086	0.0031
sensor21	8	0.30245908	0.0028



BT

Overall Statistics

Measure	Training	Validation
Entropy RSquare	0.9981	0.5788
Generalized RSquare	0.9991	0.7352
Mean -Log p	0.0013	0.2909
RASE	0.0025	0.2649
Mean Abs Dev	0.0013	0.0875
Misclassification Rate	0.0000	0.0930
N	131	43



RF

Overall Statistics

Measure	Training	Validation
Entropy RSquare	0.9186	0.6736
Generalized RSquare	0.9601	0.8089
Mean -Log p	0.0563	0.2254
RASE	0.1016	0.2543
Mean Abs Dev	0.0491	0.1253
Misclassification Rate	0.0076	0.0698
N	131	43

Boosted Trees vs. Random Forest Folklore

BT

- Fast algorithm
- Highly accurate on big data

RF

- More accurate on small data
- Robust to messy/noisy data
- Often used for variable selection



Variable selection using random forests

Robin Genuer ^a ✉, Jean-Michel Poggi ^{a, b} ✉, Christine Tuleau-Malot ^c ✉

Citation Network

In Web of Science Core Collection

1,186

Citations

[🔔 Create citation alert](#)

1,235

Times Cited in All
Databases

38

Cited References
[View Related Records](#)



Boosted Tree for status

Column Contributions

Term	Number of Splits	G ²	Portion
sensor56	82	4634.8525	0.2065
sensor18	27	4200.54219	0.1872
sensor11	21	2735.54419	0.1219
sensor61	19	2431.70533	0.1084
sensor48	17	2414.82121	0.1076
sensor57	22	2016.84895	0.0899
sensor58	10	1456.34648	0.0649
sensor59	8	726.693834	0.0324
sensor26	2	343.87221	0.0153
sensor52	2	323.166652	0.0144
sensor09	6	286.922646	0.0128
sensor01	9	194.974174	0.0087
sensor55	2	165.247012	0.0074
sensor24	4	151.216612	0.0067
sensor07	4	128.858022	0.0057
sensor12	4	117.421132	0.0052
sensor15	2	44.7671089	0.0020
sensor44	1	37.6713347	0.0017
sensor54	1	15.5711294	0.0007
sensor27	1	12.8974036	0.0006

Bootstrap Forest for status

Column Contributions

Term	Number of Splits	G ²	Portion
sensor18	579	54.9167342	0.5024
sensor61	198	18.7389273	0.1714
sensor52	145	13.1320295	0.1201
sensor53	56	5.26374221	0.0482
sensor44	33	2.53070023	0.0232
sensor48	42	2.45696551	0.0225
sensor46	31	2.08993095	0.0191
sensor11	114	1.34630042	0.0123
sensor54	12	1.01688952	0.0093
sensor58	111	0.73127415	0.0067
sensor07	61	0.68014104	0.0062
sensor26	89	0.5292647	0.0048
sensor12	40	0.51092374	0.0047
sensor50	8	0.41943383	0.0038
sensor57	75	0.3901658	0.0036
sensor01	44	0.35310066	0.0032
sensor05	47	0.3400086	0.0031
sensor21	8	0.30245908	0.0028

Make Validation Column

Stratified Validation Column

Randomly partitions the rows into training, validation and test sets while attempting to evenly distribute across levels of the stratification variable(s). Use this option when you want a balanced representation of a column's levels in each of the training, validation and test sets.

Stratification Columns: status

Specify rates or relative rates

	Adjusted Rates	Row Counts
Training Set	<input type="text" value="0.75"/>	0.75 129
Validation Set	<input type="text" value="0.25"/>	0.25 43
Test Set	<input type="text" value="0"/>	0 0
Excluded Rows		2
Total Rows		172

Options

New Column Name

Validation Column Type

Go

Cancel Help

Bootstrap Forest for status

Column Contributions

Term	Number of Splits	G ²	Portion
sensor18	527	48.0327701	0.4471
sensor61	303	27.9106906	0.2
sensor52	112	9.35593633	0.0
sensor53	67	5.65325216	0.0
sensor48	60	2.90761066	0.0
sensor46	33	1.89183143	0.0
sensor54	22	1.68095955	0.0
sensor44	16	1.12914783	0.0
sensor11	95	1.00344327	0.0
sensor50	17	0.71366776	0.0
sensor07	60	0.67747388	0.0
sensor58	96	0.64091112	0.0
sensor26	92	0.54471308	0.0
sensor12	35	0.43300361	0.0
sensor57	67	0.37339152	0.0
sensor55	11	0.34960808	0.0
sensor24	39	0.34381403	0.0
sensor45	47	0.30713564	0.0
sensor27	46	0.24187279	0.0
sensor17	17	0.23554353	0.0
sensor08	13	0.2208964	0.0021
sensor49	35	0.21863803	0.0020

- Table Style
- Columns
- Sort by Column...
- Make into Data Table
- Make Combined Data Table
- Make Into Matrix
- Select Where...
- Filter Where...
- Format Column...
- Align Decimal Separator
- Show Properties
- Copy Column
- Copy Table
- Simulate**
- Bootstrap

Switch columns to perform a simulation.

Bootstrap Forest for status

Column Contributions

Term	Number of Splits	G ²	Portion
sensor18	527	48.0327701	0.4471
sensor61	303	27.9106906	0.2598
sensor52	112	9.35593633	
sensor53	67	5.65325216	
sensor48	60	2.90761066	
sensor46	33	1.89183143	
sensor54	22	1.68095955	
sensor44	16	1.12914783	
sensor11	95	1.00344327	
sensor50	17	0.71366776	
sensor07	60	0.67747388	
sensor58	96	0.64091112	
sensor26	92	0.54471308	
sensor12	35	0.43300361	0.0040
sensor57	67	0.37339152	0.0035
sensor55	11	0.34960808	0.0033
sensor24	39	0.34381403	0.0032
sensor45	47	0.30713564	0.0029
sensor27	46	0.24187279	0.0023
sensor17	17	0.23554353	0.0022
sensor08	13	0.2208964	0.0021
sensor49	35	0.21863803	0.0020

Simulation

Column to Switch Out:

Column to Switch In:

Number of Samples:

Random Seed:

OK Cancel Help

Bootstrap Forest of status Simulate Results (Portion) - JMP

File Edit Tables Rows Cols DOE Analyze Graph Tools Add-Ins View Window Help

Bootstrap Forest of statu... >

- Make Combined Data Table
- Distribution

Columns (66/0)

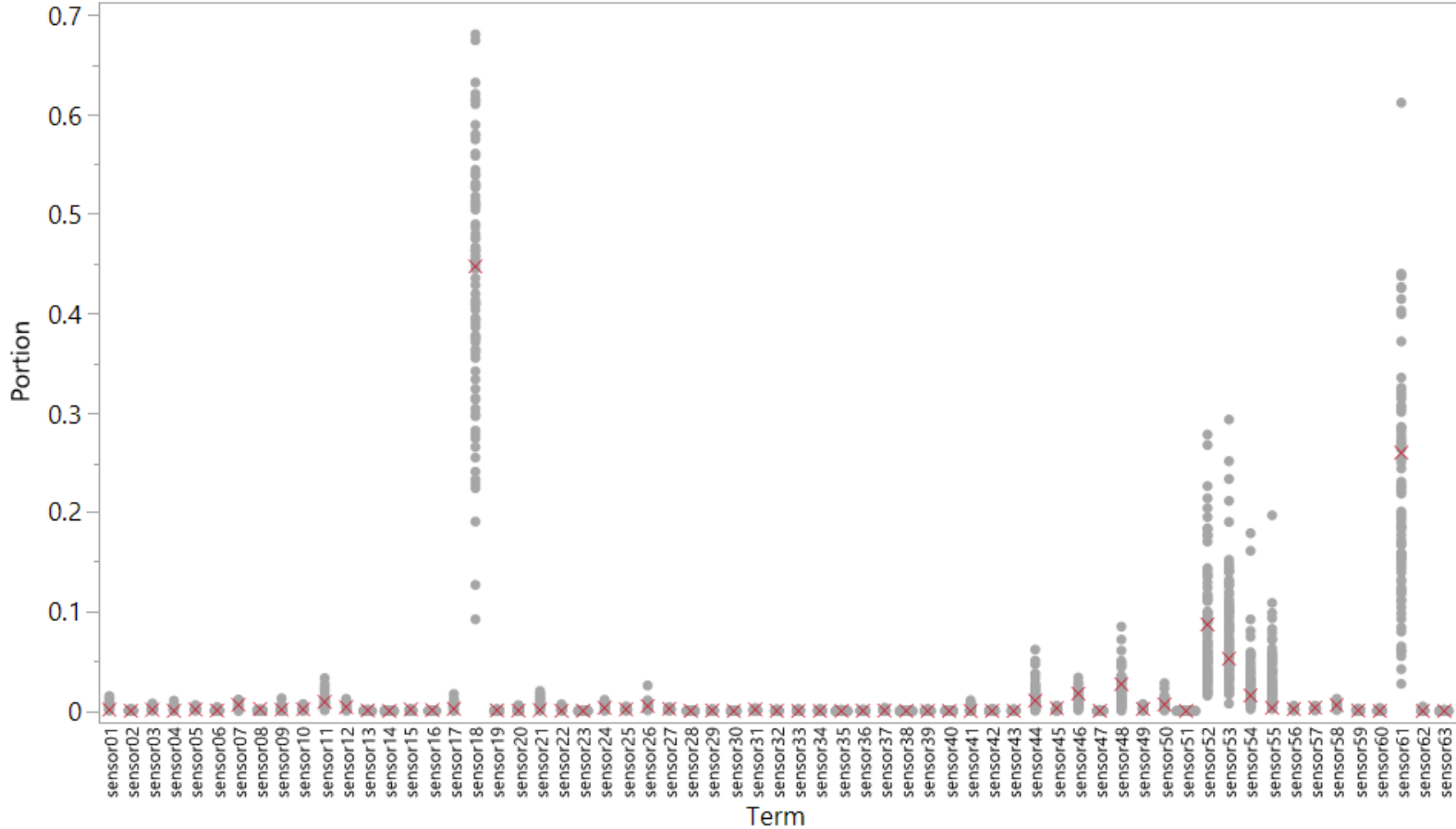
Table *
Y
SimID•
sensor01
sensor02
sensor03
sensor04
sensor05
sensor06
sensor07
sensor08
sensor09
sensor10
sensor11

Rows

	Table	Y	SimID•	sensor01	sensor02	sensor03	sensor04	sens
1	Sensors No SO...	status	0	0.0014	0.0002	0.0013	0.0002	
2	Sensors No SO...	status	1	0.0055	0.0011	0.0033	0.0036	
3	Sensors No SO...	status	2	0.0086	0.0009	0.0056	0.0043	
4	Sensors No SO...	status	3	0.0035	0.0004	0.0022	0.0011	
5	Sensors No SO...	status	4	0.0053	0.0018	0.0030	0.0048	
6	Sensors No SO...	status	5	0.0035	0.0006	0.0014	0.0024	
7	Sensors No SO...	status	6	0.0044	0.0016	0.0022	0.0033	
8	Sensors No SO...	status	7	0.0108	0.0008	0.0077	0.0017	
9	Sensors No SO...	status	8	0.0066	0.0007	0.0019	0.0003	
10	Sensors No SO...	status	9	0.0033	0.0004	0.0012	0.0020	
11	Sensors No SO...	status	10	0.0030	0.0003	0.0009	0.0007	
12	Sensors No SO...	status	11	0.0022	0.0007	0.0015	0.0002	
13	Sensors No SO...	status	12	0.0013	0.0006	0.0011	0.0003	
14	Sensors No SO...	status	13	0.0056	0.0011	0.0022	0.0032	
15	Sensors No SO...	status	14	0.0024	0.0003	0.0013	0.0005	
16	Sensors No SO...	status	15	0.0084	0.0009	0.0020	0.0030	
17	Sensors No SO...	status	16	0.0037	0.0003	0.0022	0.0030	
18	Sensors No SO...	status	17	0.0063	0.0006	0.0016	0.0042	
19	Sensors No SO...	status	18	0.0050	0.0024	0.0029	0.0057	
20	Sensors No SO...	status	19	0.0052	0.0011	0.0031	0.0059	
21	Sensors No SO...	status	20	0.0051	0.0011	0.0019	0.0038	
22								

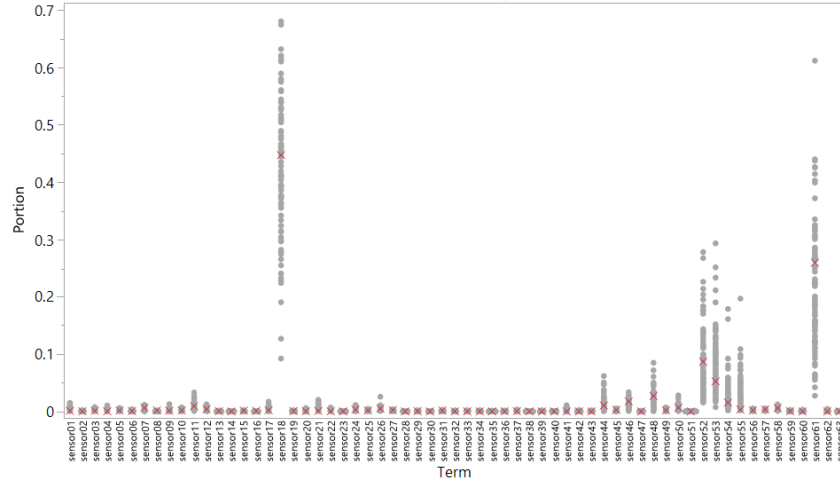
All rows 101
Selected 0
Excluded 1
Hidden 0
Labeled 0

Portion vs. Term (Bootstrap Forest)



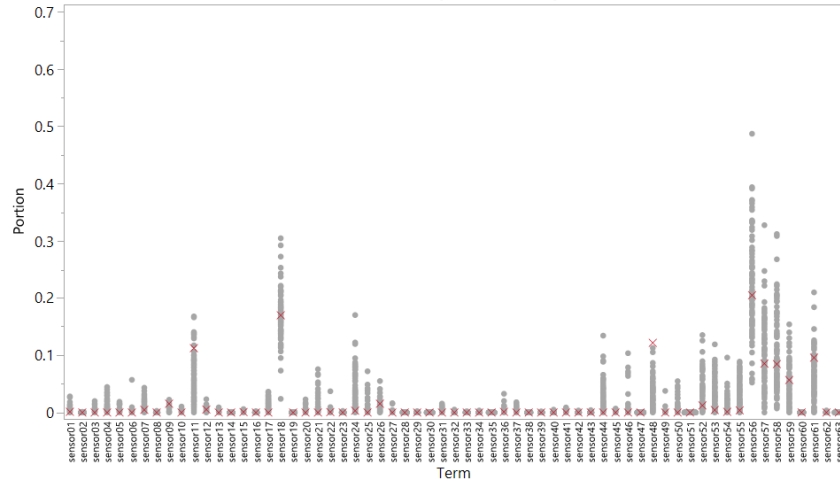
• Portion

Portion vs. Term (Bootstrap Forest)



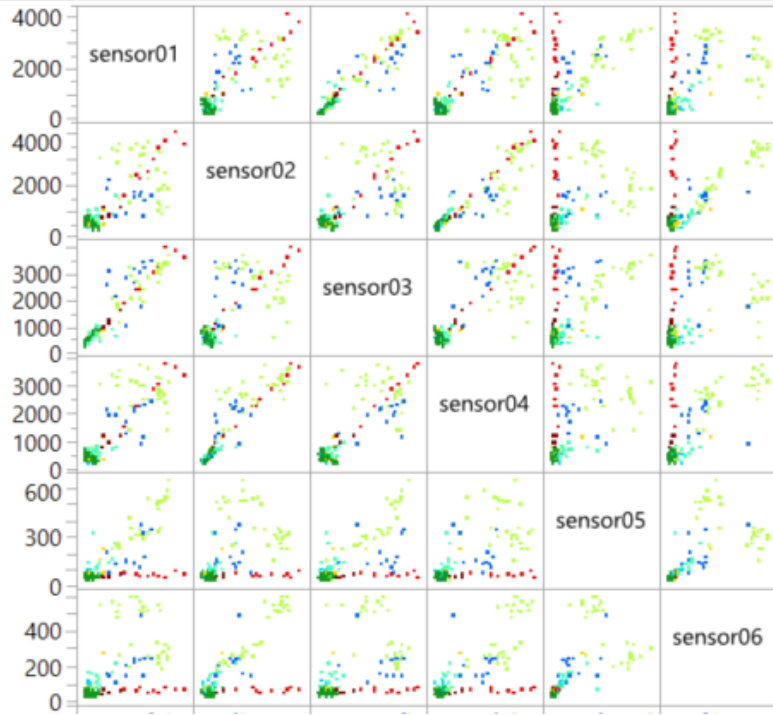
• Portion

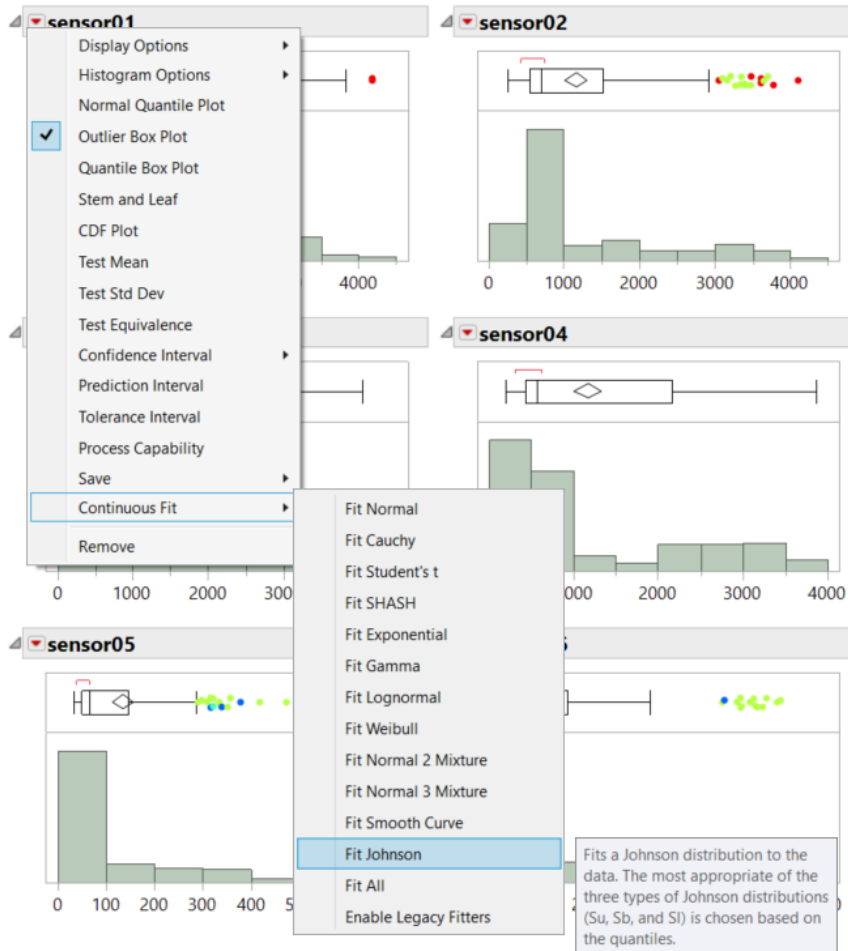
Portion vs. Term (Boosted Tree)



• Portion

Scatterplot Matrix





- Hold Alt + Click to broadcast to all columns

sensor01

Fitted Johnson Sb Distribution

	Error	Lower 95%	Upper 95%
Diagnostic Plots	3599	0.6185806	0.968865
Profilers	4469	0.3588199	0.4588212

AICc 2708.2845
BIC 2720.635

sensor02

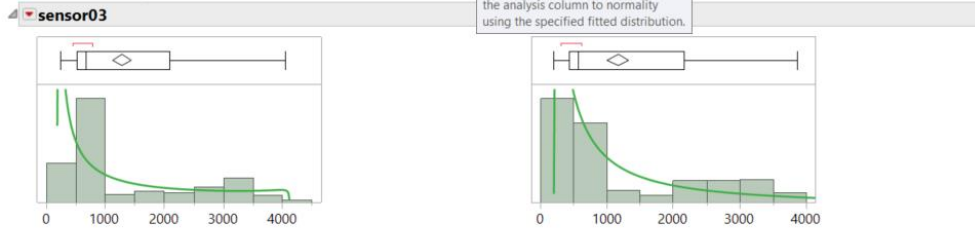
Fitted Johnson Su Distribution

Parameter	Estimate	Std Error	Lower 95%	Upper 95%
Shape γ	-0.992423	0.1262952	-1.239957	-0.744889
Shape δ	0.6380772	0.0367072	0.5700402	0.7142347
Location θ	508.94132	23.487057	462.90754	554.97511
Scale σ	104.31675	0	104.31675	104.31675

Measures

-2*LogLikelihood 2651.8731

Saves a column to the data table that contains a formula used to transform the analysis column to normality using the specified fitted distribution.



- Hold Alt + Click to broadcast to all columns

Compare Distributions

Show	Distribution	AICc ^	BIC	-2*LogLikelihood
<input checked="" type="checkbox"/>	Johnson Sb	2789.0762	2801.4267	2780.8367

Fitted Johnson Sb Distribution

Parameter	Estimate	Std Error	Lower 95%	Upper 95%
Shape γ	0.790034	0.083804	0.6257812	0.9542867
Shape δ	0.4246405	0.0271587	0.3746116	0.4813506
Location θ	194.59048	0	194.59048	194.59048
Scale σ	3925.2571	0	3925.2571	3925.2571

Measures

-2*LogLikelihood 2780.8367
AICc 2789.0762
BIC 2801.4267

Compare Distributions

Show	Distribution	AICc ^	BIC	-2*LogLikelihood
<input checked="" type="checkbox"/>	Johnson Sb	2693.1827	2705.5331	2684.9432

Fitted Johnson Sb Distribution

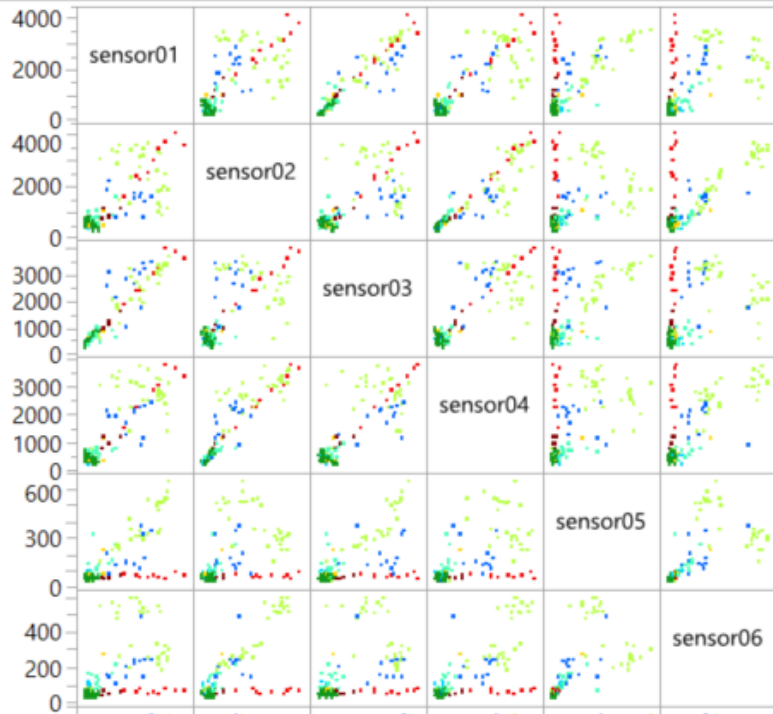
Parameter	Estimate	Std Error	Lower 95%	Upper 95%
Shape γ	1.3980018	0.1063894	1.1894824	1.6065212
Shape δ	0.6025777	0.0353684	0.5370956	0.6760434
Location θ	205.19524	2.1311578	201.01825	209.37223
Scale σ	5347.2482	0	5347.2482	5347.2482

Measures

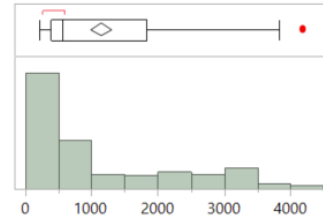
-2*LogLikelihood 2684.9432
AICc 2693.1827
BIC 2705.5331

	status	Validation	Validation Random Formula	Johnson Sb Transform to Normal sensor01	Johnson Su Transform to Normal sensor02	Johnson Sb Transform to Normal sensor03	Johnson Sb Transform to Normal sensor04	Johnson Su Transform to Normal sensor05	Johnson Su Transform to Normal sensor06
1	Pass	Validation	Training	-0.429462541	-0.023164209	-0.180868093	-0.045175325	0.2103355703	-0.013999938
2	Pass	Validation	Training	-0.055300886	-1.63236901	0.0946350653	-1.649470993	-1.009090647	-1.042115859
3	Pass	Validation	Training	-0.111839132	-0.187981022	0.0190318601	-0.321027105	0.0413421482	-0.274633425
4	Pass	Training	Training	-0.545119593	-0.394709423	-0.250233244	-0.502509817	-0.35310491	-0.19353877
5	Pass	Validation	Training	-0.592368033	-0.381589246	-0.202267621	-0.067493582	-0.021463294	-0.083870644
6	Pass	Training	Training	0.0314637112	-2.059472445	0.0999572363	-1.329631387	-0.047036417	-0.310192693
7	Pass	Training	Training	-0.768441134	-0.068940672	-0.417092494	0.0214536018	-0.420836258	-0.424783097
8	Pass	Training	Training	-0.30113471	-0.3561646	-0.139427747	-0.229023302	-0.523040338	-0.000297651
9	Pass	Training	Training	-0.860416254	-0.790455797	-0.458553392	-0.622679123	-1.647412021	-0.44909209
10	Pass	Validation	Training	-0.516276499	-0.09857755	-0.194884031	-0.159489881	-1.334245723	-0.871892236
11	Pass	Training	Training	-0.447437398	-0.337014942	-0.285230865	-0.233164785	0.0729605379	-0.303294366
12	Pass	Training	Training	-0.247673385	-0.168014048	-0.027250896	-0.184571798	-1.529483355	-1.024703913

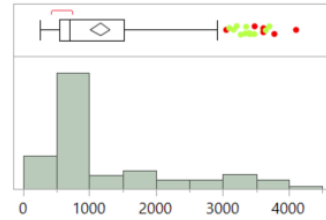
Scatterplot Matrix



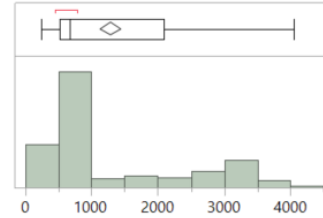
sensor01



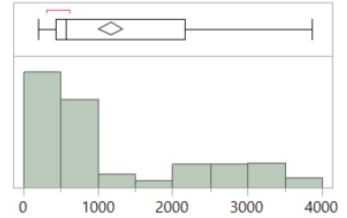
sensor02



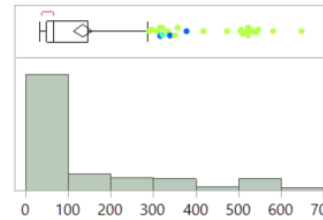
sensor03



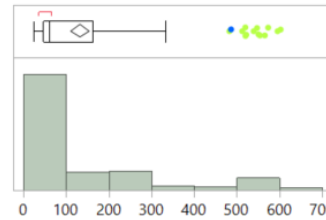
sensor04

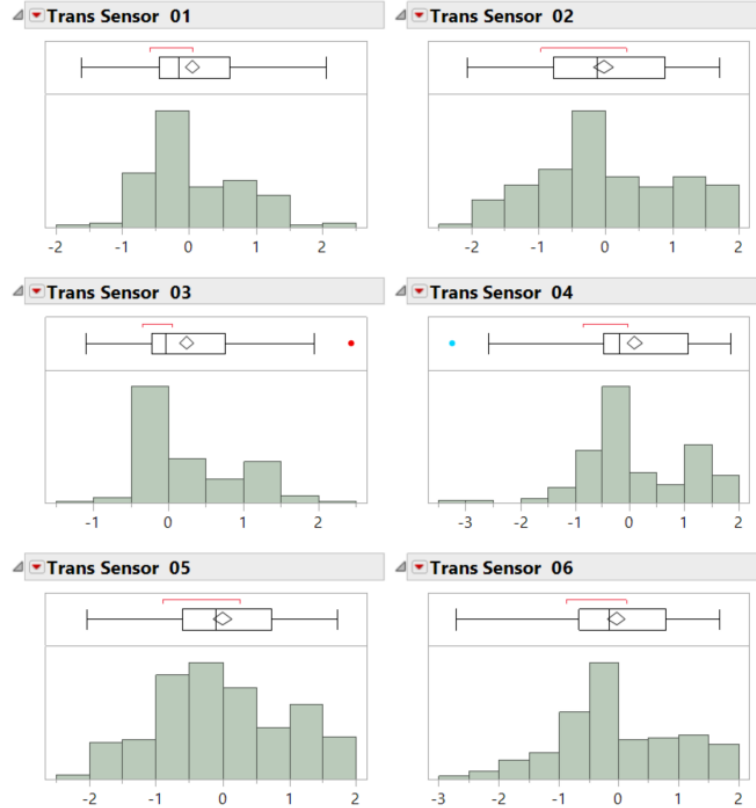
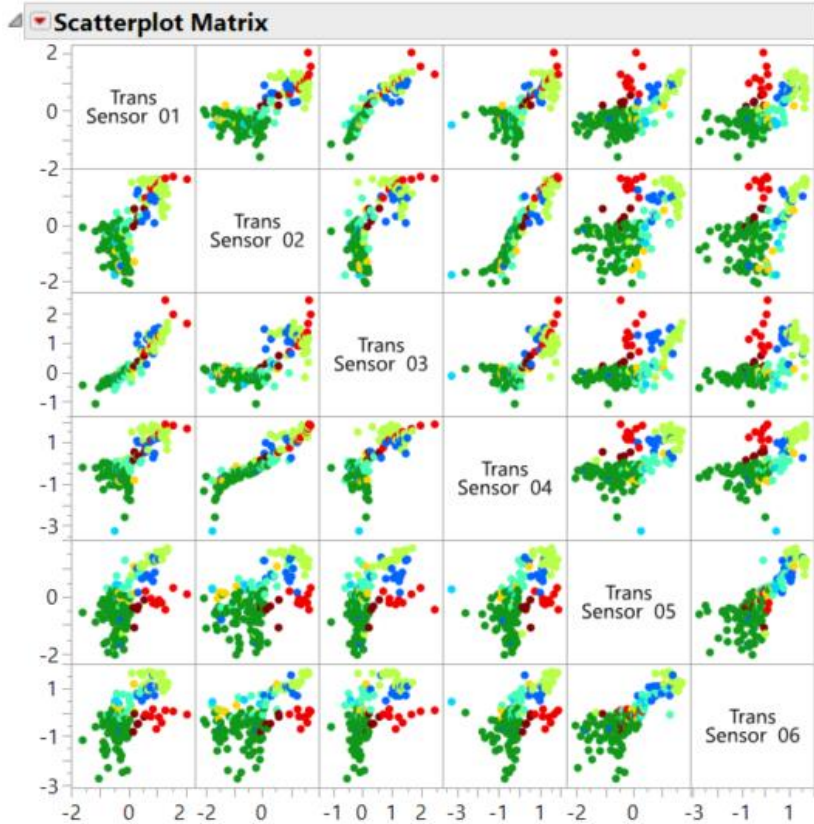


sensor05



sensor06





Cluster Variables - JMP

Clusters variables (columns) into groups of highly correlated variables.

Select Columns

157 Columns

Enter column name

- Sensor Measurements (63/0)
 - testResult
 - status
 - Stratified Validation
- Johnson Sensor Measurements (63/0)
 - Normalized Sensor 01
 - Normalized Sensor 02

Cast Selected Columns into Roles

Y, Columns

- Normalized Sensor 01
- Normalized Sensor 02
- Normalized Sensor 03
- Normalized Sensor 04

Weight optional numeric

Freq optional numeric

By optional

Action

OK

Cancel

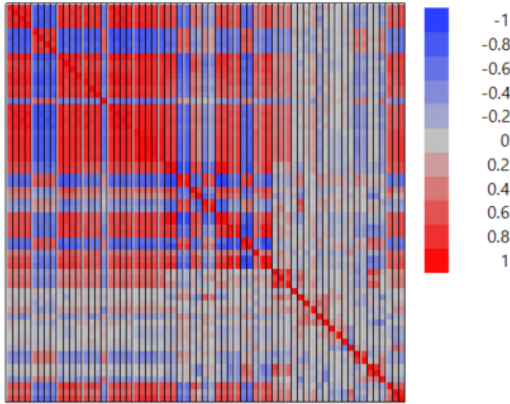
Remove

Recall

Help

Variable Clustering

Color Map on Correlations



Cluster Summary

Cluster	Number of Members	Most Representative Variable	Cluster Proportion of Variation Explained	Total Proportion of Variation Explained	.2	.4	.6	.8
1	25	Trans Sensor 46	0.797	0.316	[Bar chart showing cumulative variation explained]			
2	10	Trans Sensor 36	0.77	0.122				
3	7	Trans Sensor 38	0.818	0.091				
4	4	Trans Sensor 31	0.622	0.04				
5	5	Trans Sensor 51	0.466	0.037				
9	3	Trans Sensor 62	0.747	0.036				
8	3	Trans Sensor 35	0.675	0.032				
6	4	Trans Sensor 63	0.478	0.03				
7	2	Trans Sensor 43	0.861	0.027				

Proportion of variation explained by clustering: 0.731

Variable Clustering

Cluster Members

Cluster	Members	RSquare with Own Cluster	RSquare with Next Closest	1-RSquare Ratio
1	Trans Sensor 46	0.915	0.514	0.174
1	Trans Sensor 48	0.894	0.455	0.194
1	Trans Sensor 50	0.905	0.517	0.197
1	Trans Sensor 25	0.888	0.473	0.214
1	Trans Sensor 44	0.869	0.427	0.229
1	Trans Sensor 18	0.922	0.667	0.235
1	Trans Sensor 08	0.87	0.471	0.246
1	Trans Sensor 53	0.9	0.643	0.28
1	Trans Sensor 24	0.844	0.465	0.291
1	Trans Sensor 06	0.812	0.431	0.33
1	Trans Sensor 61	0.878	0.639	0.336
1	Trans Sensor 07	0.799	0.411	0.341
1	Trans Sensor 05	0.798	0.412	0.343
1	Trans Sensor 54	0.88	0.656	0.349
1	Trans Sensor 27	0.76	0.354	0.371
1	Trans Sensor 14	0.773	0.407	0.383
1	Trans Sensor 13	0.739	0.362	0.408
1	Trans Sensor 52	0.824	0.582	0.422
1	Trans Sensor 55	0.851	0.667	0.449
1	Trans Sensor 15	0.681	0.348	0.489
1	Trans Sensor 26	0.685	0.36	0.492
1	Trans Sensor 16	0.683	0.366	0.499
1	Trans Sensor 21	0.72	0.588	0.679
1	Trans Sensor 41	0.373	0.217	0.8
1	Trans Sensor 20	0.655	0.623	0.915
2	Trans Sensor 36	0.938	0.536	0.134
2	Trans Sensor 40	0.939	0.576	0.145
2	Trans Sensor 11	0.896	0.555	0.233
2	Trans Sensor 09	0.881	0.498	0.237
2	Trans Sensor 03	0.877	0.588	0.299
2	Trans Sensor 01	0.872	0.585	0.309
2	Trans Sensor 32	0.662	0.165	0.404
2	Trans Sensor 34	0.594	0.125	0.464
2	Trans Sensor 19	0.484	0.275	0.711
2	Trans Sensor 17	0.554	0.436	0.791
3	Trans Sensor 38	0.92	0.407	0.135

Bootstrap Forest for status

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	579	54.9167342	0.5024
sensor61	198	18.7389273	0.1714
sensor52	145	13.1320255	0.1201
sensor53	36	2.6574221	0.0482
sensor44	33	2.5267108	0.0232
sensor48	42	2.45696551	0.0225
sensor46	31	2.08993095	0.0191
sensor11	114	1.34630042	0.0123
sensor54	12	1.01688952	0.0093
sensor58	111	0.73127415	0.0067
sensor07	61	0.68014104	0.0062
sensor26	89	0.5292647	0.0048
sensor12	40	0.51092374	0.0047
sensor50	8	0.41943383	0.0038
sensor57	75	0.3901658	0.0036
sensor01	44	0.35310066	0.0032
sensor05	47	0.3400086	0.0031
sensor21	8	0.30245908	0.0028

Cluster Members

Cluster	Members	RSquare with Own Cluster	RSquare with Next Closest	1-RSquare Ratio
1	Normalized Sensor 46	0.915	0.514	0.174
1	Normalized Sensor 48	0.894	0.455	0.194
1	Normalized Sensor 50	0.905	0.517	0.197
1	Normalized Sensor 25	0.888	0.473	0.214
1	Normalized Sensor 44	0.869	0.427	0.229
1	Normalized Sensor 18	0.922	0.667	0.235
1	Normalized Sensor 08	0.87	0.471	0.246
1	Normalized Sensor 53	0.9	0.643	0.28
1	Normalized Sensor 24	0.844	0.465	0.291
1	Normalized Sensor 06	0.812	0.431	0.33
1	Normalized Sensor 61	0.878	0.639	0.336
1	Normalized Sensor 07	0.799	0.411	0.341
1	Normalized Sensor 05	0.798	0.412	0.343
1	Normalized Sensor 54	0.88	0.656	0.349
1	Normalized Sensor 27	0.76	0.354	0.371
1	Normalized Sensor 14	0.773	0.407	0.383
1	Normalized Sensor 13	0.739	0.362	0.408
1	Normalized Sensor 52	0.824	0.582	0.422
1	Normalized Sensor 55	0.851	0.667	0.449
1	Normalized Sensor 15	0.681	0.348	0.489
1	Normalized Sensor 26	0.685	0.36	0.492
1	Normalized Sensor 16	0.683	0.366	0.499
1	Normalized Sensor 21	0.72	0.588	0.679
1	Normalized Sensor 41	0.373	0.217	0.8
1	Normalized Sensor 20	0.655	0.623	0.915

Variable Clustering

Cluster Members

Cluster	Members	RSquare with Own Cluster	RSquare with Next Closest	1-RSquare Ratio
1	Trans Sensor 46	0.915	0.514	0.174
1	Trans Sensor 48	0.894	0.455	0.194
1	Trans Sensor 50	0.905	0.517	0.197
1	Trans Sensor 25	0.888	0.473	0.214
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1	Trans Sensor 26	0.685	0.36	0.492
1	Trans Sensor 16	0.683	0.366	0.499
1	Trans Sensor 21	0.72	0.588	0.679
1	Trans Sensor 41	0.373	0.217	0.8
1	Trans Sensor 20	0.655	0.623	0.915
2	Trans Sensor 36	0.938	0.536	0.134
2	Trans Sensor 40	0.939	0.576	0.145
2	Trans Sensor 11	0.896	0.555	0.233
2	Trans Sensor 09	0.881	0.498	0.237
2	Trans Sensor 03	0.877	0.588	0.299
2	Trans Sensor 01	0.872	0.585	0.309
2	Trans Sensor 32	0.662	0.165	0.404
2	Trans Sensor 34	0.594	0.125	0.464
2	Trans Sensor 19	0.484	0.275	0.711
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Variable Clustering

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1	Trans Sensor 26	0.685	0.36	0.492
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1	Trans Sensor 21	0.72	0.588	0.679
1	Trans Sensor 41	0.373	0.217	0.8
1	Trans Sensor 20	0.655	0.623	0.915
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2	Trans Sensor 40	0.939	0.576	0.145
2	Trans Sensor 11	0.896	0.555	0.233
2	Trans Sensor 09	0.881	0.498	0.237
2	Trans Sensor 03	0.877	0.588	0.299
2	Trans Sensor 01	0.872	0.585	0.309
2	Trans Sensor 32	0.662	0.165	0.404
2	Trans Sensor 34	0.594	0.125	0.464
2	Trans Sensor 19	0.484	0.275	0.711
2	Trans Sensor 17	0.554	0.436	0.791
3	Trans Sensor 38	0.92	0.407	0.135

Variable Clustering				
Cluster Members				
Cluster	Members	RSquare with Own Cluster	RSquare with Next Closest	1-RSquare Ratio
1	Trans Sensor 46	0.915	0.514	0.174
1	Trans Sensor 48	0.894	0.455	0.194
1	Trans Sensor 50	0.905	0.517	0.197
1	Trans Sensor 25	0.888	0.473	0.214
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1	Trans Sensor 18	0.922	0.667	0.235
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1	Trans Sensor 53	0.9	0.643	0.28
1	Trans Sensor 24	0.844	0.465	0.291
1	Trans Sensor 06	0.812	0.431	0.33
1	Trans Sensor 61	0.878	0.639	0.336
1	Trans Sensor 07	0.799	0.411	0.341
1	Trans Sensor 05	0.798	0.412	0.343
1	Trans Sensor 54	0.88	0.656	0.349
1	Trans Sensor 27	0.76	0.354	0.371
1	Trans Sensor 14	0.773	0.407	0.383
1	Trans Sensor 13	0.739	0.362	0.408
1	Trans Sensor 52	0.824	0.582	0.422
1	Trans Sensor 55	0.851	0.667	0.449
1	Trans Sensor 15	0.681	0.348	0.489
1	Trans Sensor 26	0.685	0.36	0.492
1	Trans Sensor 16	0.683	0.366	0.499
1	Trans Sensor 21	0.72	0.588	0.679
1	Trans Sensor 41	0.373	0.217	0.8
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2	Trans Sensor 36	0.938	0.536	0.134
2	Trans Sensor 40	0.939	0.576	0.145
2	Trans Sensor 11	0.896	0.555	0.233
2	Trans Sensor 09	0.881	0.498	0.237
2	Trans Sensor 03	0.877	0.588	0.299
2	Trans Sensor 01	0.872	0.585	0.309
2	Trans Sensor 32	0.662	0.165	0.404
2	Trans Sensor 34	0.594	0.125	0.464
2	Trans Sensor 19	0.484	0.275	0.711
2	Trans Sensor 17	0.554	0.436	0.791
3	Trans Sensor 38	0.92	0.407	0.135

Trans Sensor 01	Trans Sensor 02	Trans Sensor 03	Trans Sensor 04	Trans Sensor 05	Trans Sensor 06	Trans Sensor 07	Trans Sensor 08	Trans Sensor 09
-0.4294...	-0.0231...	-0.1808...	-0.0451...	0.2103...	-0.0139...	-0.1479...	-0.0003...	0.045...
-0.0553...	-1.6323...	0.0946...	-1.6494...	-1.0090...	-1.0421...	-1.1202...	-1.5259...	-0.07...
-0.1118...	-0.1879...	0.0190...	-0.3210...	0.0413...	-0.2746...	-0.2776...	-0.5321...	-0.00...
-0.5451...	-0.3947...	-0.2502...	-0.5025...	-0.3531...	-0.1935...	-0.0970...	-0.9698...	0.296...
-0.5923...	-0.3815...	-0.2022...	-0.0674...	-0.0214...	-0.0838...	-0.1310...	-0.0554...	0.205...
0.0314...	-2.0594...	0.0999...	-1.3296...	-0.0470...	-0.3101...	-0.1242...	-0.5256...	-0.20...
-0.7684...	-0.0689...	-0.4170...	0.0214...	-0.4208...	-0.4247...	-0.2626...	-0.7629...	0.208...
-0.3011...	-0.3561...	-0.1394...	-0.2290...	-0.5230...	-0.0002...	-0.0466...	0.1336...	-0.08...
-0.8604...	-0.7904...	-0.4585...	-0.6226...	-1.6474...	-0.4490...	-0.5911...	-0.6703...	0.279...
-0.5162...	-0.0985...	-0.1948...	-0.1594...	-1.3342...	-0.8718...	-0.8667...	-0.6355...	0.130...
-0.4474...	-0.3370...	-0.2852...	-0.2331...	0.0729...	-0.3032...	0.0418...	-0.9479...	0.145...
-0.2476...	-0.1680...	-0.0272...	-0.1845...	-1.5294...	-1.0247...	-1.2402...	-0.9938...	0.077...
-0.4825...	-0.9196...	-0.2014...	-0.7169...	-2.0343...	-0.5324...	-0.7525...	-0.6485...	0.105...

Fit Model - JMP

Model Specification

Select Columns

174 Columns

Enter column name

- Original Sensors (63/0)
- testResult
- status
- Validation
- Validation Random Formula
- Transformed Sensors (63/0)
 - Trans Sensor 01
 - Trans Sensor 02
 - Trans Sensor 03
 - Trans Sensor 04
 - Trans Sensor 05
 - Trans Sensor 06
 - Trans Sensor 07
 - Trans Sensor 08
 - Trans Sensor 09
 - Trans Sensor 10
 - Trans Sensor 11
 - Trans Sensor 12
 - Trans Sensor 13

Pick Role Variables

Y: status

Weight: optional numeric

Freq: optional numeric

Validation: Validation

By: optional

Personality: Generalized Regression

Distribution: Binomial

Target Level: Pass

Help Run

Recall Keep dialog open

Remove

Construct Model Effects

Add Cross Nest Macros

Degree: 2

Attributes Transform

No Intercept

- Trans Sensor 05
- Trans Sensor 06
- Trans Sensor 07
- Trans Sensor 08
- Trans Sensor 13
- Trans Sensor 14
- Trans Sensor 15
- Trans Sensor 16
- Trans Sensor 18
- Trans Sensor 20

▼ **Generalized Regression for status = Pass**

▼ **Model Comparison**

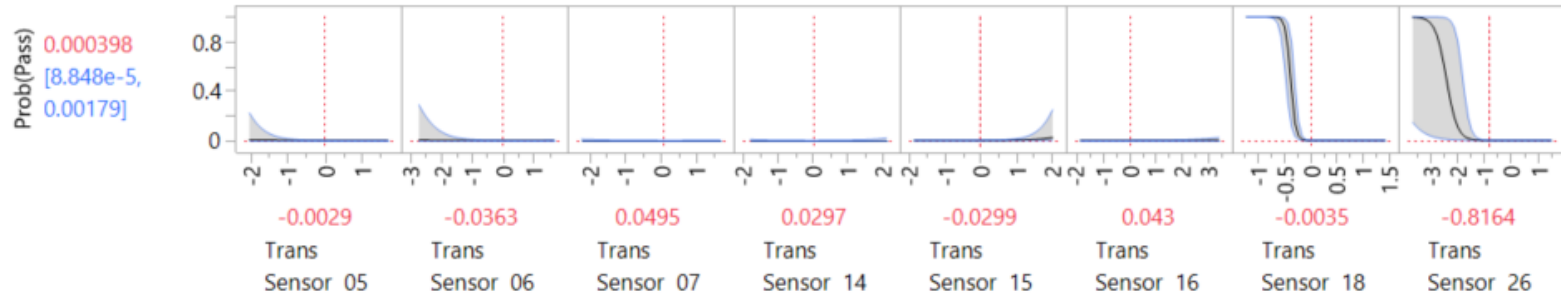
Show	Response Distribution	Estimation Method	Validation Method	Nonzero Parameters	AICc	BIC	Generalized RSquare	Validation Generalized RSquare
<input checked="" type="checkbox"/>	Binomial	Logistic Regression	Validation Column	26	.	.	.	0.6234149
<input checked="" type="checkbox"/>	Binomial	Lasso	Validation Column	13	30.775781	64.788125	0.9958038	0.906737
<input checked="" type="checkbox"/>	Binomial	Elastic Net	Validation Column	17	43.746715	86.850012	0.9888577	0.8883607
<input checked="" type="checkbox"/>	Binomial	Ridge	Validation Column	26	76.931684	137.5221	0.9697985	0.8336802

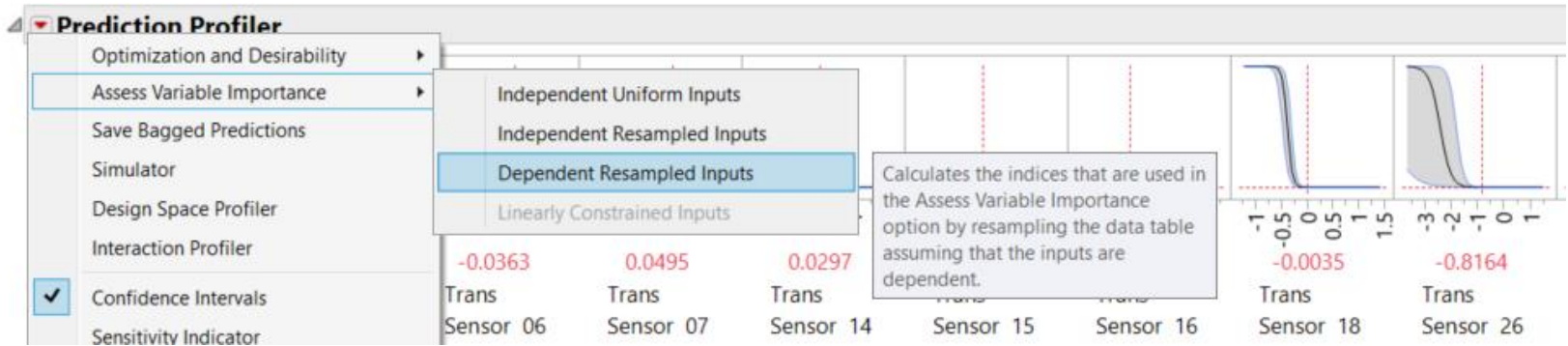
Binomial Lasso with Validation Column

Parameter Estimates for Original Predictors

Term	Estimate	Std Error	Wald ChiSquare	Prob > ChiSquare	Lower 95%	Upper 95%
Trans Sensor 18	-21.50633	1.983503	117.56198	<.0001*	-25.39392	-17.61874
Intercept	-16.15049	2.0322961	63.153519	<.0001*	-20.13372	-12.16726
Trans Sensor 27	7.6947349	1.5130301	25.863792	<.0001*	4.7292504	10.660219
Trans Sensor 26	-4.982007	1.4309036	12.12238	0.0005*	-7.786526	-2.177487
Trans Sensor 15	2.0136856	0.7221117	7.7763279	0.0053*	0.5983727	3.4289985
Trans Sensor 52	-6.155699	3.8026345	2.6205089	0.1055	-13.60873	1.2973273
Trans Sensor 05	-1.227494	0.9327291	1.7319197	0.1882	-3.05561	0.6006214
Trans Sensor 16	0.4251844	0.3580648	1.4100395	0.2350	-0.27661	1.1269786
Trans Sensor 53	-3.442666	3.6166922	0.9060802	0.3412	-10.53125	3.6459207
Trans Sensor 61	-2.92957	3.5324812	0.6877774	0.4069	-9.853105	3.9939665
Trans Sensor 06	-0.67685	0.8698959	0.6054114	0.4365	-2.381815	1.0281144
Trans Sensor 07	-0.165354	0.5695772	0.0842799	0.7716	-1.281705	0.9509968
Trans Sensor 14	0.1156922	0.816768	0.0200637	0.8874	-1.485144	1.7165282
Trans Sensor 08	0	0	0	1.0000	0	0
Trans Sensor 13	0	0	0	1.0000	0	0
Trans Sensor 20	0	0	0	1.0000	0	0

Prediction Profiler





Binomial Lasso with Validation Column

Prediction Profiler

Variable Importance: Dependent Resampled Inputs

Summary Report

Column	Main Effect	Total Effect	.2	.4	.6	.8
Trans Sensor 18	0.053	0.175				
Trans Sensor 27	0.035	0.077				
Trans Sensor 52	0.051	0.051				
Trans Sensor 61	0.051	0.051				
Trans Sensor 53	0.05	0.05				
Trans Sensor 26	0.041	0.041				
Trans Sensor 06	0.038	0.038				
Trans Sensor 07	0.037	0.037				
Trans Sensor 05	0.036	0.036				
Trans Sensor 14	0.034	0.034				
Trans Sensor 16	0.03	0.03				
Trans Sensor 15	0.029	0.029				

$Rsq=.9$

$Rsq=.8$

Binomial Lasso with Validation Column

Prediction Profiler

Variable Importance: Dependent Resampled Inputs

Summary Report

Column	Main Effect	Total Effect	.2	.4	.6	.8
Trans Sensor 18	0.053	0.175				
Trans Sensor 27	0.035	0.035				
Trans Sensor 52	0.051	0.051				
Trans Sensor 61	0.051	0.051				
Trans Sensor 53	0.05	0.05				
Trans Sensor 26	0.041	0.041				
Trans Sensor 06	0.038	0.038				
Trans Sensor 07	0.037	0.037				
Trans Sensor 05	0.036	0.036				
Trans Sensor 14	0.034	0.034				
Trans Sensor 16	0.03	0.03				
Trans Sensor 15	0.029	0.029				

$Rsq=.9$

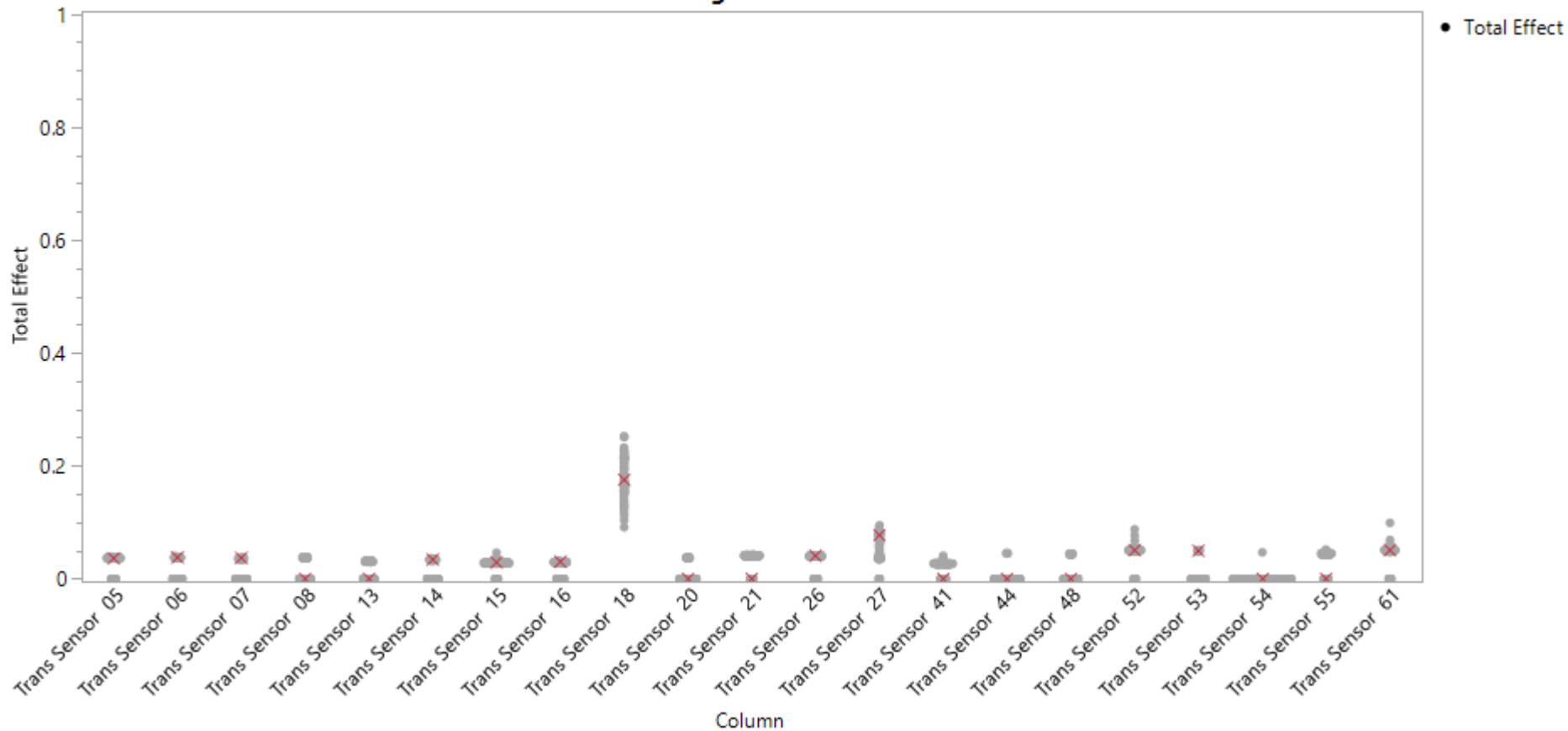
Bootstrap Forest for status

Column Contributions

Term	Number of Splits	G^2	Portion
sensor18	579	54.9167342	0.5024
sensor61	198	18.7389273	0.1714
sensor52	145	13.1320295	0.1201
sensor53	56	5.26374221	0.0482
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sensor57	75	0.3901658	0.0036
sensor01	44	0.35310066	0.0032
sensor05	47	0.3400086	0.0031
sensor21	8	0.30245908	0.0028

$Rsq=.8$

Lasso Validation Shuffling Total Effect vs. Column



“How important are the inputs to a predictive model”

Column Contributions

- What predictors explain the most **response** variation on the **training data**?
- Partition-based models only
- Based on equivalent Least Sq model
- Includes residual error
- Robust and stable (random forests)
- Results will not change if columns monotonically transformed
- Good early step in modeling process

Variable Importance

- What predictors explain the most variation in *predictive model on the data or a region*?
- General: applies to all supervised models
- Based on Sobol (1990) sensitivity analysis
- Model variation based, not residual error
- Very sensitive to model over/under fit
- Results change unpredictably if columns are transformed
- Descriptive tool at the end of the modeling process

“What are the groups of related columns?”

“How representative are each column to its group?”

Variable Clustering

- Unsupervised method
- Based on recursive partitioning of columns guided by PCA/Factor Analysis of groups
- Reference: PROC VARCLUS documentation
- Only seeks linear relationships among columns
- Sensitive to outliers
- Useful in the early stages of data exploration

“How did each input column contribute to this model’s prediction at a particular value of X?”

Shapley (SHAP) Values

- Additive decomposition of a single predicted value that can be anywhere (not just data used for fitting the model)
- $\hat{f}(x_1 x_2 \dots) = SHAP_{Intercept} + SHAP_{\hat{f},1}(x_1) + SHAP_{\hat{f},1}(x_2) + \dots$
- General: applies to all supervised models
- Based on Shapley (1951) – resulted in 2012 Nobel
- Model variation based, not residual error
- Very sensitive to model over/under fit
- Results change unpredictably if columns are transformed
- Descriptive tool at the end of the modeling process

Binomial Lasso with Validation Column

Prediction Profiler

- Optimization and Desirability
- Assess Variable Importance
- Save Bagged Predictions
- Simulator
- Design Space Profiler
- Interaction Profiler
- Confidence Intervals
- Sensitivity Indicator
- Extrapolation Control
- Reset Factor Grid
- Factor Settings
- Default N Levels
- Output Grid Table
- Output Random Table
- Shapley Values
- Alter Linear Constraints
- Save Linear Constraints
- Appearance

Trans	Trans	Trans	Trans	Trans
0.3704	-0.212	0.0069	-0.0184	-0.8164
Sensor 27	Sensor 52	Sensor 61	Sensor 53	Sensor 26

Shapley Values

Effect	.2	.4	.6	.8
0.175				
0.077				
0.051				
0.051				
0.037				
0.036				
0.034				
0.03				
0.029				

Save Shapley Values

Set Shapley Values Options

Calculates Shapley values for each row in the data table that is not excluded.
This item is new as of version 17.

SHAP Trans Sensor 05	SHAP Trans Sensor 06	SHAP Trans Sensor 07	SHAP Trans Sensor 14	SHAP Trans Sensor 15	SHAP Trans Sensor 16	SHAP Trans Sensor 18	SHAP Trans Sensor 26	SHAP Trans Sensor 27	SHAP Trans Sensor 52	SHAP Trans Sensor 53	SHAP Trans Sensor 61	SHAP Intercept	SHAP Trans Sensor 05+SHAP Trans Sensor 06+SHAP T...ns Sensor 53+SHAP Trans Sensor 61+SHAP Intercept	Probability(status=Pass)
-0.01...	-0.00...	0.000...	0.000...	0.073...	-0.00...	0.138...	0.038...	0.019...	0.103...	0.078...	0.050...	0.480...	0.9646941837	0.9646941837
0.016...	0.007...	0.001...	0.002...	0.019...	0.006...	0.333...	0.052...	-0.05...	0.060...	0.037...	0.037...	0.480...	0.9999999949	0.9999999949
0.001...	0.006...	0.001...	0.002...	-0.01...	-0.00...	0.255...	0.104...	-0.08...	0.082...	0.068...	0.060...	0.480...	0.9669140606	0.9669140606

Local Data Filter

Clear

Favorites

Inverse

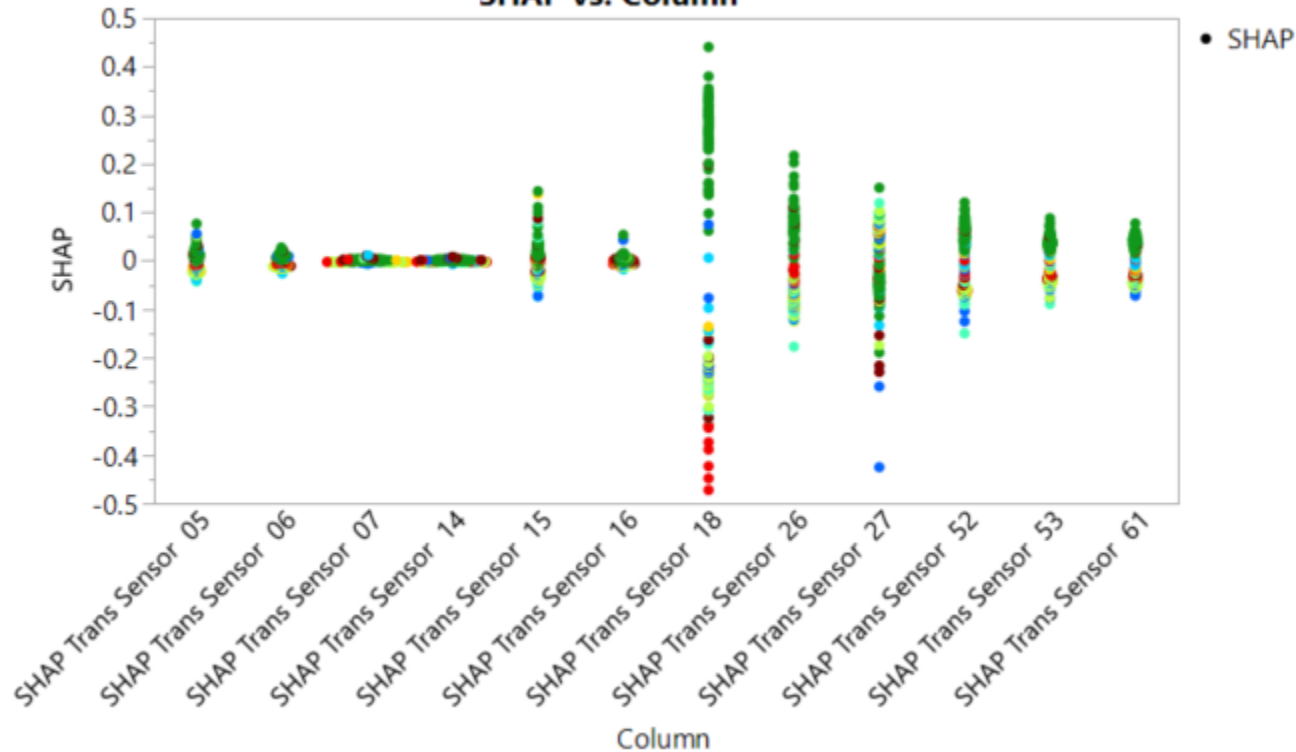
<input checked="" type="checkbox"/> testResult (8)	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND

OR

Graph Builder

SHAP vs. Column



Local Data Filter

Clear

Favorites ▾

984 matching rows

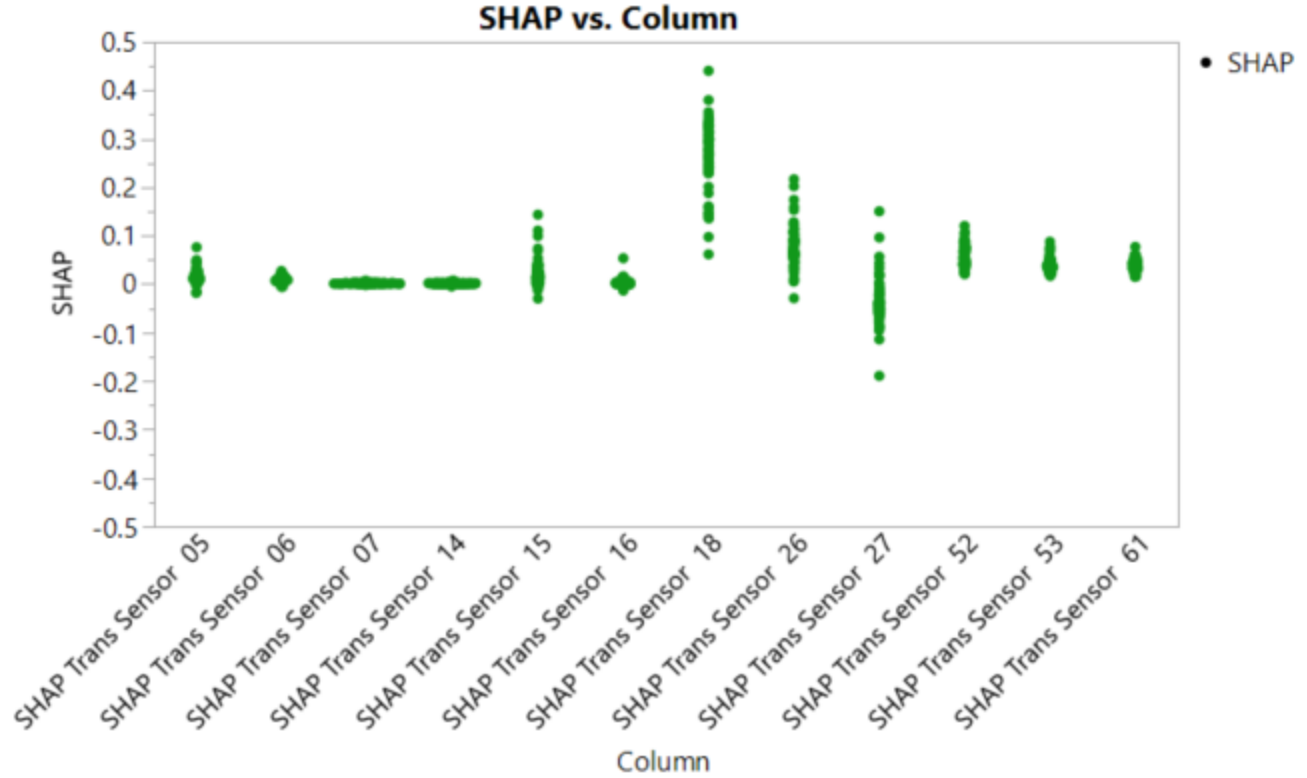
Inverse

<input checked="" type="checkbox"/> testResult (8)	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND

OR

Graph Builder



Where(testResult = Good)

Local Data Filter

Clear Favorites

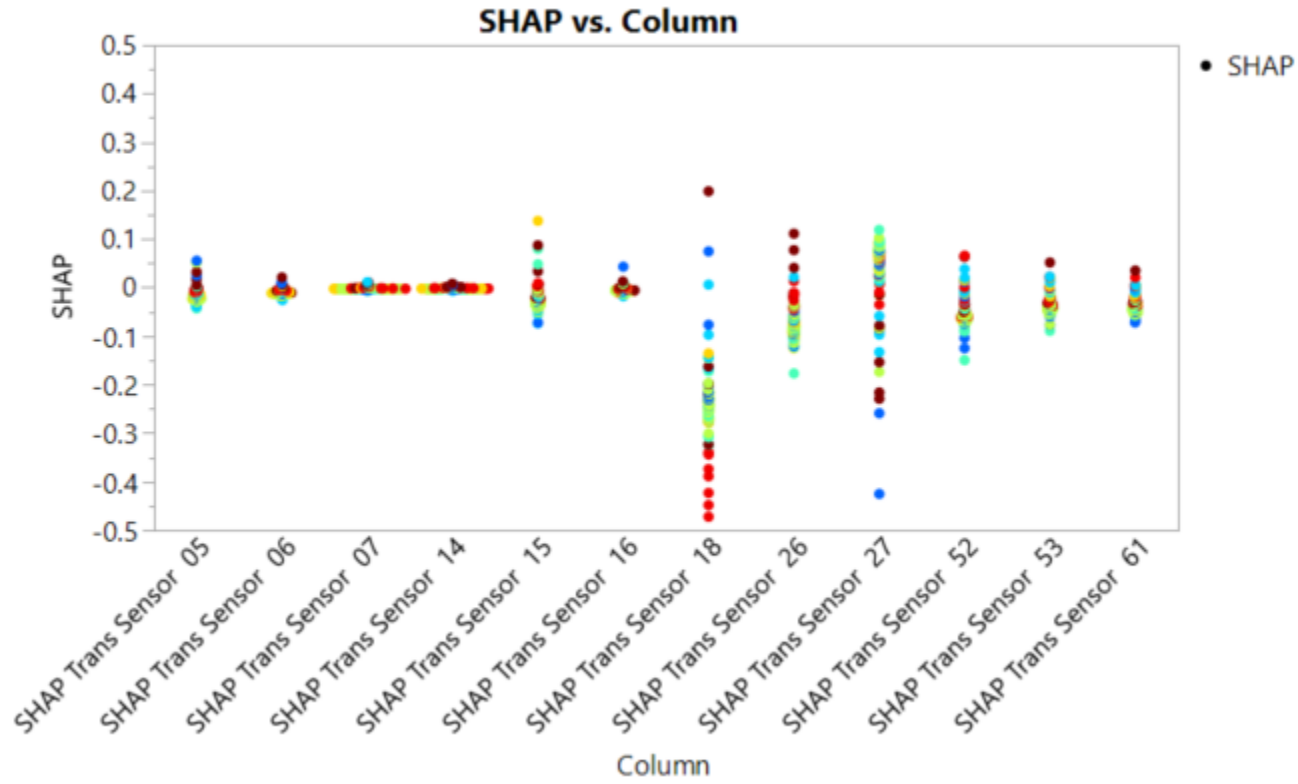
1080 matching rows

Inverse

testResult (8)	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND OR

Graph Builder



Where(Not (testResult = Good))

Local Data Filter

Clear Favorites ▾

60 matching rows

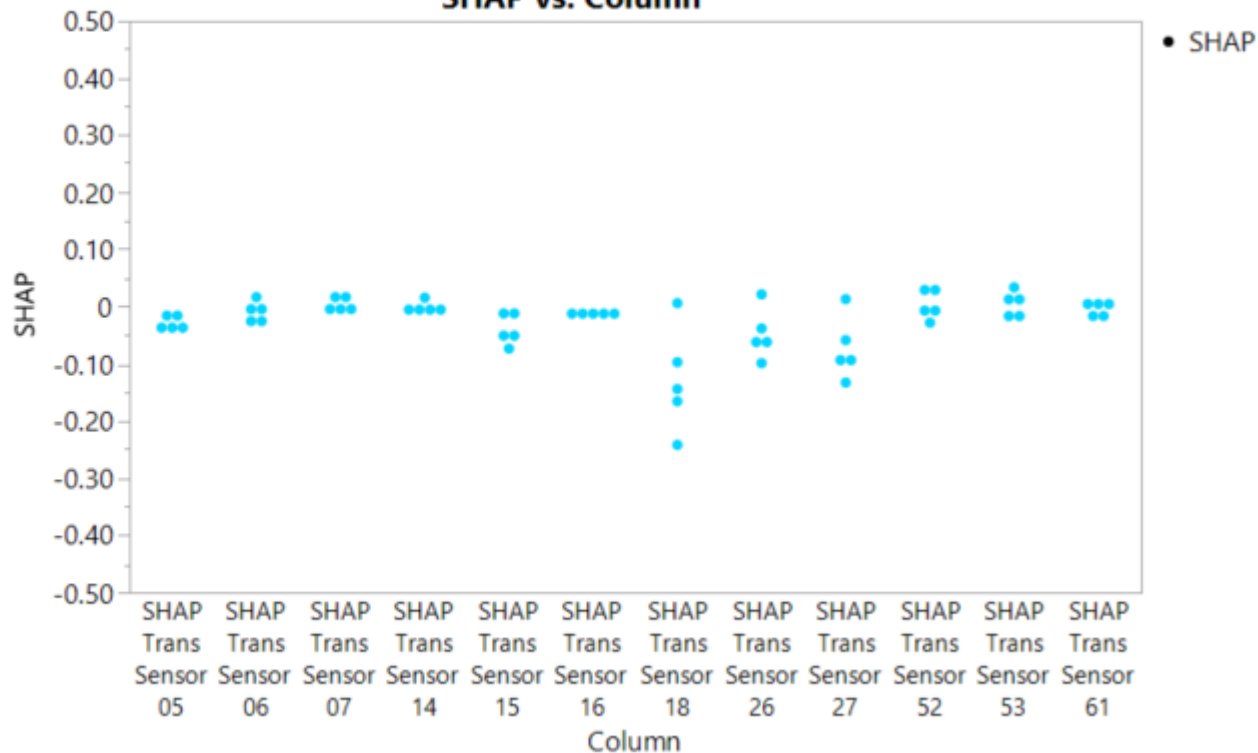
Inverse

<input checked="" type="checkbox"/> testResult (8) ×	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND OR

Graph Builder

SHAP vs. Column



Where(testResult = IMP)

Local Data Filter

Clear

Favorites ▾

168 matching rows

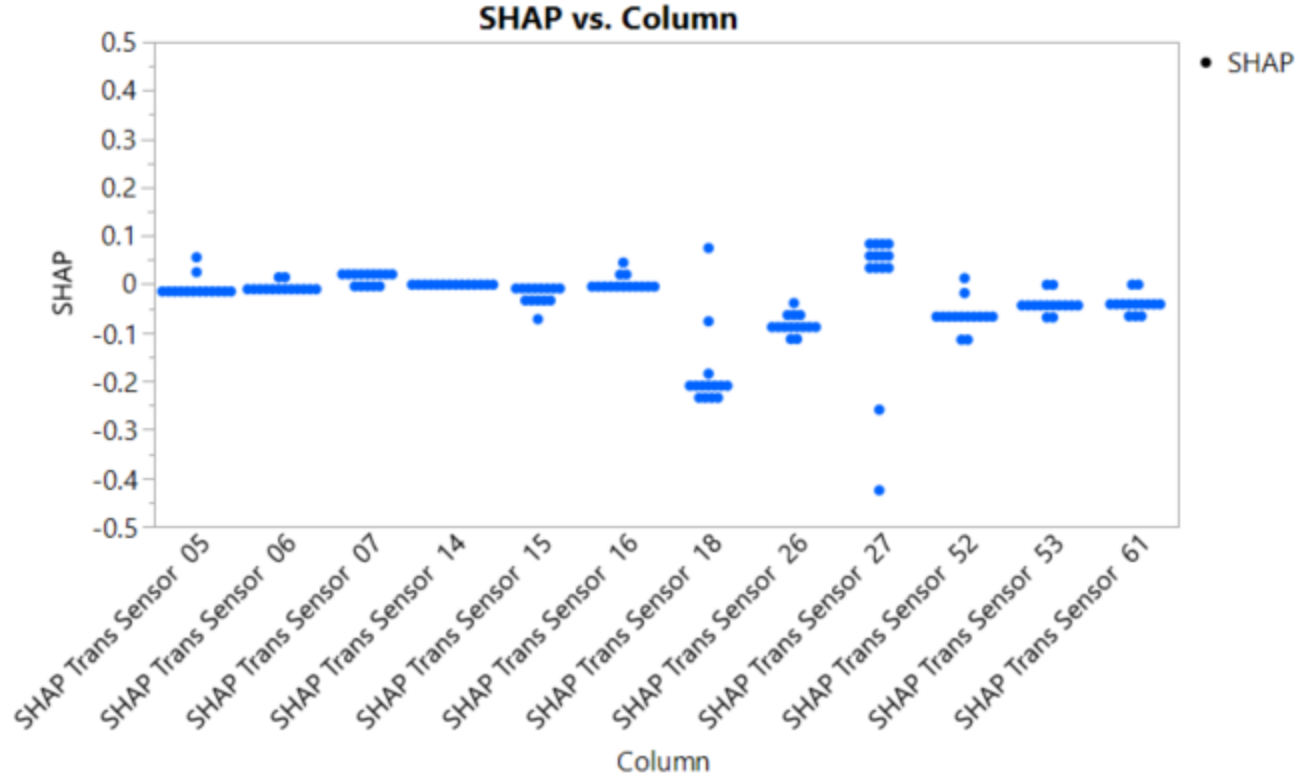
Inverse

<input checked="" type="checkbox"/> testResult (8)	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND

OR

Graph Builder



Where(testResult = Grippers)

Local Data Filter

Clear

Favorites ▾

192 matching rows

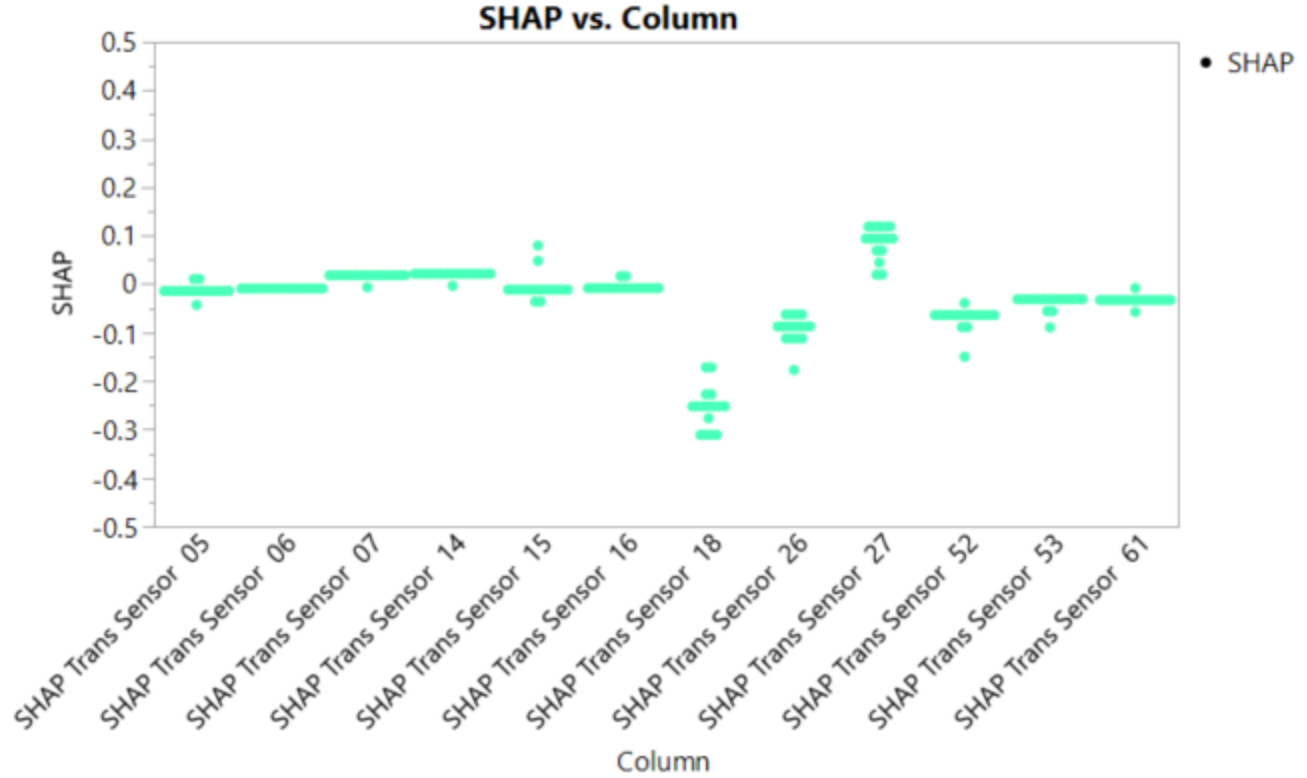
Inverse

<input checked="" type="checkbox"/> testResult (8) ×	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND

OR

Graph Builder



Where(testResult = Motor)

Local Data Filter

Clear

Favorites ▾

396 matching rows

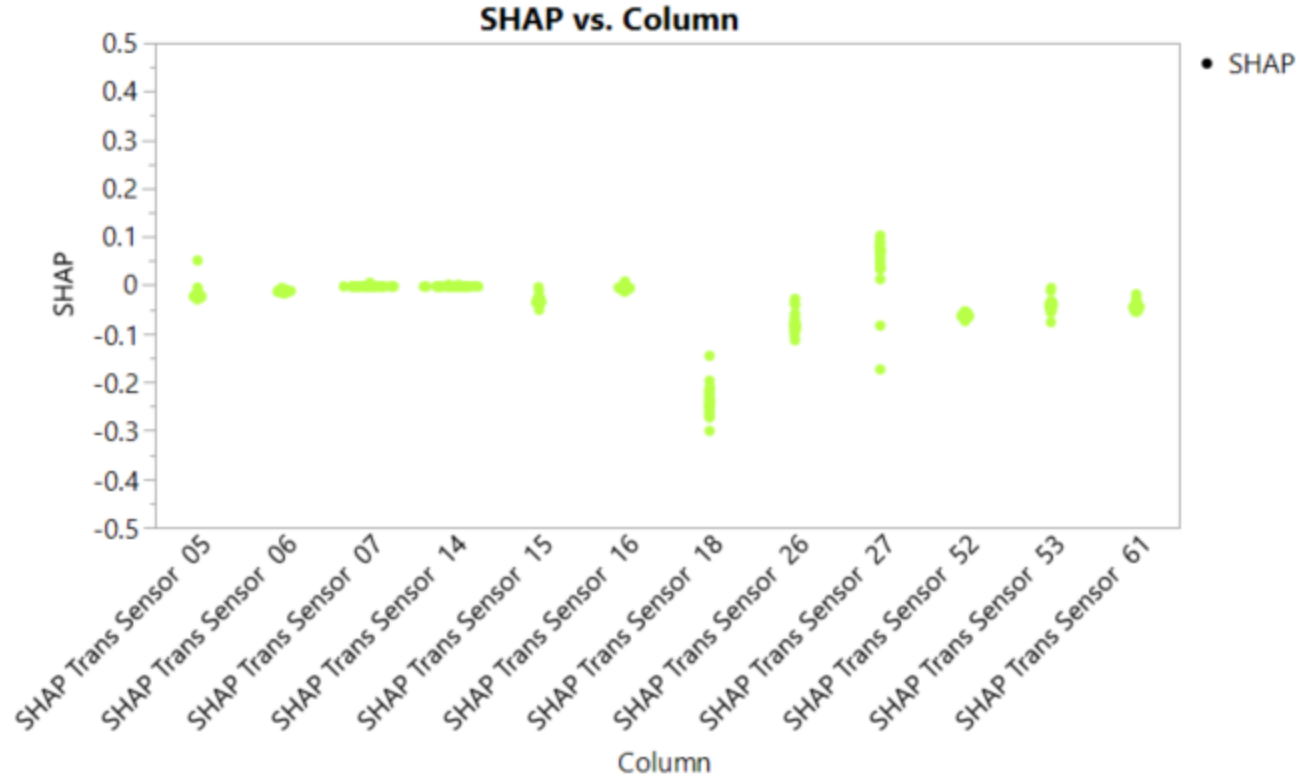
Inverse

<input checked="" type="checkbox"/> testResult (8) ×	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND

OR

Graph Builder



Where(testResult = ITM)

Local Data Filter

Clear

Favorites ▾

72 matching rows

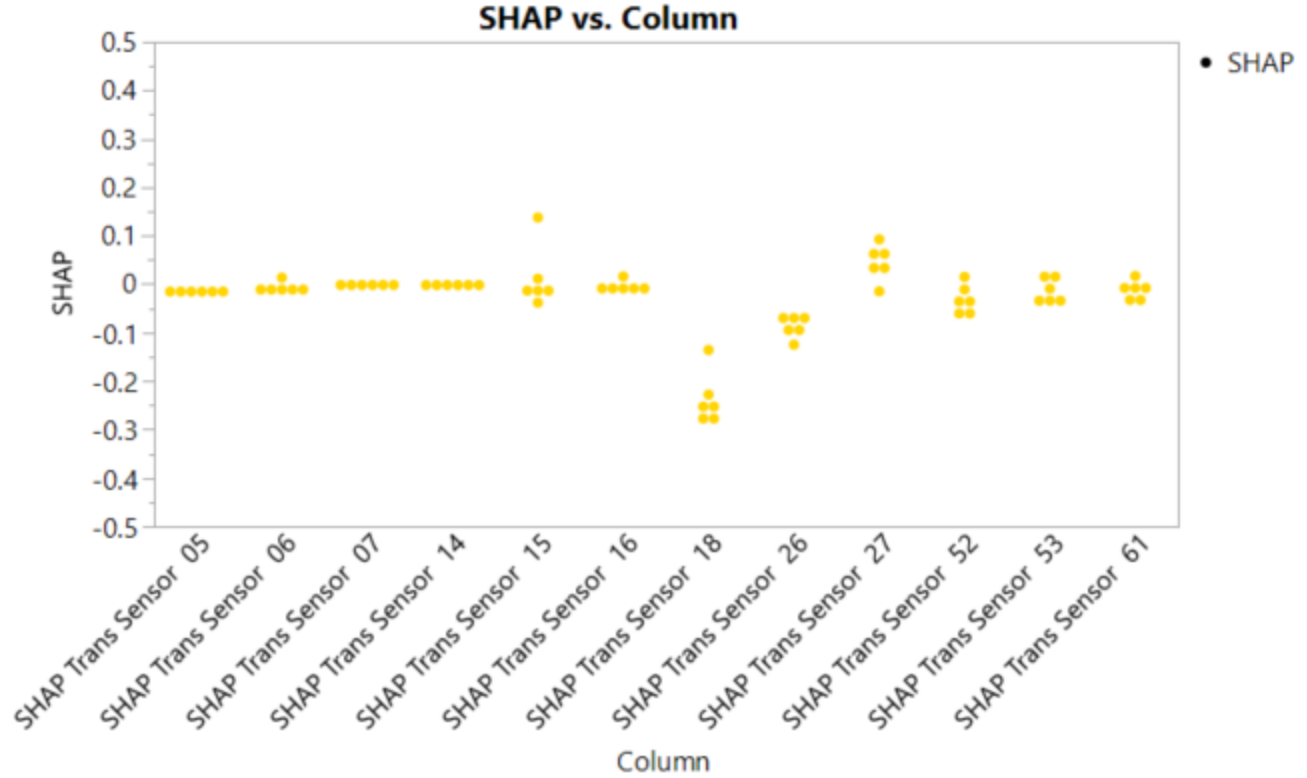
Inverse

<input checked="" type="checkbox"/> testResult (8) ×	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND

OR

Graph Builder



Where(testResult = Brake)

Local Data Filter

Clear Favorites

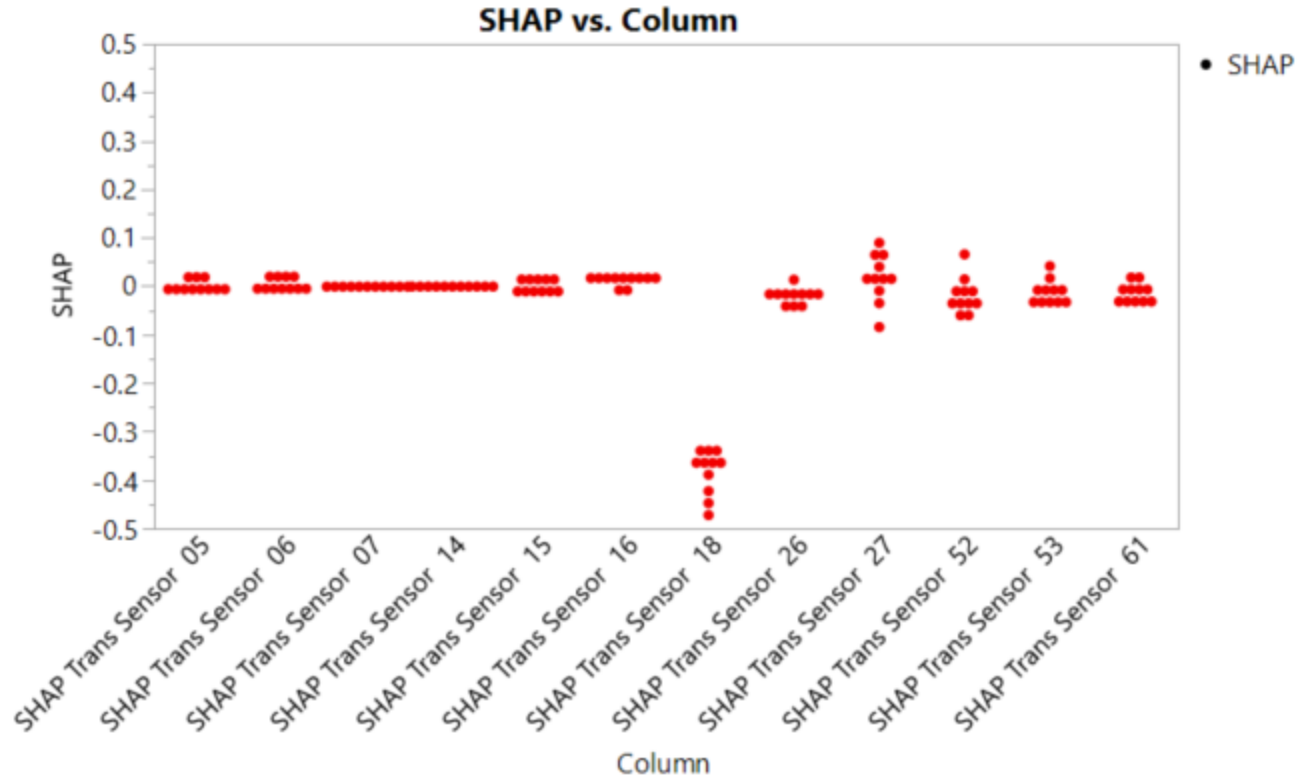
132 matching rows

Inverse

<input checked="" type="checkbox"/> testResult (8)	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND OR

Graph Builder



Where(testResult = Velocity Type I)

Local Data Filter

Clear Favorites

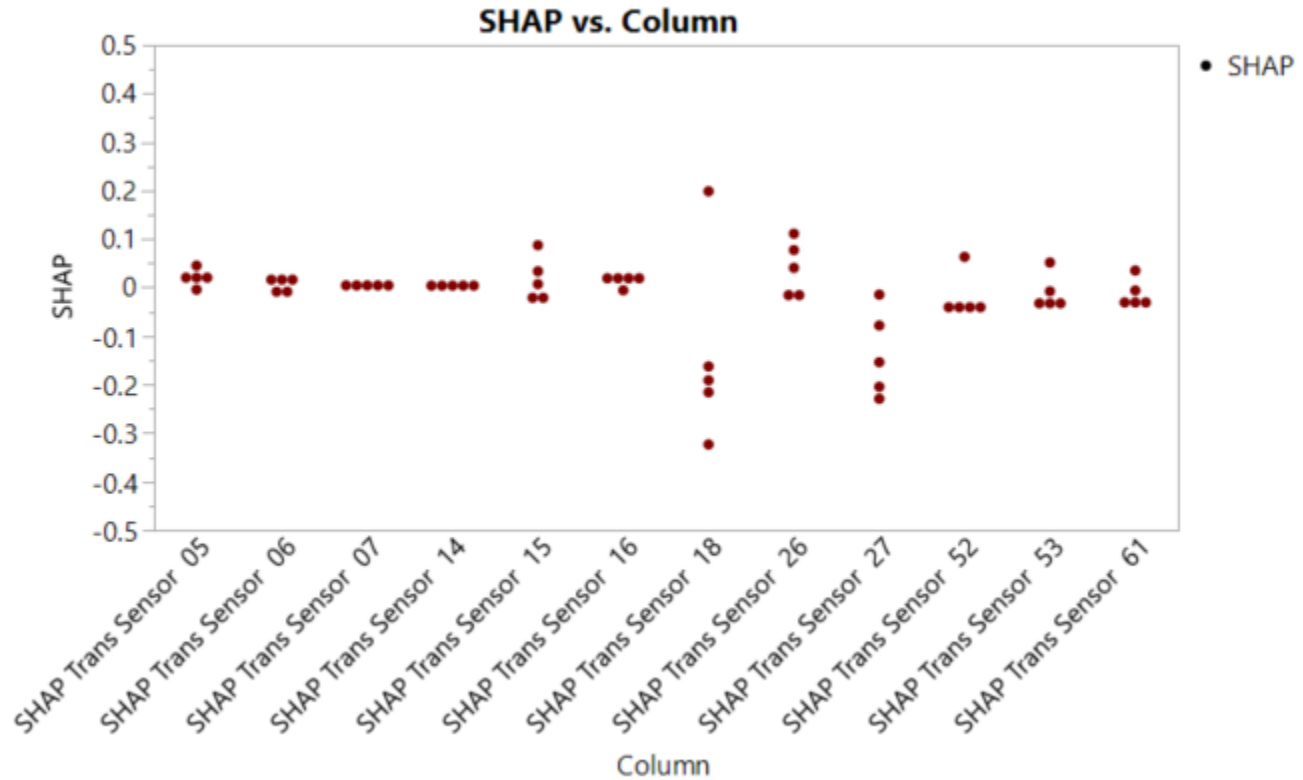
60 matching rows

Inverse

testResult (8)	
Good	984
Grippers	168
IMP	60
Motor	192
ITM	396
Brake	72
Velocity Type I	132
Velocity Type II	60

AND OR

Graph Builder



Where(testResult = Velocity Type II)

Generalized Regression for testResult

Model Comparison

Show	Response Distribution	Estimation Method	Validation Method	Nonzero Parameters	AICc	BIC	Generalized RSquare	Validation Generalized RSquare
<input checked="" type="checkbox"/>	Multinomial	Maximum Likelihood	Validation Column	156	.	655.93721	0.999997	-43.17824
<input checked="" type="checkbox"/>	Multinomial	Lasso	Validation Column	60	1346.9128	259.19431	0.995714	0.9396993
<input checked="" type="checkbox"/>	Multinomial	Elastic Net	Validation Column	64	4304.7032	285.80357	0.988835	0.9282288
<input checked="" type="checkbox"/>	Multinomial	Ridge	Validation Column	156	.	682.86499	0.9804884	0.8778949

- Exclude all the “Pass” rows to focus on the failures
- Same Cluster 1 columns used in the Pass model

Partition - JMP

Builds a decision tree to predict a response.

Select Columns

▼ 151 Columns

Enter column name

- Original Sensors (63/0)
 - sensor01
 - sensor02
 - sensor03
 - sensor04
 - sensor05
 - sensor06
 - sensor07
 - sensor08
 - sensor09

Options

Method: Decision Tree

Validation Portion: 0

Informative Missing

Ordinal Restricts Order

Cast Selected Columns into Roles

Y, Response: testResult (optional)

X, Factor: Prob(Pass), Prob[Grippers], Prob[IMP], Prob[Motor], Prob[ITM], Prob[Brake], Prob[Velocity Type I], Prob[Velocity Type II]

Weight: optional numeric

Freq: optional numeric

Validation: Validation

By: optional

Action

OK

Cancel

Remove

Recall

Help

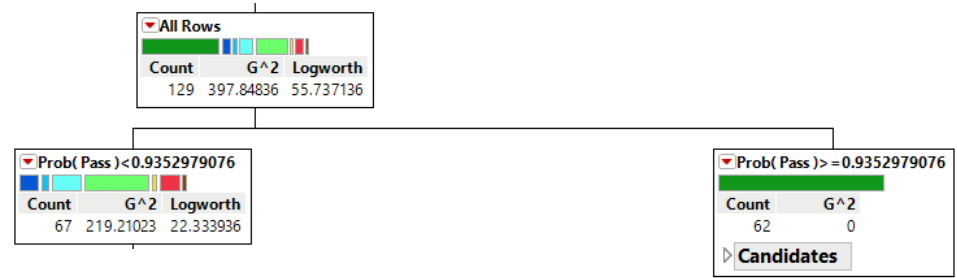
All Rows		
Count	G^2	Logworth
129	397.84836	55.737136

testResult

- Good
- Grippers
- IMP
- Motor
- ITM
- Brake
- SOS
- Velocity Type I
- Velocity Type II

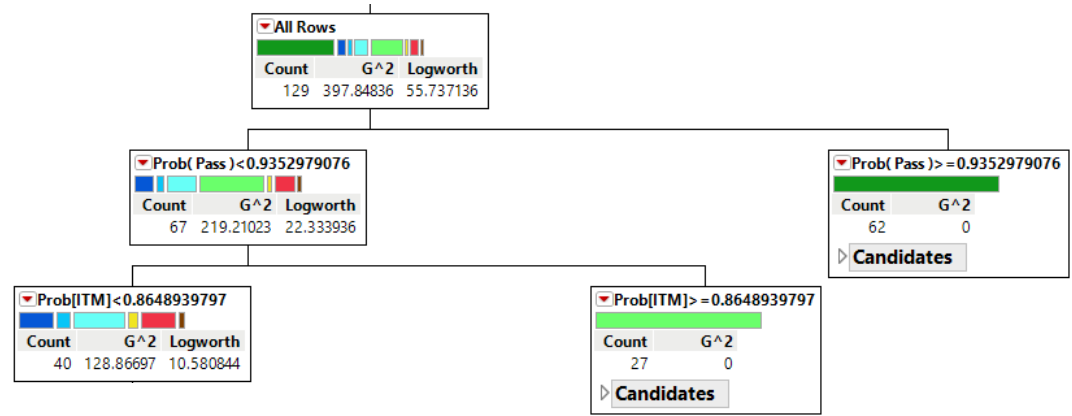
testResult

- Good
- Grippers
- IMP
- Motor
- ITM
- Brake
- SOS
- Velocity Type I
- Velocity Type II



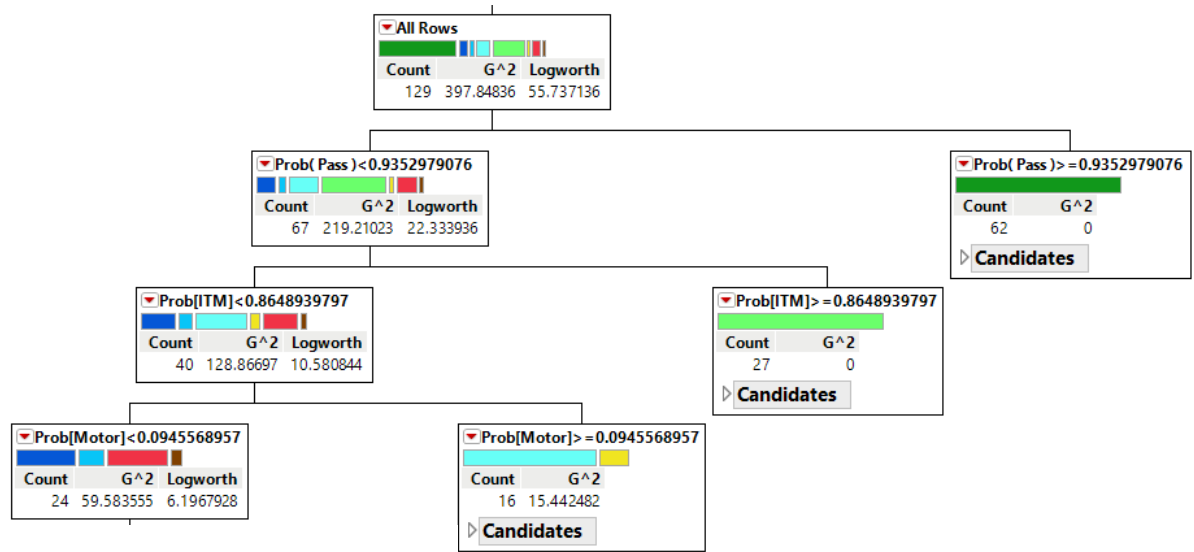
testResult

- Good
- Grippers
- IMP
- Motor
- ITM
- Brake
- SOS
- Velocity Type I
- Velocity Type II



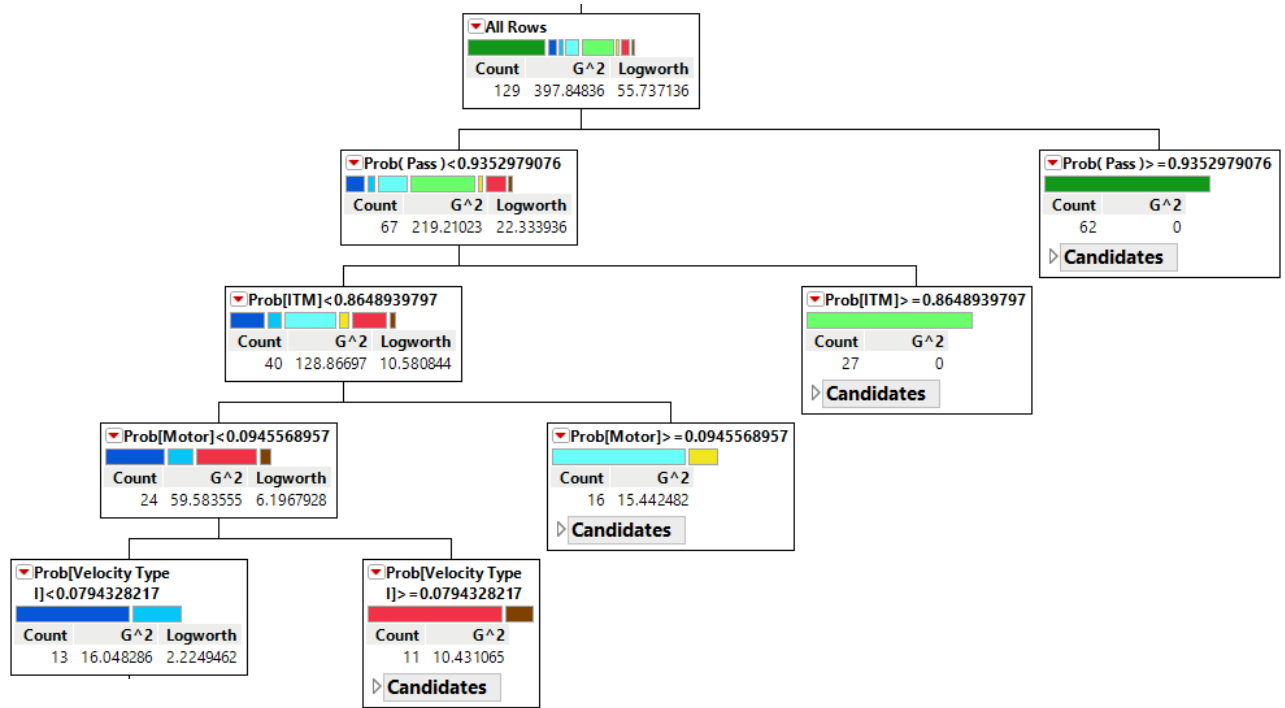
testResult

- Good
- Grippers
- IMP
- Motor
- ITM
- Brake
- SOS
- Velocity Type I
- Velocity Type II



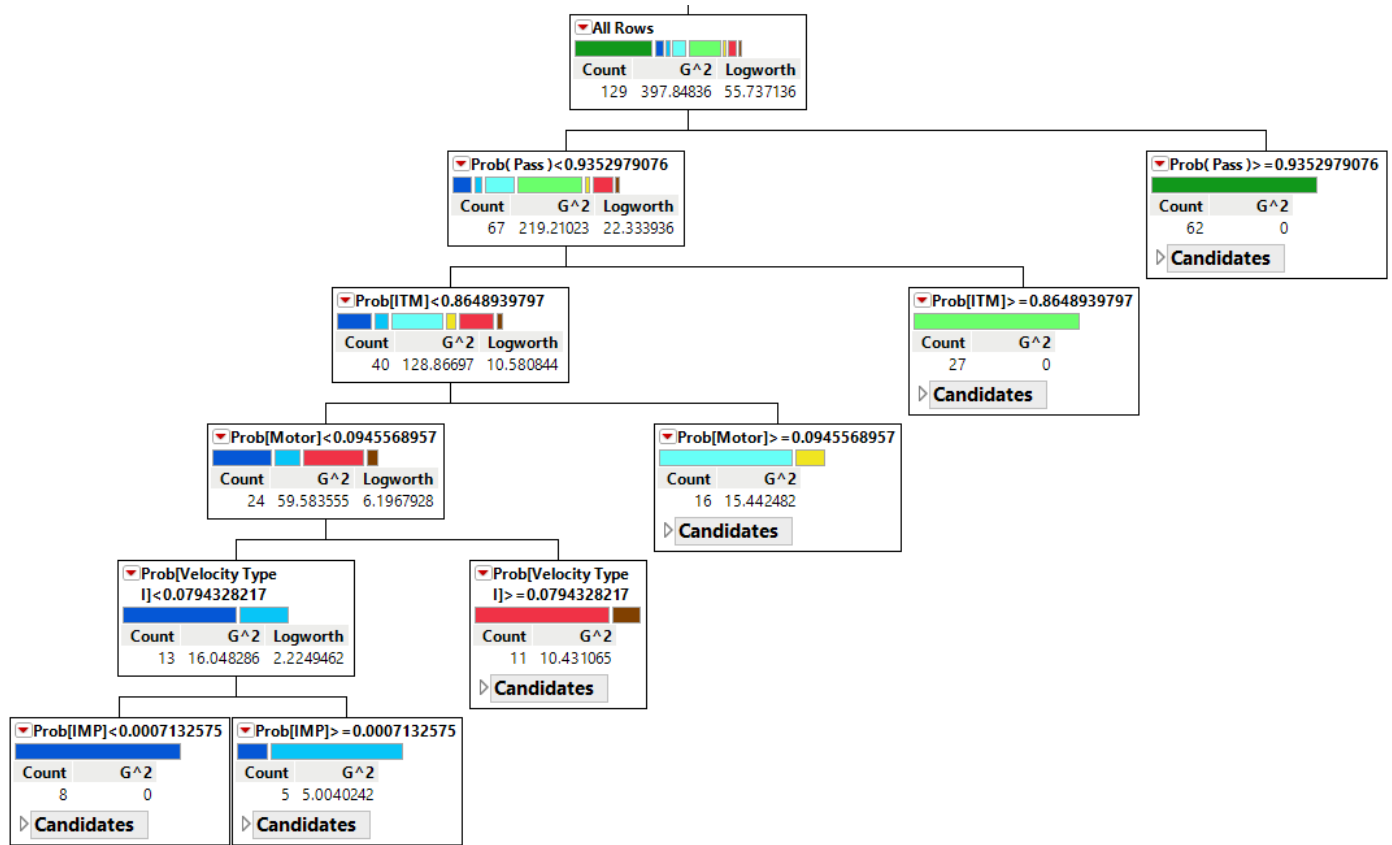
testResult

- Good
- Grippers
- IMP
- Motor
- ITM
- Brake
- SOS
- Velocity Type I
- Velocity Type II



testResult

- Good
- Grippers
- IMP
- Motor
- ITM
- Brake
- SOS
- Velocity Type I
- Velocity Type II



Actual By Predicted Category on Training

Leaf Label Formula	testResult								
	Count	Good	Grippers	IMP	Motor	ITM	Brake	Velocity Type I	Velocity Type II
Predict Good	62	0	0	0	0	0	0	0	0
Predict Grippers or IMP	0	9	4	0	0	0	0	0	0
Predict ITM	0	0	0	0	27	0	0	0	0
Predict Motor or Brake	0	0	0	13	0	3	0	0	0
Predict Velocity Type I or II	0	0	0	0	0	0	9	2	

Actual By Predicted Category on Validation

Leaf Label Formula	testResult								
	Count	Good	Grippers	IMP	Motor	ITM	Brake	Velocity Type I	Velocity Type II
Predict Good	18	0	0	0	0	0	0	0	1
Predict Grippers or IMP	2	5	1	0	0	0	1	0	2
Predict ITM	0	0	0	0	6	0	0	0	0
Predict Motor or Brake	0	0	0	3	0	2	0	0	0
Predict Velocity Type I or II	0	0	0	0	0	0	2	0	0

Thank you for your attention